AN496: HID USB-to-SMBus API Specification

The Silicon Labs HID USB-to-SMBus interface library provides a simple API to configure and operate CP2112 devices.

The library provides interface abstraction so that users can develop their application without writing any USB HID Code. C libraries implementing the CP2112 Interface Specification are provided for Windows 2000 and later and Mac OS X 10.5 and later. Similarly, various include files are provided to import library functions into C# .NET, and Visual Basic .NET. Refer to the table in 1. Include Files for complete details.

KEY POINTS

• The CP2112 library enables application development and device configuration on multiple platforms and operating systems.
1. Include Files

The files required for application development using the CP2112 API are listed in the following table:

<table>
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<tr>
<th>Operating System</th>
<th>Library</th>
<th>Include Files</th>
<th>Version</th>
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<tr>
<td>Windows 2000 and later</td>
<td>SLABHIDtoSMBus.dll$^1$</td>
<td>SLABCP2112.h (C/C++)</td>
<td>1.2</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SLABCP2112.cs (C# .NET)</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>SLABCP2112.vb (VB .NET)</td>
<td></td>
</tr>
<tr>
<td>Mac OS X 10.5 and later</td>
<td>libSLABHIDtoSMBus.dylib</td>
<td>SLABCP2112.h (C, C++, Obj-C)</td>
<td>1.0</td>
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<tr>
<td></td>
<td></td>
<td>Types.h (Compatibility)</td>
<td></td>
</tr>
<tr>
<td>Linux$^2$</td>
<td>libslabhidtosmbus.so.1.0$^3$</td>
<td>SLABCP2112.h (C, C++, Obj-C)</td>
<td>1.0</td>
</tr>
</tbody>
</table>

Note:

1. Requires SLABHIDDevice.dll version 1.5 during runtime.
2. Library binaries are provided for Ubuntu 16.x for i386 and amd64 (32-bit and 64-bit x86 processors). Source packages are available in the CP2112 Software Development Kit (www.silabs.com/interface-software), which can be modified and compiled for additional platforms.
3. Requires the libslabhiddevice.so.1.0 HID library during runtime.
# 2. API Functions

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<td>Returns a string for a device by index</td>
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<td>Returns an indexed USB string descriptor by device object pointer (Windows Only)</td>
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<td>Returns the VID, PID, and release number for a device by index</td>
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<tr>
<td>HidSmbus_GetOpenedAttributes()</td>
<td>Returns the VID, PID and release number for a device by device object pointer</td>
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<td>Opens a device and returns a device object pointer</td>
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<td>HidSmbus_Close()</td>
<td>Cancels pending IO and closes a device</td>
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<td>HidSmbus_IsOpened()</td>
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<td>HidSmbus_ReadRequest()</td>
<td>Initiates a fixed length read request to the desired slave device</td>
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<tr>
<td>HidSmbus_AddressReadRequest()</td>
<td>Initiates a fixed length read request to the desired slave device specifying the memory address to read</td>
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<td>HidSmbus_GetReadResponse()</td>
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<tr>
<td>HidSmbus_WriteRequest()</td>
<td>Initiates a write request to the desired slave device</td>
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<td>HidSmbus_TransferStatusRequest()</td>
<td>Requests the status of the current read or write request</td>
</tr>
<tr>
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<td>Returns the status of the current read or write request</td>
</tr>
<tr>
<td>HidSmbus_CancelTransfer()</td>
<td>Cancels the current read or write request</td>
</tr>
<tr>
<td>HidSmbus_CancelIo()</td>
<td>Cancels pending HID reads and writes (Windows Only)</td>
</tr>
<tr>
<td>HidSmbus_SetTimeouts()</td>
<td>Sets the response timeouts for a device</td>
</tr>
<tr>
<td>HidSmbus_GetTimeouts()</td>
<td>Gets the response timeouts for a device</td>
</tr>
<tr>
<td>HidSmbus_SetSmbusConfig()</td>
<td>Sets the bit rate, master address, timeouts, and transfer settings</td>
</tr>
<tr>
<td>HidSmbus_GetSmbusConfig()</td>
<td>Gets the bit rate, master address, timeouts, and transfer settings</td>
</tr>
<tr>
<td>HidSmbus_Reset()</td>
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<tr>
<td>HidSmbus_SetGpioConfig()</td>
<td>Sets GPIO direction and mode configuration</td>
</tr>
<tr>
<td>HidSmbus_GetGpioConfig()</td>
<td>Gets GPIO direction and mode configuration</td>
</tr>
<tr>
<td>HidSmbus_ReadLatch()</td>
<td>Gets the GPIO latch value</td>
</tr>
<tr>
<td>HidSmbus_WriteLatch()</td>
<td>Sets the GPIO latch value using a bitmask</td>
</tr>
<tr>
<td>HidSmbus_GetPartNumber()</td>
<td>Gets the device part number and version</td>
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<tr>
<td>HidSmbus_GetLibraryVersion()</td>
<td>Gets the DLL Library version</td>
</tr>
<tr>
<td>HidSmbus_GetHidLibraryVersion()</td>
<td>Gets the HID Device Interface Library version</td>
</tr>
<tr>
<td>HidSmbus_GetHidGuid()</td>
<td>Gets the HID GUID (Windows® only)</td>
</tr>
</tbody>
</table>
2.1 HidSmbus_GetNumDevices

Description: This function returns the number of devices connected to the host with matching vendor and product ID (VID, PID).

