



User's Manual

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USER'S MANUAL VERSIONS

If you find any errors in this document, please inform us and we will make the appropriate corrections for future releases.

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Introduction

Designed with Micrium's renowned quality, scalability and reliability, the purpose of μ C/CPU is to provide a clean, organized ANSI C implementation of each processor's/ compiler's hardware-dependent.

1-1 PORTABLE

μ C/CPU was designed for the vast variety of embedded applications. The processor-dependent source code for μ C/CPU is designed to be ported to any processor (CPU) and compiler while μ C/CPU's core library source code is designed to be independent of and used with any processor/compiler.

1-2 SCALABLE

The memory footprint of μ C/CPU can be adjusted at compile time based on the features you need and the desired level of run-time performance.

1-3 CODING STANDARDS

Coding standards have been established early in the design of μ C/CPU and include:

- C coding style
- Naming convention for `#define` constants, macros, variables and functions
- Commenting
- Directory structure

1-4 MISRA C

The source code for μ C/CPU follows the Motor Industry Software Reliability Association (MISRA) C Coding Standards. These standards were created by MISRA to improve the reliability and predictability of C programs in critical automotive systems. Members of the MISRA consortium include Delco Electronics, Ford Motor Company, Jaguar Cars Ltd., Lotus Engineering, Lucas Electronics, Rolls-Royce, Rover Group Ltd., and other firms and universities dedicated to improving safety and reliability in automotive electronics. Full details of this standard can be obtained directly from the MISRA web site, <http://www.misra.org.uk>.

1-5 SAFETY CRITICAL CERTIFICATION

μ C/CPU has been designed and implemented with safety critical certification in mind. μ C/CPU is intended for use in any high-reliability, safety-critical systems including avionics RTCA DO-178B and EUROCAE ED-12B, medical FDA 510(k), IEC 61508 industrial control systems, and EN-50128 rail transportation and nuclear systems.

For example, the FAA (Federal Aviation Administration) requires that all the source code for an application be available in source form and conforming to specific software standards in order to be certified for avionics systems. Since most standard library functions are provided by compiler vendors in uncertifiable binary format, μ C/CPU provides its library functions in certifiable source-code format.

If your product is not safety critical, you should view the software and safety-critical standards as proof that μ C/CPU is a very robust and highly-reliable software module.

1-6 μ C/CPU LIMITATIONS

By design, we have limited some of the feature of μ C/CPU:

- Support for 64-bit data not available for all CPUs

Directories and Files

The distribution of μ C/CPU is typically included in a ZIP file called: `Micrium_uC-CPU-Vxyy.zip`. (Note: The ZIP file name might also include customer names, invoice numbers, and file creation date.) The ZIP file contains all the source code and documentation for μ C/CPU organized in a directory structure according to “AN-2002, μ C/OS-II Directory Structure.” Specifically, the files may be found in the following directories:

`\Micrium\Software\uC-CPU`

This is the main directory for μ C/CPU and contains generic, processor-independent source code including:

`cpu_def.h`

This file declares `#define` constants used to configure processor/compiler-specific CPU word sizes, endianness word order, critical section methods, and other processor configuration.

`cpu_core.c` and `cpu_core.h`

These files contain source code that implements μ C/CPU features such as host name allocation, timestamps, time measurements, and counting lead zeros.

`\Micrium\Software\uC-CPU\Doc`

This directory contains all μ C/CPU documentation files.

`\Micrium\Software\uC-CPU\Cfg\Template`

This directory contains a template file, `cpu_cfg.h`, which includes configuration for μ C/CPU features such as host name allocation, timestamps, time measurements, and assembly optimization. Your application must include a `cpu_cfg.h` configuration file with application-specific configuration settings.

\Micrium\Software\uC-CPU\BSP\Template

This directory contains a template file, `cpu_bsp.c`, which includes function templates for the board-specific (BSP) code required if certain μ C/CPU features such as timestamp time measurements and assembly optimization are enabled. Your application must include code for all BSP functions enabled in `cpu_cfg.h`.

\Micrium\Software\<CPU Type>\<Compiler>

μ C/CPU also contains additional sub-directories specific to each processor/compiler combination organized as follows:

cpu.h

This file contains μ C/CPU configuration specific to the processor (**CPU Type**) and compiler (**Compiler**), such as data type definitions, processor address and data word sizes, endianness word order, and critical section macros. See Chapter 3, “ μ C/CPU Processor/Compiler Port Files” on page 12 for more details.

cpu_a.asm or cpu_a.s

These (optional) files contains assembly code to enable/disable interrupts, implement critical section methods, and any other processor-specific code not already defined or implemented in the processor's `cpu.h` (or `cpu.c`).

cpu.c

This (optional) file contains C and/or assembly code to implement processor-specific code not already defined or implemented in the processor's `cpu.h` (or `cpu_a.asm`).

\Template\cpu.h and cpu_a.asm

These template μ C/CPU configuration files include example configurations for a generic processor/compiler.

An example of ARM-specific CPU processor files is shown in Figure 2-1:

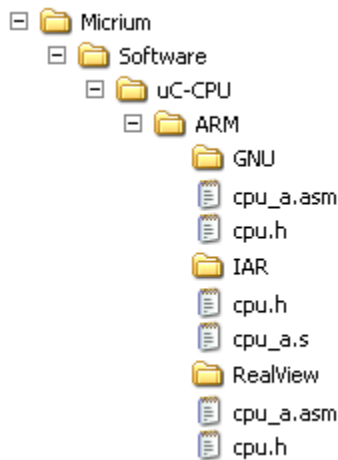


Figure 2-1 **µC/CPU ARM CPU Directories and Files Example**

Application files which intend to make use of µC/CPU macros or functions should **#include** the desired µC/CPU header files. In addition, applications are required to configure µC/CPU features in application-specific configuration file, **cpu_cfg.h**.

µC/CPU Processor/Compiler Port Files

µC/CPU contains configuration specific to each processor and compiler, such as standard data type definitions, processor address and data word sizes, endianness word order, critical section macros, and possibly other functions and macros. These are defined in each specific processor/compiler subdirectory's `cpu.h`.

3-1 STANDARD DATA TYPES

µC/CPU ports define standard data types such as `CPU_CHAR`, `CPU_BOOLEAN`, `CPU_INT08U`, `CPU_INT16S`, `CPU_FP32`, etc. These data types are used in Micrium applications, and may be used in your applications, to facilitate portability independent of and between processors/compilers. Most µC/CPU processor/compiler port files minimally support 32-bit data types, but may optionally support 64-bit (or greater) data types.

In addition, several regularly-used function pointer data types are defined.