Prototype: 

```c
HID_SMBUS_STATUS HidSmbus_GetNumDevices (DWORD* numDevices, WORD vid, WORD pid)
```

Parameters:

1. numDevices — returns the number of devices connected on return.
2. vid — filters device results by vendor ID. If both vid and pid are set to 0x0000, then HID devices will not be filtered by VID/PID.
3. pid — filters device results by product ID. If both vid and pid are set to 0x0000, then HID devices will not be filtered by VID/PID.

Return Value: 

- HID_SMBUS_SUCCESS
- HID_SMBUS_INVALID_PARAMETER

2.2 HidSmbus_GetString

Description: This function returns a null-terminated vendor ID string, product ID string, serial string, device path string, manufacturer string, or product string for the device specified by an index passed in deviceNum. The index for the first device is 0, and the last device is the value returned by HidSmbus_GetNumDevices() - 1.

Prototype: 

```c
HID_SMBUS_STATUS HidSmbus_GetString (DWORD deviceNum, WORD vid, WORD pid, char* deviceString, DWORD options)
```

Parameters:

1. deviceNum — is the index of the device for which the string is desired.
2. vid — filters device results by vendor ID. If both vid and pid are set to 0x0000, then HID devices will not be filtered by VID/PID.
3. pid — filters device results by product ID. If both vid and pid are set to 0x0000, then HID devices will not be filtered by VID/PID.
4. deviceString — is a variable of type HID_SMBUS_DEVICE_STR, which will contain a null-terminated ASCII device string on return. The string is 260 bytes on Windows and Linux and 512 bytes on Mac OS X.
5. options — determines if deviceString will contain a vendor ID string, product ID string, serial string, device path string, manufacturer string, or product string.

<table>
<thead>
<tr>
<th>Definition</th>
<th>Value</th>
<th>Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>HID_SMBUS_GET_VID_STR</td>
<td>0x01</td>
<td>5</td>
<td>Vendor ID</td>
</tr>
<tr>
<td>HID_SMBUS_GET_PID_STR</td>
<td>0x02</td>
<td>5</td>
<td>Product ID</td>
</tr>
<tr>
<td>HID_SMBUS_GET_PATH_STR</td>
<td>0x03</td>
<td>260/512</td>
<td>Device path</td>
</tr>
<tr>
<td>HID_SMBUS_GET_SERIAL_STR</td>
<td>0x04</td>
<td>256</td>
<td>Serial string</td>
</tr>
<tr>
<td>HID_SMBUS_GET_MANUFACTURER_STR</td>
<td>0x05</td>
<td>256</td>
<td>Manufacturer string</td>
</tr>
<tr>
<td>HID_SMBUS_GET_PRODUCT_STR</td>
<td>0x06</td>
<td>256</td>
<td>Product string</td>
</tr>
</tbody>
</table>

Return Value: 

- HID_SMBUS_SUCCESS
- HID_SMBUS_DEVICE_NOT_FOUND
- HID_SMBUS_INVALID_PARAMETER
- HID_SMBUSDEVICE_ACCESS_ERROR
2.3 HidSmbus_GetOpenedString

**Description**: This function returns a null-terminated vendor ID string, product ID string, serial string, device path string, manufacturer string, or product string for the device specified by `device`.

**Prototype**:

```c
HID_SMBUS_STATUS HidSmbus_GetOpenedString (HID_SMBUS_DEVICE device, char* deviceString, DWORD options)
```

**Parameters**:
1. `device`—is the device object pointer as returned by `HidSmbus_Open()`.
2. `deviceString`—is a variable of type `HID_SMBUS_DEVICE_STR`, which will contain a null-terminated ASCII device string on return. The string is 260 bytes on Windows and Linux and 512 bytes on Mac OS X.
3. `options`—determines if `deviceString` will contain a vendor ID string, product ID string, serial string, device path string, manufacturer string, or product string.

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<th>Definition</th>
<th>Value</th>
<th>Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>HID_SMBUS_GET_VID_STR</td>
<td>0x01</td>
<td>5</td>
<td>Vendor ID</td>
</tr>
<tr>
<td>HID_SMBUS_GET_PID_STR</td>
<td>0x02</td>
<td>5</td>
<td>Product ID</td>
</tr>
<tr>
<td>HID_SMBUS_GET_PATH_STR</td>
<td>0x03</td>
<td>260/512</td>
<td>Device path</td>
</tr>
<tr>
<td>HID_SMBUS_GET_SERIAL_STR</td>
<td>0x04</td>
<td>256</td>
<td>Serial string</td>
</tr>
<tr>
<td>HID_SMBUS_GET_MANUFACTURER_STR</td>
<td>0x05</td>
<td>256</td>
<td>Manufacturer string</td>
</tr>
<tr>
<td>HID_SMBUS_GET_PRODUCT_STR</td>
<td>0x06</td>
<td>256</td>
<td>Product string</td>
</tr>
</tbody>
</table>

**Return Value**: `HID_SMBUS_STATUS`

- `HID_SMBUS_SUCCESS`
- `HID_SMBUS_INVALID_DEVICE_OBJECT`
- `HID_SMBUS_INVALID_PARAMETER`
- `HID_SMBUS_DEVICE_ACCESS_ERROR`

2.4 HidSmbus_GetIndexedString

**Description**: This function returns a null-terminated USB string descriptor for the device specified by an index passed in `deviceNum` (Windows Only).