3-2 CPU WORDS

3-2-1 CPU Word Sizes

µC/CPU ports include word size configuration such as `CPU_CFG_ADDR_SIZE`, `CPU_CFG_DATA_SIZE`, and `CPU_CFG_DATA_SIZE_MAX`; configured via `CPU_WORD_SIZE_08`, `CPU_WORD_SIZE_16`, `CPU_WORD_SIZE_32`, and `CPU_WORD_SIZE_64`.

In addition, the following CPU word sizes are also defined based on the configured sizes of `CPU_CFG_ADDR_SIZE` and `CPU_CFG_DATA_SIZE` : `CPU_ADDR`, `CPU_DATA`, `CPU_ALIGN`, and `CPU_SIZE_T`.

3-2-2 CPU Word-Memory Order

µC/CPU ports configure `CPU_CFG_ENDIAN_TYPE` to indicate the processor's word-memory order endianness. `CPU_ENDIAN_TYPE_LITTLE` indicates that a CPU stores/reads data words in memory with the most significant octets at lower memory addresses (and the least significant octets at higher memory addresses) while a `CPU_ENDIAN_TYPE_BIG` CPU stores/reads data words in memory with the most significant octets at higher memory addresses (and the least significant octets at lower memory addresses).

3-3 CPU STACKS

µC/CPU ports configure `CPU_CFG_STK_GROWTH` to indicate the direction in memory a CPU updates its stack pointers after pushing data onto its stacks. `CPU_STK_GROWTH_HI_TO_LO` indicates that a CPU decrements its stack pointers to the next lower memory address after data is pushed onto a CPU stack while a `CPU_STK_GROWTH_LO_TO_HI` CPU increments its stack pointers to the next higher memory address after data is pushed.

In addition, each µC/CPU processor port defines a `CPU_STK` data type to the CPU's stack word size.

3-4 CPU CRITICAL SECTIONS

µC/CPU ports include CPU critical section configuration `CPU_CFG_CRITICAL_METHOD` that indicates how a CPU disables/re-enables interrupts when entering/exiting critical, protected sections:

`CPU_CRITICAL_METHOD_INT_DIS_EN` merely disables/enables interrupts on critical section enter/exit. This is not a preferred method since it does not support multiple levels of interrupts. However, with some processors/compilers, this is the only available method.

`CPU_CRITICAL_METHOD_STATUS_STK` pushes/pops interrupt status onto stack before disabling/re-enabling interrupts. This is one preferred method since it supports multiple levels of interrupts. However, this method assumes that the compiler provides C-level and/or assembly-level functionality for pushing/saving the interrupt status onto a local stack, disabling interrupts, and popping/restoring the interrupt status from the local stack.

`CPU_CRITICAL_METHOD_STATUS_LOCAL` saves/restores interrupt status to a local variable before disabling/re-enabling interrupts. This also is a preferred method since it supports multiple levels of interrupts. However, this method assumes that the compiler provides C-level and/or assembly-level functionality for saving the interrupt status to a local variable, disabling interrupts, and restoring the interrupt status from the local variable.

Each μ C/CPU processor port implements critical section macros with calls to interrupt disable/enable macros. Applications should only use the critical section macros (see section 3-4-2 “`CPU_CRITICAL_ENTERO`” on page 16 and section 3-4-3 “`CPU_CRITICAL_EXITO`” on page 18) since interrupt disable/enable macros (see section 3-4-4 “`CPU_INT_DISO`” on page 20 and section 3-4-5 “`CPU_INT_ENO`” on page 22) are intended for use only by core μ C/CPU functions.

Each μ C/CPU processor port may define its interrupt disable/enable macros with inline-assembly directly in `cpu.h`, or calls to C functions defined in `cpu.c`, or calls to assembly subroutines defined in `cpu_a.asm` (or `cpu_a.s`). The specific implementation should be based on the processor port’s configured CPU critical section method.

In addition, each μ C/CPU processor port defines an appropriately-sized `CPU_SR` data type large enough to completely store the processor’s/compiler’s status word. `CPU_CRITICAL_METHOD_STATUS_LOCAL` method requires each function that calls critical section macros or interrupt disable/enable macros to declare local variable `cpu_sr` of type `CPU_SR`, which should be declared via the `CPU_SR_ALLOC()` macro (see section 3-4-1).

3-4-1 CPU_SR_ALLOC()

Allocates CPU status register word as local variable `cpu_sr`, when necessary, for use with critical section macros.

FILES

Each specific processor's/compiler's `cpu.h`

PROTOTYPE

```
CPU_SR_ALLOC();
```

ARGUMENTS

None.

RETURNED VALUE

None.

REQUIRED CONFIGURATION

None.

NOTES / WARNINGS

`CPU_SR_ALLOC()` *must* be called immediately after the last local variable declaration in a function but before any code statements.

EXAMPLE USAGE

```
CPU_BOOLEAN  ts_init;
CPU_TS       ts_cur;
CPU_SR_ALLOC();           /* Declared immediately after all local variables ... */
                          /* ... but before any code statements.                */

ts_init = DEF_YES;
ts_cur  = CPU_TS_TmrRd();
```

3-4-2 CPU_CRITICAL_ENTER()

Enters critical sections, disabling interrupts.

FILES

Each specific processor's/compiler's `cpu.h`

PROTOTYPE

```
CPU_CRITICAL_ENTER();
```

ARGUMENTS

None.

RETURNED VALUE

None.

REQUIRED CONFIGURATION

None.

NOTES / WARNINGS

`CPU_CRITICAL_ENTER()/CPU_CRITICAL_EXIT()` should be used to protect critical sections of code from interrupted or concurrent access when no other protection mechanisms are available or appropriate. For example, system code that must be re-entrant but without use of a software lock should protect the code using CPU critical sections.

Since interrupts are disabled upon calling `CPU_CRITICAL_ENTER()` and are not re-enabled until after calling `CPU_CRITICAL_EXIT()`, interrupt and operating system context switching are postponed while all critical sections have not completely exited.

Critical sections can be nested any number of times as long as `CPU_CFG_CRITICAL_METHOD` is not configured as `CPU_CRITICAL_METHOD_INT_DIS_EN`, which would re-enable interrupts upon the first call to `CPU_CRITICAL_EXIT()`, not the last call.

`CPU_CRITICAL_ENTER()` *should/must* always call `CPU_CRITICAL_EXIT()` once critical section protection is no longer needed.

EXAMPLE USAGE

```
CPU_SR_ALLOC();

CPU_CRITICAL_ENTER();
:
:          /* Code protected by critical sections ... */
:          /* ... from interrupts or concurrent access. */
:
CPU_CRITICAL_EXIT();
```


3-4-3 CPU_CRITICAL_EXIT()

Exits critical sections, restoring previous interrupt status and/or enabling interrupts.