**Prototype**:

```c
HID_SMBUS_STATUS HidSmbus_GetIndexedString (DWORD deviceNum, WORD vid, WORD pid, DWORD stringIndex, char* deviceString)
```

**Parameters**:
1. `deviceNum`—is the index of the device for which the string is desired.
2. `vid`—filters device results by vendor ID. If both `vid` and `pid` are set to 0x0000, then HID devices will not be filtered by VID/PID.
3. `pid`—filters device results by product ID. If both `vid` and `pid` are set to 0x0000, then HID devices will not be filtered by VID/PID.
4. `stringIndex`—specifies the device-specific index of the USB string descriptor to return.
5. `deviceString`—is a variable of type `HID_SMBUS_DEVICE_STR` (260-byte ASCII string), which will contain a null-terminated device descriptor string on return.

**Return Value**: `HID_SMBUS_STATUS`

- `HID_SMBUS_SUCCESS`
- `HID_SMBUS_DEVICE_NOT_FOUND`
- `HID_SMBUS_INVALID_PARAMETER`
- `HID_SMBUS_DEVICE_ACCESS_ERROR`
2.5 HidSmbus_GetOpenedIndexedString

Description: This function returns a null-terminated USB string descriptor for the device specified by device (Windows Only).

Prototype: HID_SMBUS_STATUS HidSmbus_GetOpenedIndexedString (HID_SMBUS_DEVICE device, DWORD stringIndex, char* deviceString)

Parameters:
1. deviceNum—is the device object pointer as returned by HidSmbus_Open().
2. stringIndex—specifies the device-specific index of the USB string descriptor to return.
3. deviceString—is a variable of type HID_SMBUS_DEVICE_STR (260-byte ASCII string), which will contain a NULL terminated device descriptor string on return.

Return Value:
- HID_SMBUS_STATUS
  - HID_SMBUS_SUCCESS
  - HID_SMBUS_INVALID_DEVICE_OBJECT
  - HID_SMBUS_INVALID_PARAMETER
  - HID_SMBUS_DEVICE_ACCESS_ERROR

2.6 HidSmbus_GetAttributes

Description: This function returns the device vendor ID, product ID, and release number for the device specified by an index passed in deviceNum.

Prototype: HID_SMBUS_STATUS HidSmbus_GetAttributes (DWORD deviceNum, WORD vid, WORD pid, WORD* deviceVid, WORD* devicePid, WORD* deviceReleaseNumber)

Parameters:
1. deviceNum—is the index of the device for which the string is desired.
2. vid—filters device results by vendor ID. If both vid and pid are set to 0x0000, then HID devices will not be filtered by VID/PID.
3. pid—filters device results by product ID. If both vid and pid are set to 0x0000, then HID devices will not be filtered by VID/PID.
4. deviceVid—returns the device vendor ID.
5. devicePid—returns the device product ID.
6. deviceReleaseNumber—returns the USB device release number in binary-coded decimal.

Return Value:
- HID_SMBUS_STATUS
  - HID_SMBUS_SUCCESS
  - HID_SMBUS_DEVICE_NOT_FOUND
  - HID_SMBUS_INVALID_PARAMETER
  - HID_SMBUS_DEVICE_ACCESS_ERROR
2.7 HidSmbus_GetOpenedAttributes

**Description**: This function returns the device vendor ID, product ID, and release number for the device specified by `device`.

**Prototype**: `HID_SMBUS_STATUS HidSmbus_GetOpenedAttributes (HID_SMBUS_DEVICE device, WORD* deviceVid, WORD* devicePid, WORD* deviceReleaseNumber)`

**Parameters**:
1. `device`—is the device object pointer as returned by `HidSmbus_Open()`.
2. `deviceVid`—returns the device vendor ID.
3. `devicePid`—returns the device product ID.
4. `deviceReleaseNumber`—returns the USB device release number in binary-coded decimal.

**Return Value**: `HID_SMBUS_STATUS`
- `HID_SMBUS_SUCCESS`
- `HID_SMBUS_INVALID_DEVICE_OBJECT`
- `HID_SMBUS_INVALID_PARAMETER`
- `HID_SMBUS_DEVICE_ACCESS_ERROR`

2.8 HidSmbus_Open

**Description**: This function opens a device using a device number between 0 and `HidSmbus_GetNumDevices()` - 1 and returns a device object pointer that is used for subsequent accesses.

**Prototype**: `HID_SMBUS_STATUS HidSmbus_Open (HID_SMBUS_DEVICE* device, DWORD deviceNum, WORD vid, WORD pid)`

**Parameters**:
1. `device`—returns a pointer to an HID USB-to-SMBus device object. This pointer will be used by all subsequent accesses to the device.
2. `deviceNum`—is a zero-based device index, between 0 and `(HidSmbus_GetNumDevices() - 1)`. `vid`—filters device results by vendor ID. If both `vid` and `pid` are set to 0x0000, then HID devices will not be filtered by VID/PID.
4. `pid`—filters device results by product ID. If both `vid` and `pid` are set to 0x0000, then HID devices will not be filtered by VID/PID.