FILES

Each specific processor's/compiler's `cpu.h`

PROTOTYPE

```
CPU_CRITICAL_EXIT();
```

ARGUMENTS

None.

RETURNED VALUE

None.

REQUIRED CONFIGURATION

None.

NOTES / WARNINGS

`CPU_CRITICAL_ENTER()/CPU_CRITICAL_EXIT()` should be used to protect critical sections of code from interrupted or concurrent access when no other protection mechanisms are available or appropriate. For example, system code that must be re-entrant but without use of a software lock should protect the code using CPU critical sections.

Since interrupts are disabled upon calling `CPU_CRITICAL_ENTER()` and are not re-enabled until after calling `CPU_CRITICAL_EXIT()`, interrupt and operating system context switching are postponed while all critical sections have not completely exited.

Critical sections can be nested any number of times as long as `CPU_CFG_CRITICAL_METHOD` is not configured as `CPU_CRITICAL_METHOD_INT_DIS_EN`, which would re-enable interrupts upon the first call to `CPU_CRITICAL_EXIT()`, not the last call.

`CPU_CRITICAL_EXIT()` *must* always call `CPU_CRITICAL_ENTER()` at the start of critical section protection.

EXAMPLE USAGE

```
CPU_SR_ALLOC();

CPU_CRITICAL_ENTER();
:
:           /* Code protected by critical sections ... */
:           /* ... from interrupts or concurrent access. */
:
CPU_CRITICAL_EXIT();
```

3-4-4 CPU_INT_DIS()

Saves current interrupt status, if processor/compiler capable, and then disables interrupts.

FILES

Each specific processor's/compiler's `cpu.h`

PROTOTYPE

```
CPU_INT_DIS();
```

ARGUMENTS

None.

RETURNED VALUE

None.

REQUIRED CONFIGURATION

None.

NOTES / WARNINGS

`CPU_INT_DIS()` should be defined based on the processor port's configured CPU critical section method, `CPU_CFG_CRITICAL_METHOD`; and may be defined with inline-assembly directly in `cpu.h`, or with calls to C functions defined in `cpu.c`, or calls to assembly subroutines defined in `cpu_a.asm` (or `cpu_a.s`). See also section 3-4.

EXAMPLE TEMPLATES

The following example templates assume corresponding functions are defined in either `cpu.c` or `cpu_a.asm`:

```
#if (CPU_CFG_CRITICAL_METHOD == CPU_CRITICAL_METHOD_INT_DIS_EN)
                                /* Disable interrupts.          */
#define CPU_INT_DIS() do { CPU_IntDis(); } while (0)
#endif

#if (CPU_CFG_CRITICAL_METHOD == CPU_CRITICAL_METHOD_STATUS_STK)
                                /* Push CPU status & disable interrupts.
*/
#define CPU_INT_DIS() do { CPU_SR_Push(); } while (0)
#endif

#if (CPU_CFG_CRITICAL_METHOD == CPU_CRITICAL_METHOD_STATUS_LOCAL)
                                /* Save CPU status & disable interrupts.
*/
#define CPU_INT_DIS() do { cpu_sr = CPU_SR_Save(); } while (0)
#endif
```

3-4-5 CPU_INT_EN()

Restores previous interrupt status and/or enables interrupts.

FILES

Each specific processor's/compiler's `cpu.h`

PROTOTYPE

```
CPU_INT_EN();
```

ARGUMENTS

None.

RETURNED VALUE

None.

REQUIRED CONFIGURATION

None.

NOTES / WARNINGS

`CPU_INT_EN()` should be defined based on the processor port's configured CPU critical section method, `CPU_CFG_CRITICAL_METHOD`; and may be defined with inline-assembly directly in `cpu.h`, or with calls to C functions defined in `cpu.c`, or calls to assembly subroutines defined in `cpu_a.asm` (or `cpu_a.s`). See also section 3-4.

EXAMPLE TEMPLATES

The following example templates assume corresponding functions are defined in either `cpu.c` or `cpu_a.asm`:

```
#if (CPU_CFG_CRITICAL_METHOD == CPU_CRITICAL_METHOD_INT_DIS_EN)
/* Enable interrupts. */
#define CPU_INT_EN() do { CPU_IntEn(); } while (0)
#endif

#if (CPU_CFG_CRITICAL_METHOD == CPU_CRITICAL_METHOD_STATUS_STK)
/* Pop CPU status. */
#define CPU_INT_EN() do { CPU_SR_Pop(); } while (0)
#endif

#if (CPU_CFG_CRITICAL_METHOD == CPU_CRITICAL_METHOD_STATUS_LOCAL)
/* Restore CPU status. */
#define CPU_INT_EN() do { CPU_SR_Restore(cpu_sr); } while (0)
#endif
```

μC/CPU Core Library

μC/CPU core library functions initialize μC/CPU, handle software exceptions, and include features such as counting the leading or trailing zeros in a word. These features are configured in `cpu_cfg.h` and defined in `cpu_core.c`.

4-1 μC/CPU CORE LIBRARY CONFIGURATION

The following core μC/CPU configurations must be configured in `cpu_cfg.h` :

CPU_CFG_LEAD_ZEROS_ASM_PRESENT	Implements counting leading zeros functionality in assembly (see section 4-2-3). This feature is enabled if the macro is <code>#define'd</code> in <code>cpu_cfg.h</code> (or <code>cpu.h</code>).
CPU_CFG_TRAIL_ZEROS_ASM_PRESENT	Implements counting trailing zeros functionality in assembly (see section 4-2-4). This feature is enabled if the macro is <code>#define'd</code> in <code>cpu_cfg.h</code> (or <code>cpu.h</code>).

4-2 μC/CPU CORE LIBRARY FUNCTIONS AND MACROS

4-2-1 CPU_Init()

Initializes the core CPU module.

FILES

cpu_core.h/cpu_core.c

PROTOTYPE

```
void CPU_Init (void);
```

ARGUMENTS

None.

RETURNED VALUE

None.

REQUIRED CONFIGURATION

None.

NOTES / WARNINGS

CPU_Init() must be called by application code prior to calling any other core CPU functions:

- CPU host name
- CPU timestamps
- CPU interrupts disabled time measurements

4-2-2 CPU_SW_EXCEPTION()

Traps an unrecoverable software exception.

FILES

cpu_core.h

PROTOTYPE

```
CPU_SW_EXCEPTION();
```

ARGUMENTS

err_rtn_val Error type and/or value of the calling function to return.

RETURNED VALUE

None.

REQUIRED CONFIGURATION

None.

NOTES / WARNINGS

Deadlocks the current code execution—whether multi-tasked/-processed/-threaded or single-threaded—when the current code execution cannot gracefully recover or report a fault or exception condition.

EXAMPLE USAGE

```
void Fnc1 (CPU_ERR *p_err)
{
    if (p_err == (CPU_ERR *)0) { /* If 'p_err' NULL, cannot return error ... */
        CPU_SW_EXCEPTION(;);      /* ... so trap invalid argument exception. */
    }
    ...
}
```

DEVELOPER-IMPLEMENTED EXAMPLES

CPU_SW_EXCEPTION() may be developer-implemented to output and/or handle any error or exception conditions; but since CPU_SW_EXCEPTION() is intended to trap unrecoverable software conditions, it is recommended that developer-implemented versions prevent execution of any code following calls to CPU_SW_EXCEPTION() by deadlocking the code.

```
#define CPU_SW_EXCEPTION(err_rtn_val)    \
    do {                                \
        Log(__FILE__, __LINE__); \
        CPU_SW_Exception();          \ /* SHOULD deadlock to prevent further code execution.
*/
    } while (0)
```

Listing 4-1 **Developer-implemented CPU_SW_EXCEPTION() with deadlock**

However, if execution of code following calls to CPU_SW_EXCEPTION() is required (e.g. for automated testing); it is recommended that the last statement in developer-implemented versions be to return from the current function to prevent possible software exceptions in the current function from triggering CPU and/or hardware exceptions. (Note that `err_rtn_val` in the return statement *must not* be enclosed in parentheses. This allows CPU_SW_EXCEPTION() to return from functions that return `void`, i.e. no return type or value.)

```
#define CPU_SW_EXCEPTION(err_rtn_val)    \
    do {                                \
        Log(__FILE__, __LINE__); \
        return err_rtn_val;          \ /* MUST NOT enclose 'err_rtn_val' in parentheses.
*/
    } while (0)
```

Listing 4-2 **Developer-implemented CPU_SW_EXCEPTION() with return**

4-2-3 CPU_CntLeadZerosXX()

Counts the number of contiguous, most-significant, leading zero bits in a data value.

FILES

`cpu_core.h/cpu_core.c` / Specific CPU/compiler `cpu_a.asm`

PROTOTYPES

```
CPU_DATA CPU_CntLeadZeros (CPU_DATA val);

CPU_DATA CPU_CntLeadZeros08 (CPU_INT08U val);
CPU_DATA CPU_CntLeadZeros16 (CPU_INT16U val);
CPU_DATA CPU_CntLeadZeros32 (CPU_INT32U val);
CPU_DATA CPU_CntLeadZeros64 (CPU_INT64U val);
```

ARGUMENTS

`val` Data value to count leading zero bits.

RETURNED VALUE

Number of contiguous, most-significant, leading zero bits in `val`.

REQUIRED CONFIGURATION

`CPU_CntLeadZeros()` available and implemented in `cpu_core.c` if `CPU_CFG_LEAD_ZEROS_ASM_PRESENT` is not `#define'd` in `cpu_cfg.h` (or `cpu.h`), but should be implemented in `cpu_a.asm` (or `cpu_a.s`) if `CPU_CFG_LEAD_ZEROS_ASM_PRESENT` is `#define'd` in `cpu_cfg.h` (or `cpu.h`) [see section 4-1].

Each `CPU_CntLeadZerosXX()` is available and implemented in `cpu_core.c` based on `CPU_CFG_DATA_SIZE_MAX` configuration as `#define'd` in `cpu.h` :

Function available: if CPU_CFG_DATA_SIZE_MAX configuration:

```
CPU_CntLeadZero08()  = CPU_WORD_SIZE_08
CPU_CntLeadZero16()  = CPU_WORD_SIZE_16
CPU_CntLeadZero32()  = CPU_WORD_SIZE_32
CPU_CntLeadZero64()  = CPU_WORD_SIZE_64
```

NOTES / WARNINGS

None.

EXAMPLE USAGE

```
CPU_DATA  val;
CPU_DATA  nbr_lead_zeros;

val       = 0x0643A718;
nbr_lead_zeros = CPU_CntLeadZeros(val);

nbr_lead_zeros = CPU_CntLeadZeros08((CPU_INT08U)val);
nbr_lead_zeros = CPU_CntLeadZeros16((CPU_INT16U)val);
nbr_lead_zeros = CPU_CntLeadZeros32((CPU_INT32U)val);
nbr_lead_zeros = CPU_CntLeadZeros64((CPU_INT64U)val);
```

4-2-4 CPU_CntTrailZerosXX()

Counts the number of contiguous, least-significant, trailing zero bits in a data value.

FILES

`cpu_core.h/cpu_core.c`

PROTOTYPES

```
CPU_DATA CPU_CntTrailZeros (CPU_DATA val);

CPU_DATA CPU_CntTrailZeros08 (CPU_INT08U val);
CPU_DATA CPU_CntTrailZeros16 (CPU_INT16U val);
CPU_DATA CPU_CntTrailZeros32 (CPU_INT32U val);
CPU_DATA CPU_CntTrailZeros64 (CPU_INT64U val);
```

ARGUMENTS

`val` Data value to count trailing zero bits.

RETURNED VALUE

Number of contiguous, least-significant, trailing zero bits in `val`.

REQUIRED CONFIGURATION

`CPU_CntTrailZeros()` available and implemented in `cpu_core.c` if `CPU_CFG_TRAIL_ZEROS_ASM_PRESENT` is not `#define'd` in `cpu_cfg.h` (or `cpu.h`), but should be implemented in `cpu_a.asm` (or `cpu_a.s`) if `CPU_CFG_TRAIL_ZEROS_ASM_PRESENT` is `#define'd` in `cpu_cfg.h` (or `cpu.h`) [see section 4-1].

Each `CPU_CntTrailZerosXX()` is available and implemented in `cpu_core.c` based on `CPU_CFG_DATA_SIZE_MAX` configuration as `#define'd` in `cpu.h` :

Function available: if CPU_CFG_DATA_SIZE_MAX configuration:

```
CPU_CntTrailZero08()   = CPU_WORD_SIZE_08
CPU_CntTrailZero16()  = CPU_WORD_SIZE_16
CPU_CntTrailZero32()  = CPU_WORD_SIZE_32
CPU_CntTrailZero64()  = CPU_WORD_SIZE_64
```

NOTES / WARNINGS

For non-zero values, the returned number of contiguous, least-significant, trailing zero bits is also equivalent to the bit position of the least-significant set bit.