**Return Value**: `HID_SMBUS_STATUS`
- `HID_SMBUS_SUCCESS`
- `HID_SMBUS_INVALID_DEVICE_OBJECT`
- `HID_SMBUS_DEVICE_NOT_FOUND`
- `HID_SMBUS_INVALID_PARAMETER`
- `HID_SMBUS_DEVICE_IO_FAILED`
- `HID_SMBUS_DEVICE_ACCESS_ERROR`
- `HID_SMBUS_DEVICE_NOT_SUPPORTED`

**Remarks**: Be careful when opening a device. Any HID device may be opened by this library. However, if the device is not a CP2112, use of this library will cause undesirable results. The best course of action is to designate a unique VID/PID for CP2112 devices only. The application should then filter devices using this VID/PID.
2.9 HidSmbus_Close

Description: This function closes an opened device using the device object pointer provided by HidSmbus_Open().

Prototype: HID_SMBUS_STATUS HidSmbus_Close (HID_SMBUS_DEVICE device)

Parameters: 1. device—is the device object pointer as returned by HidSmbus_Open().

Return Value: HID_SMBUS_STATUS
- HID_SMBUS_SUCCESS
- HID_SMBUS_INVALID_DEVICE_OBJECT
- HID_SMBUS_INVALID_HANDLE
- HID_SMBUS_DEVICE_ACCESS_ERROR

Remarks: device is invalid after calling HidSmbus_Close(). Set device to NULL.

2.10 HidSmbus_IsOpened

Description: This function returns the device opened status.

Prototype: HID_SMBUS_STATUS HidSmbus_IsOpened (HID_SMBUS_DEVICE device, BOOL* opened)

Parameters: 1. device—is the device object pointer as returned by HidSmbus_Open().
2. opened—returns TRUE if the device object pointer is valid and the device has been opened using HidSmbus_Open().

Return Value: HID_SMBUS_STATUS
- HID_SMBUS_SUCCESS
- HID_SMBUS_INVALID_DEVICE_OBJECT
- HID_SMBUS_INVALID_PARAMETER

2.11 HidSmbus_ReadRequest

Description: This function initiates a read transfer to the specified slave device address. Read and write timeouts as well as transfer retries can be set using HidSmbus_SetSmbusConfig() as described in 2.22 HidSmbus_SetSmbusConfig.

Prototype: HID_SMBUS_STATUS HidSmbus_ReadRequest (HID_SMBUS_DEVICE device, BYTE slaveAddress, WORD numBytesToRead)

Parameters: 1. device—is the device object pointer as returned by HidSmbus_Open().
2. slaveAddress—is the address of the slave device to read from. This value must be between 0x02–0xFE. The least significant bit is the read/write bit for the SMBus transaction and must be 0.
3. numBytesToRead—is the number of bytes to read from the device (1–512).

Return Value: HID_SMBUS_STATUS
- HID_SMBUS_SUCCESS
- HID_SMBUS_INVALID_DEVICE_OBJECT
- HID_SMBUS_INVALID_PARAMETER
- HID_SMBUS_INVALID_REQUEST_LENGTH
- HID_SMBUS_DEVICE_IO_FAILED

Remarks: HidSmbus_ReadRequest() initiates a read transfer. SMBus is a half-duplex bus, which means that only one read, address read, or write transfer can be active at a time. The device will attempt to read up to transferRetries number of times and for readTimeout milliseconds before timing out. See HidSmbus_SetSmbusConfig() for more information on configuring read timeouts. If the autoReadResponse Setting is enabled, then call HidSmbus_GetReadResponse() to return the results of the read transfer.
2.12 HidSmbus_AddressReadRequest

Description: This function initiates a read transfer to the specified slave device address and specifies the address to read from on the device. Read and write timeouts as well as transfer retries can be set using HidSmbus_SetSmbusConfig() as described in 2.22 HidSmbus_SetSmbusConfig.

Prototype: HID_SMBUS_STATUS HidSmbus_AddressReadRequest (HID_SMBUS_DEVICE device, BYTE slaveAddress, WORD numBytesToRead, BYTE targetAddressSize, BYTE targetAddress[16])

Parameters:
1. device—is the device object pointer as returned by HidSmbus_Open().
2. slaveAddress—is the address of the slave device to read from. This value must be between 0x02–0xFE. The least significant bit is the read/write bit for the SMBus transaction and must be 0.
3. numBytesToRead—is the number of bytes to read from the device (1–512).
4. targetAddressSize—is the size of the target address in bytes (1-16).
5. targetAddress—is the address to read from the slave device.

Return Value: HID_SMBUS_STATUS
• HID_SMBUS_SUCCESS
• HID_SMBUS_INVALID_DEVICE_OBJECT
• HID_SMBUS_INVALID_PARAMETER
• HID_SMBUS_INVALID_REQUEST_LENGTH
• HID_SMBUS_DEVICE_IO_FAILED

Remarks: HidSmbus_AddressReadRequest() initiates a read transfer. SMBus is a half-duplex bus which means that only one read, address read, or write transfer can be active at a time. The device will attempt to read up to transferRetries number of times and for readTimeout milliseconds before timing out. See HidSmbus_SetSmbusConfig() for more information on configuring read timeouts. If the autoReadRespond setting is enabled, then call HidSmbus_GetReadResponse() to return the results of the read transfer. The device will transmit the target address on the bus after the slave device has acknowledged its address. This function is designed to read from EEPROMs with an SMBus interface.