EXAMPLE USAGE

```
CPU_DATA  val;
CPU_DATA  nbr_trail_zeros;

val       = 0x0643A718;
nbr_trail_zeros = CPU_CntTrailZeros(val);

nbr_trail_zeros = CPU_CntTrailZeros08((CPU_INT08U)val);
nbr_trail_zeros = CPU_CntTrailZeros16((CPU_INT16U)val);
nbr_trail_zeros = CPU_CntTrailZeros32((CPU_INT32U)val);
nbr_trail_zeros = CPU_CntTrailZeros64((CPU_INT64U)val);
```

µC/CPU Host Name

µC/CPU host name feature allows a target host to configure a name for itself. This may be used to uniquely identify the target in a system or network of inter-connected hosts. The CPU host name feature is available only if `CPU_CFG_NAME_EN` is `DEF_ENABLED` in `cpu_cfg.h`.

5-1 µC/CPU HOST NAME CONFIGURATION

The following µC/CPU host name configurations must be configured in `cpu_cfg.h` :

<code>CPU_CFG_NAME_EN</code>	Includes code to set and get a configured CPU host name. This feature may be configured to either <code>DEF_DISABLED</code> or <code>DEF_ENABLED</code> .
<code>CPU_CFG_NAME_SIZE</code>	Configures the maximum CPU name size (in number of ASCII characters, including the terminating <code>NULL</code> character).

5-2 μC/CPU HOST NAME FUNCTIONS

5-2-1 CPU_NameClr()

Clears the CPU host name.

FILES

cpu_core.h/cpu_core.c

PROTOTYPE

```
void CPU_NameClr (void);
```

ARGUMENTS

None.

RETURNED VALUE

None.

REQUIRED CONFIGURATION

Available only if CPU_CFG_NAME_EN is DEF_ENABLED in cpu_cfg.h (see section 5-1).

NOTES / WARNINGS

CPU_Init() must be called by application code prior to calling any other core CPU functions:

5-2-2 CPU_NameGet()

Gets the CPU host name.

FILES

`cpu_core.h/cpu_core.c`

PROTOTYPE

```
void CPU_NameGet (CPU_CHAR *p_name,  
                  CPU_ERR *p_err);
```

ARGUMENTS

p_name Pointer to an ASCII character array that will receive the return CPU host name ASCII string from this function.

p_err Pointer to variable that will receive the return error code from this function:

CPU_ERR_NONE
CPU_ERR_NULL_PTR

RETURNED VALUE

None.

REQUIRED CONFIGURATION

Available only if CPU_CFG_NAME_EN is DEF_ENABLED in `cpu_cfg.h` (see section 5-1).

NOTES / WARNINGS

The size of the ASCII character array that will receive the return CPU host name ASCII string must be greater than or equal to the current CPU host name's ASCII string size including the terminating NULL character; and should be greater than or equal to CPU_CFG_NAME_SIZE.

EXAMPLE USAGE

```
CPU_CHAR  *p_name;
CPU_ERR   err;

CPU_NameGet(p_name, &err);    /* Get CPU host name. */

if (err == CPU_ERR_NONE) {
    printf("CPU Host Name = %s", p_name);
} else {
    printf("COULD NOT GET CPU HOST NAME.");
}
```

5-2-3 CPU_NameSet()

Sets the CPU host name.

FILES

`cpu_core.h/cpu_core.c`

PROTOTYPE

```
void CPU_NameSet (const CPU_CHAR *p_name,  
                  CPU_ERR *p_err);
```

ARGUMENTS

p_name Pointer to an ASCII character string with CPU host name to set.

p_err Pointer to variable that will receive the return error code from this function:

CPU_ERR_NONE
CPU_ERR_NULL_PTR
CPU_ERR_NAME_SIZE

RETURNED VALUE

None.

REQUIRED CONFIGURATION

Available only if CPU_CFG_NAME_EN is DEF_ENABLED in `cpu_cfg.h` (see section 5-1).

NOTES / WARNINGS

p_name's ASCII string size, including the terminating NULL character, *must* be less than or equal to CPU_CFG_NAME_SIZE.

EXAMPLE USAGE

```
CPU_CHAR  *p_name;
CPU_ERR   err;

p_name = "CPU Host Target";

CPU_NameSet(p_name, &err);    /* Set CPU host name. */

if (err != CPU_ERR_NONE) {
    printf("COULD NOT SET CPU HOST NAME.");
}
```

μC/CPU Timestamps

μC/CPU timestamps emulate a real-time 32- or 64-bit timer using any size hardware (or software) timer. If the hardware (or software) timer used has the same (or greater) number of bits as the 32- or 64-bit CPU timestamps, then calls to `CPU_TS_Get()` functions return the timer value directly with no additional calculation overhead. But if the timer has less bits than the 32- or 64-bit CPU timestamps, `CPU_TS_Update()` must be called periodically by an application-/developer-defined function (see section 6-2-3) to accumulate timer counts into the 32- or 64-bit CPU timestamps. An application can then use CPU timestamps either as raw timer counts or converted to microseconds (see section 6-2-8 and section 6-2-9).

Note that if either the CPU timestamp feature or the interrupts disable time measurement feature is enabled (see section 6-1 and section 7-1), then the application/developer must provide CPU timestamp timer functions (see section 6-2-4 “`CPU_TS_TmrInit()`” on page 45 and section 6-2-5 “`CPU_TS_TmrRd()`” on page 47). In addition, the CPU timestamp timer word size must be appropriately configured via `CPU_CFG_TS_TMR_SIZE` in `cpu_cfg.h` :

<code>CPU_WORD_SIZE_08</code>	8-bit word size
<code>CPU_WORD_SIZE_16</code>	16-bit word size
<code>CPU_WORD_SIZE_32</code>	32-bit word size
<code>CPU_WORD_SIZE_64</code>	64-bit word size

This configures the size of the `CPU_TS_TMR` data type (see section 6-2-5). Since the CPU timestamp timer must not have less bits than the `CPU_TS_TMR` data type; `CPU_CFG_TS_TMR_SIZE` must be configured so that all bits in `CPU_TS_TMR` data type are significant. In other words, if the size of the CPU timestamp timer is not a binary-multiple of 8-bit octets (e.g. 20-bits or even 24-bits), then the next lower, binary-multiple octet word size should be configured (e.g. to 16-bits). However, the minimum supported word size for CPU timestamp timers is 8-bits.

6-1 μC/CPU TIMESTAMPS CONFIGURATION

The following μC/CPU timestamps configurations must be configured in `cpu_cfg.h` :

<code>CPU_CFG_TS_32_EN</code>	Includes 32-bit CPU timestamp functionality (see section 6-2-1). This feature may be configured to either <code>DEF_DISABLED</code> or <code>DEF_ENABLED</code> .
<code>CPU_CFG_TS_64_EN</code>	Includes 64-bit CPU timestamp functionality (see section 6-2-2). This feature may be configured to either <code>DEF_DISABLED</code> or <code>DEF_ENABLED</code> .
<code>CPU_CFG_TS_TMR_SIZE</code>	Configures the CPU timestamp's hardware or software timer word size (see Chapter 6, on page 38).