2.13 HidSmbus_ForceReadResponse

Description: This function causes the device to send a read response to the host after a read transfer has been issued.

Prototype: HID_SMBUS_STATUS HidSmbus_ForceReadResponse (HID_SMBUS_DEVICE device, WORD numBytesToRead)

Parameters:
1. device—is the device object pointer as returned by HidSmbus_Open().
2. numBytesToRead—is the number of bytes to read from the device (1–512).

Return Value: HID_SMBUS_STATUS
• HID_SMBUS_SUCCESS
• HID_SMBUS_INVALID_DEVICE_OBJECT
• HID_SMBUS_INVALID_REQUEST_LENGTH
• HID_SMBUS_DEVICE_IO_FAILED

Remarks: HidSmbus_ForceReadResponse() should only be called if autoReadRespond is disabled using HidSmbus_SetSmbusConfig(). This allows the user to read data in a polled mode. Call HidSmbus_ReadRequest() or HidSmbus_AddressReadRequest() first. Next, call HidSmbus_TransferStatusRequest() and HidSmbus_TransferStatusResponse() to check if the device has received data. Next, call HidSmbus_ForceReadResponse(). Finally, call HidSmbus_GetReadResponse() repeatedly until all read data is returned. Typically, this procedure is not necessary as users should enable the autoReadRespond setting.
2.14 HidSmbus_GetReadResponse

**Description**: This function returns the read response to a read request. Read and write timeouts as well as transfer retries can be set using `HidSmbus_SetSmbusConfig()` as described in 2.22 HidSmbus_SetSmbusConfig.

**Prototype**: `HID_SMBUS_STATUS HidSmbus_GetReadResponse (HID_SMBUS_DEVICE device, 
HID_SMBUS_S0* status, BYTE* buffer, BYTE bufferSize, 
BYTE* numBytesRead)`

**Parameters**:
1. `device`—is the device object pointer as returned by `HidSmbus_Open()`.
2. `status`—returns the status of the read request.
3. `buffer`—returns up to 61 read data bytes.
4. `bufferSize`—is the size of buffer and must be at least 61 bytes.
5. `numBytesRead`—returns the number of valid data bytes returned in `buffer`.

**Return Value**: `HID_SMBUS_STATUS`
- `HID_SMBUS_SUCCESS`
- `HID_SMBUS_INVALID_DEVICE_OBJECT`
- `HID_SMBUS_INVALID_PARAMETER`
- `HID_SMBUS_READ_TIMED_OUT`
- `HID_SMBUS_READ_ERROR`

**Remarks**: `HidSmbus_GetReadResponse()` waits for up to `readTimeout` milliseconds for the device to send a read response interrupt report to the host. This function should be called repeatedly until all read data has been received or an error occurs. Call `HidSmbus_ReadRequest()` or `HidSmbus_AddressReadRequest()` followed by `HidSmbus_GetReadResponse()` to read data when `autoReadResponse` is enabled using `HidSmbus_SetSmbusConfig()`. `HidSmbus_GetReadResponse()` will wait for up to `responseTimeout` milliseconds before returning `HID_SMBUS_READ_TIMED_OUT`. 

<table>
<thead>
<tr>
<th>Definition</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>HID_SMBUS_S0_IDLE</td>
<td>0x00</td>
<td>No transfers are currently active on the bus.</td>
</tr>
<tr>
<td>HID_SMBUS_S0_BUSY</td>
<td>0x01</td>
<td>A read or write transfer is in progress.</td>
</tr>
<tr>
<td>HID_SMBUS_S0_COMPLETE</td>
<td>0x02</td>
<td>A read or write transfer completed without error and without retry.</td>
</tr>
<tr>
<td>HID_SMBUS_S0_ERROR</td>
<td>0x03</td>
<td>A read or write transfer completed with an error.</td>
</tr>
</tbody>
</table>
2.15 HidSmbus_WriteRequest

**Description**: This function writes the specified number of bytes from the supplied buffer to the specified slave device and returns immediately after sending the request to the CP2112. Read and write timeouts can be set using HidSmbus_SetTimeouts() as described in 2.20 HidSmbus_SetTimeouts.

**Prototype**: HID_SMBUS_STATUS HidSmbus_WriteRequest (HID_SMBUS_DEVICE device,

BYTE slaveAddress, BYTE* buffer, BYTE numBytesToWrite)

**Parameters**:
1. `device`—is the device object pointer as returned by HidSmbus_Open().
2. `slaveAddress`—is the address of the slave device to write to. This value must be between 0x02-0xFE. The least significant bit is the read/write bit for the SMBus transaction and must be 0.
3. `buffer`—is the address of a buffer to be sent to the device.
4. `numBytesToWrite`—is the number of bytes to write to the device (1–61). This value must be less than or equal to the size of buffer.