6-2 μC/CPU TIMESTAMPS FUNCTIONS

6-2-1 CPU_TS_Get32()

Gets current 32-bit CPU timestamp.

FILES

cpu_core.h/cpu_core.c

PROTOTYPE

```
CPU_TS32 CPU_TS_Get32 (void);
```

ARGUMENTS

None.

RETURNED VALUE

None.

REQUIRED CONFIGURATION

Available only if CPU_CFG_TS_32_EN is DEF_ENABLED in `cpu_cfg.h` (see section 6-1).

NOTES / WARNINGS

The amount of time measured by CPU timestamps is calculated by either of the following equations:

$$\text{Time measured} = \text{Number timer counts} * \text{Timer period}$$

Number timer counts	Number of timer counts measured
Timer period	Timer's period in some units of (fractional) seconds
Time measured	Amount of time measured, in same units of (fractional) seconds as the Timer period

Time measured = Number timer counts / Timer frequency

Number timer counts	Number of timer counts measured
Timer frequency	Timer's frequency in some units of counts per second
Time measured	Amount of time measured, in seconds

EXAMPLE USAGE

```
CPU_TS32 ts32;  
  
ts32 = CPU_TS_Get32(); /* Get current 32-bit CPU timestamp. */
```


6-2-2 CPU_TS_Get64()

Gets current 64-bit CPU timestamp.

FILES

cpu_core.h/cpu_core.c

PROTOTYPE

```
CPU_TS32 CPU_TS_Get64 (void);
```

ARGUMENTS

None.

RETURNED VALUE

None.

REQUIRED CONFIGURATION

Available only if CPU_CFG_TS_64_EN is DEF_ENABLED in cpu_cfg.h (see section 6-1).

NOTES / WARNINGS

The amount of time measured by CPU timestamps is calculated by either of the following equations:

$$\text{Time measured} = \text{Number timer counts} * \text{Timer period}$$

Number timer counts	Number of timer counts measured
Timer period	Timer's period in some units of (fractional) seconds
Time measured	Amount of time measured, in same units of (fractional) seconds as the Timer period

Time measured = Number timer counts / Timer frequency

Number timer counts	Number of timer counts measured
Timer frequency	Timer's frequency in some units of counts per second
Time measured	Amount of time measured, in seconds

EXAMPLE USAGE

```
CPU_TS64  ts64;  
  
ts64 = CPU_TS_Get64(); /* Get current 64-bit CPU timestamp. */
```

6-2-3 CPU_TS_Update()

Updates current 32- and 64-bit CPU timestamps.

FILES

cpu_core.h/cpu_core.c

PROTOTYPE

```
void CPU_TS_Update (void);
```

ARGUMENTS

None.

RETURNED VALUE

None.

REQUIRED CONFIGURATION

Available only if either CPU_CFG_TS_32_EN or CPU_CFG_TS_64_EN is DEF_ENABLED in cpu_cfg.h (see section 6-1).

NOTES / WARNINGS

CPU timestamps *must* be updated periodically by some application (or BSP) time handler in order to adequately maintain the CPU timestamps' time and *must* be updated more frequently than the CPU timestamp timer overflows; otherwise, CPU timestamps will lose time.

EXAMPLE USAGE

```
void AppPeriodicTimeHandler (void)
{
    :
    CPU_TS_Update(); /* Update current CPU timestamps. */
    :
}
```

6-2-4 CPU_TS_TmrInit()

Application-defined function to initialize and start the CPU timestamp's (hardware or software) timer.

FILES

cpu_core.h / Application's cpu_bsp.c

PROTOTYPE

```
void CPU_TS_TmrInit (void);
```

ARGUMENTS

None.

RETURNED VALUE

None.

REQUIRED CONFIGURATION

CPU_TS_TmrInit() is an application/BSP function that *must* be defined by the developer if either of the following CPU features is enabled in cpu_cfg.h :

- CPU timestamps when either CPU_CFG_TS_32_EN or CPU_CFG_TS_64_EN is DEF_ENABLED (see section 6-1)
- CPU interrupts disabled time measurements when CPU_CFG_INT_DIS_MEAS_EN is #define'd (see section 7-1)

NOTES / WARNINGS

CPU timestamp timer count values must be returned via word-size-configurable CPU_TS_TMR data type. If timer has more bits, truncate timer values' higher-order bits greater than the configured CPU_TS_TMR timestamp timer data type word size. However, since the timer must not have less bits than the configured CPU_TS_TMR timestamp timer data type word size; CPU_CFG_TS_TMR_SIZE must be configured so that all bits in CPU_TS_TMR data

type are significant. In other words, if timer size is not a binary-multiple of 8-bit octets (e.g., 20-bits or even 24-bits), then the next lower, binary-multiple octet word size should be configured (e.g. to 16-bits). However, the minimum supported word size for CPU timestamp timers is 8-bits.

CPU timestamp timer should be an ‘up’ counter whose values increase with each time count. If timer is a ‘down’ counter whose values decrease with each time count, then the returned timer value must be ones-complemented.

When applicable, CPU timestamp timer period should be less than the typical measured time but must be less than the maximum measured time; otherwise, timer resolution inadequate to measure desired times.

EXAMPLE TEMPLATE

```
void CPU_TS_TmrInit (void)
{
    /* Insert code to initialize/start CPU timestamp timer. */ ;
}
```

6-2-5 CPU_TS_TmrRd()

Application-defined function to get current CPU timestamp timer count.

FILES

`cpu_core.h` / Application's `cpu_bsp.c`

PROTOTYPE

```
CPU_TS_TMR CPU_TS_TmrRd (void);
```

ARGUMENTS

None.

RETURNED VALUE

CPU timestamp timer count value.

REQUIRED CONFIGURATION

`CPU_TS_TmrRd()` is an application/BSP function that *must* be defined by the developer if either of the following CPU features is enabled in `cpu_cfg.h` :

- CPU timestamps when either `CPU_CFG_TS_32_EN` or `CPU_CFG_TS_64_EN` is `DEF_ENABLED` (see section 6-1)
- CPU interrupts disabled time measurements when `CPU_CFG_INT_DIS_MEAS_EN` is `#define'd` (see section 7-1)

NOTES / WARNINGS

CPU timestamp timer count values must be returned via word-size-configurable `CPU_TS_TMR` data type. If timer has more bits, truncate timer values' higher-order bits greater than the configured `CPU_TS_TMR` timestamp timer data type word size. However, since the timer must not have less bits than the configured `CPU_TS_TMR` timestamp timer data type word size; `CPU_CFG_TS_TMR_SIZE` must be configured so that all bits in `CPU_TS_TMR` data type are significant. In other words, if timer size is not a binary-multiple of 8-bit octets (e.g.