**Return Value**: HID_SMBUS_STATUS
- HID_SMBUS_SUCCESS
- HID_SMBUS_INVALID_DEVICE_OBJECT
- HID_SMBUS_INVALID_PARAMETER
- HID_SMBUS_INVALID_REQUEST_LENGTH
- HID_SMBUS_DEVICE_IO_FAILED

**Remarks**: Call HidSmbus_TransferStatusRequest() / HidSmbus_GetTransferStatusResponse() to wait for the write transfer to complete before issuing another transfer request. The device waits for up to `transferRetries` number of retries and `writeTimeout` number of milliseconds before timing out.

2.16 HidSmbus_TransferStatusRequest

**Description**: This function requests the status of the current read or write transfer.

**Prototype**: HID_SMBUS_STATUS HidSmbus_TransferStatusRequest (HID_SMBUS_DEVICE device),

**Parameters**:
1. `device`—is the device object pointer as returned by HidSmbus_Open().

**Return Value**: HID_SMBUS_STATUS
- HID_SMBUS_SUCCESS
- HID_SMBUS_INVALID_DEVICE_OBJECT
- HID_SMBUS_DEVICE_IO_FAILED

**Remarks**: Call HidSmbus_TransferStatusRequest() followed by HidSmbus_GetTransferStatusResponse() to get the status of the current read or write transfer.
2.17 HidSmbus_GetTransferStatusResponse

**Description**: This function returns the status of the current read or write transfer.

**Prototype**: `HID_SMBUS_STATUS HidSmbus_GetTransferStatusResponse (HID_SMBUS_DEVICE device, HID_SMBUS_S0* status, HID_SMBUS_S1* detailedStatus, WORD* numRetries, WORD* bytesRead)`

**Parameters**:
1. `device`—is the device object pointer as returned by `HidSmbus_Open()`.
2. `status`—returns the status of the read or write transfer.
3. `detailedStatus`—returns the extended status of the read or write transfer. See the following tables for more information.

During initialization, the CP2112-F03 device tests for SCL and/or SDA being stuck low. For more information, see AN495: CP2112 Interface Specification.

**Return Value**: `HID_SMBUS_STATUS`
- `HID_SMBUS_SUCCESS`
- `HID_SMBUS_INVALID_DEVICE_OBJECT`
- `HID_SMBUS_INVALID_PARAMETER`
- `HID_SMBUS_READ_TIMED_OUT`
- `HID_SMBUS_READ_ERROR`

**Remarks**: Call `HidSmbus_TransferStatusRequest()` followed by `HidSmbus_GetTransferStatusResponse()` to get the status of the current read or write transfer. `HidSmbus_GetTransferStatusResponse()` will wait for up to `responseTimeout` milliseconds before returning `HID_SMBUS_READ_TIMED_OUT`.

detailedStatus values for a status value of `HID_SMBUS_S0_IDLE` are:

<table>
<thead>
<tr>
<th>Definition</th>
<th>Value (binary)</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Initial (first) Transfer Status Request</td>
<td>1xxx xxxx</td>
<td>SDA line is stuck low.</td>
</tr>
<tr>
<td></td>
<td>x1xx xxxx</td>
<td>SCL line is stuck low.</td>
</tr>
</tbody>
</table>

Subsequent Transfer Status Requests

<table>
<thead>
<tr>
<th>Definition</th>
<th>Value (binary)</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>xxxx xxxx</td>
<td></td>
<td>detailedStatus value is undefined.</td>
</tr>
</tbody>
</table>

detailedStatus values for a status value of `HID_SMBUS_S0_BUSY` are:

<table>
<thead>
<tr>
<th>Definition</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>HID_SMBUS_S1_BUSY_ADDRESS_ACKED</code></td>
<td>0x00</td>
<td>The slave address was acknowledged.</td>
</tr>
<tr>
<td><code>HID_SMBUS_S1_BUSY_ADDRESS_NACKED</code></td>
<td>0x01</td>
<td>The slave address has not been acknowledged.</td>
</tr>
<tr>
<td><code>HID_SMBUS_S1_BUSY_READING</code></td>
<td>0x02</td>
<td>Read data phase in progress.</td>
</tr>
<tr>
<td><code>HID_SMBUS_S1_BUSY_WRITING</code></td>
<td>0x03</td>
<td>Write data phase in progress.</td>
</tr>
</tbody>
</table>

detailedStatus values for a status value of `HID_SMBUS_S0_ERROR` are:
<table>
<thead>
<tr>
<th>Definition</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>HID_SMBUS_S1_ERROR_TIMEOUT_NACK</td>
<td>0x00</td>
<td>Transfer timeout: SMBus slave address was NACKed</td>
</tr>
<tr>
<td>HID_SMBUS_S1_ERROR_TIMEOUT_BUS_NOT_FREE</td>
<td>0x01</td>
<td>Transfer timeout: SMBus not free (or SCL low timeout occurred)</td>
</tr>
<tr>
<td>HID_SMBUS_S1_ERROR_ARB_LOST</td>
<td>0x02</td>
<td>Bus arbitration was lost</td>
</tr>
<tr>
<td>HID_SMBUS_S1_ERROR_READ_INCOMPLETE</td>
<td>0x03</td>
<td>Read was incomplete</td>
</tr>
<tr>
<td>HID_SMBUS_S1_ERROR_WRITE_INCOMPLETE</td>
<td>0x04</td>
<td>Write was incomplete</td>
</tr>
<tr>
<td>HID_SMBUS_S1_ERROR_SUCCESS_AFTER_RETRY</td>
<td>0x05</td>
<td>Transfer completed after numRetries number of retries</td>
</tr>
</tbody>
</table>