20-bits or even 24-bits), then the next lower, binary-multiple octet word size should be configured (e.g. to 16-bits). However, the minimum supported word size for CPU timestamp timers is 8-bits.

CPU timestamp timer should be an ‘up’ counter whose values increase with each time count. If timer is a ‘down’ counter whose values decrease with each time count, then the returned timer value must be ones-complemented.

When applicable, CPU timestamp timer period should be less than the typical measured time but must be less than the maximum measured time; otherwise, timer resolution inadequate to measure desired times.

EXAMPLE TEMPLATE

```
CPU_TS_TMR CPU_TS_TmrRd (void)
{
    CPU_TS_TMR ts_tmr_cnts;

    ...
    ts_tmr_cnts = /* Insert code to get/return CPU timestamp timer counts. */ ;
    ...

    return (ts_tmr_cnts);
}
```

16-BIT UP TIMER EXAMPLE

```
CPU_TS_TMR CPU_TS_TmrRd (void)
{
    CPU_TS_TMR ts_tmr_cnts; /* sizeof(CPU_TS_TMR) = 16 bits */

    ts_tmr_cnts = /* Insert code to read 16-bit up timer value. */ ;

    return (ts_tmr_cnts);
}
```

16-BIT DOWN TIMER EXAMPLE

```
CPU_TS_TMR CPU_TS_TmrRd (void)
{
    CPU_INT16U  tmr_val;
    CPU_TS_TMR  ts_tmr_cnts; /* sizeof(CPU_TS_TMR) = 16 bits */

    tmr_val      =          /* Insert code to read 16-bit down timer value. */ ;
    ts_tmr_cnts = ~tmr_val; /* Ones-complement 16-bit down timer value. */

    return (ts_tmr_cnts);
}
```

32-BIT UP TIMER EXAMPLE

```
CPU_TS_TMR CPU_TS_TmrRd (void)
{
    CPU_TS_TMR  ts_tmr_cnts; /* sizeof(CPU_TS_TMR) = 32 bits */

    ts_tmr_cnts = /* Insert code to read 32-bit up timer value. */ ;

    return (ts_tmr_cnts);
}
```

48-BIT DOWN TIMER EXAMPLE

```
CPU_TS_TMR CPU_TS_TmrRd (void)
{
    CPU_INT64U  tmr_val;
    CPU_TS_TMR  ts_tmr_cnts; /* sizeof(CPU_TS_TMR) = 32 bits */

    tmr_val      =          /* Insert code to read 48-bit down timer value. */ ;
    ts_tmr_cnts = (CPU_TS_TMR)tmr_val; /* Truncate 48-bit timer value to 32-bit timestamp ... */
                                      /* ... timer data type. */
    ts_tmr_cnts = ~ts_tmr_cnts; /* Ones-complement truncated down timer value. */

    return (ts_tmr_cnts);
}
```


6-2-6 CPU_TS_TmrFreqGet()

Gets CPU timestamp's timer frequency, in Hertz.

FILES

`cpu_core.h/cpu_core.c`

PROTOTYPE

```
CPU_TS_TMR_FREQ CPU_TS_TmrFreqGet (CPU_ERR *p_err);
```

ARGUMENTS

p_err Pointer to variable that will receive the return error code from this function:

CPU_ERR_NONE
CPU_ERR_NULL_PTR

RETURNED VALUE

CPU timestamp's timer frequency (in Hertz), if no errors;

0, otherwise.

REQUIRED CONFIGURATION

Available only if either of the following CPU features is enabled in `cpu_cfg.h` :

- CPU timestamps when either `CPU_CFG_TS_32_EN` or `CPU_CFG_TS_64_EN` is `DEF_ENABLED` (see section 6-1)
- CPU interrupts disabled time measurements when `CPU_CFG_INT_DIS_MEAS_EN` is `#define'd` (see section 7-1)

NOTES / WARNINGS

None.

EXAMPLE USAGE

```
CPU_TS_TMR_FREQ  freq_hz;
CPU_ERR          err;

freq_hz = CPU_TS_TmrFreqGet(&err); /* Get CPU timestamp timer frequency. */

if (err == CPU_ERR_NONE) {
    printf("CPU Timestamp Timer Frequency = %d", freq_hz);
} else {
    printf("CPU TIMESTAMP TIMER FREQUENCY NOT AVAILABLE.");
}
```

6-2-7 CPU_TS_TmrFreqSet()

Sets CPU timestamp's timer frequency, in Hertz.

FILES

`cpu_core.h/cpu_core.c`

PROTOTYPE

```
void CPU_TS_TmrFreqSet (CPU_TS_TMR_FREQ freq_hz);
```

ARGUMENTS

freq_hz Frequency (in Hertz) to set for CPU timestamp's timer.

RETURNED VALUE

None.

REQUIRED CONFIGURATION

Available only if either of the following CPU features is enabled in `cpu_cfg.h` :

- CPU timestamps when either `CPU_CFG_TS_32_EN` or `CPU_CFG_TS_64_EN` is `DEF_ENABLED` (see section 6-1)
- CPU interrupts disabled time measurements when `CPU_CFG_INT_DIS_MEAS_EN` is `#define'd` (see section 7-1)

NOTES / WARNINGS

CPU timestamp timer frequency is not required for internal CPU timestamp operations and may optionally be configured by application/BSP initialization functions for use with optional `CPU_TS_to_uSec()` functions to convert CPU timestamps from timer counts into microseconds (see section 6-2-8 “`CPU_TS32_to_uSec()`” on page 54 and section 6-2-9 “`CPU_TS64_to_uSec()`” on page 56).

EXAMPLE USAGE

```
CPU_TS_TmrFreqSet(2500000u); /* Set CPU timestamp timer frequency to 2.5 MHz. */
```

6-2-8 CPU_TS32_to_uSec()

Application-defined function to convert a 32-bit CPU timestamp from timer counts to microseconds.

FILES

cpu_core.h / Application's cpu_bsp.c

PROTOTYPE

```
CPU_INT64U CPU_TS32_to_uSec (CPU_TS32 ts_cnts);
```

ARGUMENTS

ts_cnts 32-bit CPU timestamp (in CPU timestamp timer counts).

RETURNED VALUE

Converted 32-bit CPU timestamp (in microseconds).

REQUIRED CONFIGURATION

CPU_TS32_to_uSec() is an application/BSP function that may be optionally defined by the developer if CPU_CFG_TS_32_EN is DEF_ENABLED in cpu_cfg.h (see section 6-1).

NOTES / WARNINGS

The amount of time measured by CPU timestamps is calculated by either of the following equations:

Time measured = Number timer counts * Timer period * 10⁶ microseconds

Time measured = (Number timer counts / Timer frequency) * 10⁶ microseconds

Number timer counts	Number of timer counts measured
Timer period	Timer's period in some units of (fractional) seconds
Timer frequency	Timer's frequency in some units of counts per second
Time measured	Amount of time measured, in microseconds

Developer-defined `CPU_TS32_to_uSec()` implementations may convert any number of `CPU_TS32` bits, up to 32, into microseconds.

EXAMPLE TEMPLATE

```
CPU_INT64U CPU_TS32_to_uSec (CPU_TS32 ts_cnts)
{
    CPU_INT64U ts_usec;

    :
    : /* Insert code to convert 32-bit CPU timestamp into microseconds. */
    :

    return (ts_usec);
}
```

6-2-9 CPU_TS64_to_uSec()

Application-defined function to convert a 64-bit CPU timestamp from timer counts to microseconds.

FILES

cpu_core.h / Application's cpu_bsp.c

PROTOTYPE

```
CPU_INT64U CPU_TS64_to_uSec (CPU_TS64 ts_cnts);
```

ARGUMENTS

ts_cnts 64-bit CPU timestamp (in CPU timestamp timer counts).

RETURNED VALUE

Converted 64-bit CPU timestamp (in microseconds).

REQUIRED CONFIGURATION

CPU_TS64_to_uSec() is an application/BSP function that may be optionally defined by the developer if CPU_CFG_TS_64_EN is DEF_ENABLED in cpu_cfg.h (see section 6-1).

NOTES / WARNINGS

The amount of time measured by CPU timestamps is calculated by either of the following equations:

Time measured = Number timer counts * Timer period * 10⁶ microseconds

Time measured = (Number timer counts / Timer frequency) * 10⁶ microseconds

Number timer counts	Number of timer counts measured
Timer period	Timer's period in some units of (fractional) seconds
Timer frequency	Timer's frequency in some units of counts per second
Time measured	Amount of time measured, in microseconds

Developer-defined `CPU_TS64_to_uSec()` implementations may convert any number of `CPU_TS64` bits, up to 64, into microseconds.

EXAMPLE TEMPLATE

```
CPU_INT64U CPU_TS64_to_uSec (CPU_TS64 ts_cnts)
{
    CPU_INT64U ts_usec;

    :
    : /* Insert code to convert 64-bit CPU timestamp into microseconds. */
    :

    return (ts_usec);
}
```


μC/CPU Interrupts Disabled Time Measurement

μC/CPU can measure the maximum amount of time interrupts are disabled during calls to `CPU_CRITICAL_ENTER()/CPU_CRITICAL_EXIT()` is measured and saved. There are two maximum interrupts disable time measurements, one resetable and the other non-resetable, both measured in units of CPU timestamp timer counts.

The interrupts disabled time measurement feature is available only if `CPU_CFG_INT_DIS_MEAS_EN` is `DEF_ENABLED` in `cpu_cfg.h`. Note that this feature requires that the application/developer provide CPU timestamp timer functions (see section 6-2-4 “`CPU_TS_TmrInit()`” on page 45 and section 6-2-5 “`CPU_TS_TmrRd()`” on page 47).

7-1 μC/CPU INTERRUPTS DISABLED TIME MEASUREMENT CONFIGURATION

The following μC/CPU interrupts disabled time measurement configurations must be configured in `cpu_cfg.h` :

<code>CPU_CFG_INT_DIS_MEAS_EN</code>	Includes code to measure and return maximum interrupts disabled time. This feature is enabled if the macro is <code>#define'd</code> in <code>cpu_cfg.h</code> .
<code>CPU_CFG_INT_DIS_MEAS_OVRHD_NBR</code>	Configures the number of times to measure and calculate the interrupts disabled time measurement overhead.

7-2 µC/CPU INTERRUPTS DISABLED TIME MEASUREMENT FUNCTIONS

7-2-1 CPU_IntDisMeasMaxGet()

Gets (non-resetable) maximum interrupts disabled time.

FILES

cpu_core.h/cpu_core.c

PROTOTYPE

```
CPU_TS_TMR CPU_IntDisMeasMaxGet (void);
```

ARGUMENTS

None.

RETURNED VALUE

(Non-resetable) maximum interrupts disabled time (in CPU timestamp timer counts).

REQUIRED CONFIGURATION

Available only if CPU_CFG_INT_DIS_MEAS_EN is #define'd in cpu_cfg.h (see section 7-1).

NOTES / WARNINGS

None.

EXAMPLE USAGE

```
CPU_TS_TMR time_max_cnts;

time_max_cnts = CPU_IntDisMeasMaxGet(); /* Get maximum interrupts disabled time. */
```

7-2-2 CPU_IntDisMeasMaxCurGet()

Gets current/resetable maximum interrupts disabled time.

FILES

cpu_core.h/cpu_core.c

PROTOTYPE

```
CPU_TS_TMR CPU_IntDisMeasMaxCurGet (void);
```

ARGUMENTS

None.

RETURNED VALUE

Current maximum interrupts disabled time (in CPU timestamp timer counts).

REQUIRED CONFIGURATION

Available only if CPU_CFG_INT_DIS_MEAS_EN is #define'd in cpu_cfg.h (see section 7-1).

NOTES / WARNINGS

None.

EXAMPLE USAGE

```
CPU_TS_TMR time_max_cnts;  
  
time_max_cnts = CPU_IntDisMeasMaxCurGet(); /* Get current maximum interrupts disabled time. */
```

7-2-3 CPU_IntDisMeasMaxCurReset()

Resets current maximum interrupts disabled time.

FILES

cpu_core.h/cpu_core.c

PROTOTYPE

```
CPU_TS_TMR CPU_IntDisMeasMaxCurReset (void);
```

ARGUMENTS

None.

RETURNED VALUE

Maximum interrupts disabled time (in CPU timestamp timer counts) before resetting.

REQUIRED CONFIGURATION

Available only if CPU_CFG_INT_DIS_MEAS_EN is #define'd in cpu_cfg.h (see section 7-1).

NOTES / WARNINGS

None.

EXAMPLE USAGE

```
CPU_TS_TMR time_max_cnts;

time_max_cnts = CPU_IntDisMeasMaxCurReset(); /* Reset current maximum interrupts disabled time.
*/
```

Appendix

A

μC/CPU Licensing Policy

You need to obtain an “Object Code Distribution License” to embed μC/CPU in a product that is sold with the intent to make a profit. Each individual product (*i.e.*, your product) requires its own license, but the license allows you to distribute an unlimited number of units for the life of your product. Please indicate the processor type(s) (*i.e.*, ARM7, ARM9, MCF5272, MicroBlaze, Nios II, PPC, *etc.*) that you intend to use.

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