2.18 HidSmbus_CancelTransfer

**Description**: This function cancels the current read or write transfer.

**Prototype**: `HID_SMBUS_STATUS HidSmbus_TransferStatusRequest (HID_SMBUS_DEVICE device)`

**Parameters**: 1. device—is the device object pointer as returned by HidSmbus_Open().

**Return Value**: `HID_SMBUS_STATUS`
- HID_SMBUS_SUCCESS
- HID_SMBUS_INVALID_DEVICE_OBJECT
- HID_SMBUS_DEVICE_IO_FAILED

**Remarks**: This function will clear any read responses received.

2.19 HidSmbus_CancelIo

**Description**: This function cancels any pending HID reads and writes (Windows Only).

**Prototype**: `HID_SMBUS_STATUS HidSmbus_CancelIo (HID_SMBUS_DEVICE device)`

**Parameters**: 1. device—is the device object pointer as returned by HidSmbus_Open().

**Return Value**: `HID_SMBUS_STATUS`
- HID_SMBUS_SUCCESS
- HID_SMBUS_INVALID_DEVICE_OBJECT
- HID_SMBUS_DEVICE_IO_FAILED
2.20 HidSmbus_SetTimeouts

Description: This function sets the response timeouts. Response timeouts are used by HidSmbus_GetReadResponse() and HidSmbus_GetTransferStatusResponse(). The default value for response timeouts is 1000 ms, but timeouts can be set to wait for any number of milliseconds between 1 and 0xFFFFFFFF. Specifying a response timeout of 0, will wait indefinitely.

Prototype: HID_SMBUS_STATUS HidSmbus_SetTimeouts (HID_SMBUS_DEVICE device,
DWORD responseTimeout)

Parameters:
1. device—is the device object pointer as returned by HidSmbus_Open().
2. responseTimeout—is the HidSmbus_GetReadResponse() and HidSmbus_GetTransferStatusResponse() timeout.

Return Value: HID_SMBUS_STATUS
• HID_SMBUS_SUCCESS
• HID_SMBUS_INVALID_DEVICE_OBJECT

Remarks: If timeouts are set to a large value and no data is received, the application may appear unresponsive. It is recommended to set timeouts appropriately before using the device. Typically, users will want to specify a response timeout that is greater than the read and write timeouts.

2.21 HidSmbus_GetTimeouts

Description: This function returns the current response timeouts specified in milliseconds. A response timeout value of 0 indicates an infinite timeout.

Prototype: HID_SMBUS_STATUS HidSmbus_GetTimeouts (HID_SMBUS_DEVICE device,
DWORD* responseTimeout)

Parameters:
1. device—is the device object pointer as returned by HidSmbus_Open().
2. responseTimeout—is the response operation timeout in milliseconds.

Return Value: HID_SMBUS_STATUS
• HID_SMBUS_SUCCESS
• HID_SMBUS_INVALID_DEVICE_OBJECT
• HID_SMBUS_INVALID_PARAMETER

Remarks: Timeouts are maintained for each device but are not persistent across HidSmbus_Open()/HidSmbus_Close().
2.22 HidSmbus_SetSmbusConfig

Description: This function sets the SMBus bit rate, address, and transfer settings such as timeouts and retries. Refer to the device data sheet for a list of supported configuration settings.

Prototype: 

```c
HID_SMBUS_STATUS HidSmbus_SetSmbusConfig (HID_SMBUS_DEVICE device,
    DWORD bitRate, BYTE address, BOOL autoReadRespond, WORD writeTimeout,
    WORD readTimeout, BOOL sclLowTimeout, WORD transferRetries)
```

Parameters:

1. `device`—is the device object pointer as returned by `HidSmbus_Open()`.
2. `bitRate`—is the bit rate for SMBus communication. The default is 100 kHz. This value must be non-zero.
3. `address`—is the device’s slave address (0x02–0xFE) address. The device will only acknowledge this address. The default is 0x02. The least significant bit is the read/write bit for the SMBus transaction and must be 0.
4. `autoReadRespond`—controls the read response behavior of the device. If enabled, the device will automatically send read response interrupt reports to the device after initiating a read transfer. If disabled, the user must call `HidSmbus_ForceReadResponse()` before read response interrupt reports will be sent to the host. The default is FALSE (0).
5. `writeTimeout`—is the time limit in milliseconds (0–1000) before the device will automatically cancel a write transfer. A value of 0 indicates an infinite timeout. In this case, a write transfer will wait indefinitely for a write to complete or until `HidSmbus_CancelTransfer()` is called. The default is 0.
6. `readTimeout`—is the time limit in milliseconds (0 - 1000) before the device will automatically cancel a read transfer. A value of 0 indicates an infinite timeout. In this case, a read transfer will wait indefinitely for a read to complete or until `HidSmbus_CancelTransfer()` is called. The default is 0.
7. `sclLowTimeout`—is a timeout that will reset the SMBus if the SCL line is held low for more than 25 ms. If enabled and an SCL Low Timeout occurs, the status byte of the Transfer Status Response command will be set appropriately. The default is FALSE (0).
8. `transferRetries`—is the number of times to retry (0 - 1000) a failed read or write transfer. A value of 0 indicates an infinite number of retries until the specified read or write timeout has elapsed. The default is 0.

Return Value:

- `HID_SMBUS_STATUS`
  - `HID_SMBUS_SUCCESS`
  - `HID_SMBUS_INVALID_DEVICE_OBJECT`
  - `HID_SMBUS_INVALID_PARAMETER`
  - `HID_SMBUS_DEVICE_IO_FAILED`
2.23 HidSmbus_GetSmbusConfig

Description: This function gets the SMBus bit rate, address, and transfer settings such as timeouts and retries. Refer to the device data sheet for a list of supported configuration settings.

Prototype: 

```c
HID_SMBUS_STATUS HidSmbus_GetSmbusConfig (HID_SMBUS_DEVICE device,
DWORD* bitRate, BYTE* address, BOOL* autoReadRespond,
WORD* writeTimeout, WORD* readTimeout, BOOL* sclLowTimeout,
WORD* transferRetries)
```

Parameters:

1. `device`—is the device object pointer as returned by `HidSmbus_Open()`.
2. `bitRate`—returns the bit rate for SMBus communication. The default is 100 kHz. This value must be non-zero.
3. `address`—returns the device’s slave address (0x02–0xFE) address. The device will only acknowledge this address. The default is 0x02.
4. `autoReadRespond`—returns the read response behavior of the device. If auto read response is enabled, then the device will automatically send read response interrupt reports to the device after initiating a read transfer. If disabled, the user must call `HidSmbus_ForceReadResponse()` before read response interrupt reports will be sent to the host. The default is FALSE (0).
5. `writeTimeout`—returns the time limit in milliseconds (0–1000) before the device will automatically cancel a write transfer. A value of 0 indicates an infinite timeout. In this case, a write transfer will wait indefinitely for a write to complete or until `HidSmbus_CancelTransfer()` is called. The default is 0.
6. `readTimeout`—returns the time limit in milliseconds (0–1000) before the device will automatically cancel a read transfer. A value of 0 indicates an infinite timeout. In this case, a read transfer will wait indefinitely for a read to complete or until `HidSmbus_CancelTransfer()` is called. The default is 0.
7. `sclLowTimeout`—is a timeout that will reset the SMBus if the SCL line is held low for more than 25 ms. If enabled and an SCL Low Timeout occurs, the status byte of the Transfer Status Response command will be set appropriately. The default is FALSE (0).
8. `transferRetries`—returns the number of times to retry (0–1000) a failed read or write transfer. A value of 0 indicates an infinite number of retries until the specified read or write timeout has elapsed. The default is 0.

Return Value:

- `HID_SMBUS_STATUS`
  - `HID_SMBUS_SUCCESS`
  - `HID_SMBUS_INVALID_DEVICE_OBJECT`
  - `HID_SMBUS_INVALID_PARAMETER`
  - `HID_SMBUSDEVICE_IO_FAILED`

2.24 HidSmbus_Reset

Description: This function initiates a full device reset. All configuration settings will be reset to their default values after the device re-enumerates.

Prototype: 

```c
HID_SMBUS_STATUS HidSmbus_Reset (HID_SMBUS_DEVICE device)
```

Parameters:

1. `device`—is the device object pointer as returned by `HidSmbus_Open()`.

Return Value:

- `HID_SMBUS_STATUS`
  - `HID_SMBUS_SUCCESS`
  - `HID_SMBUS_INVALID_DEVICE_OBJECT`
  - `HID_SMBUS_INVALID_PARAMETER`
  - `HID_SMBUS_DEVICE_IO_FAILED`

Remarks: Resetting the device will make the device’s handle stale. Users must close the device using the old handle before proceeding to reconnect to the device. See `HidSmbus_SetSmbusConfig()` and `HidSmbus_SetGpioConfig()` for default configuration settings.
2.25 HidSmbus_SetGpioConfig

Description: This function configures the GPIO pins' directions and modes.

Prototype: `HID_SMBUS_STATUS HidSmbus_SetGpioConfig (HID_SMBUS_DEVICE device,
BYTE direction, BYTE mode, BYTE special, BYTE clkDiv)`

Parameters:
1. `device`—is the device object pointer as returned by `HidSmbus_Open()`.
2. `direction`—is a bitmask that specifies each GPIO pin's direction.

<table>
<thead>
<tr>
<th>Definition</th>
<th>Bit Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>HID_SMBUS_DIRECTION_INPUT</td>
<td>0</td>
<td>Input</td>
</tr>
<tr>
<td>HID_SMBUS_DIRECTION_OUTPUT</td>
<td>1</td>
<td>Output</td>
</tr>
</tbody>
</table>

3. `mode`—is a bitmask that specifies each GPIO pin's mode.

<table>
<thead>
<tr>
<th>Definition</th>
<th>Bit Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>HID_SMBUS_MODE_OPEN_DRAIN</td>
<td>0</td>
<td>Open-Drain</td>
</tr>
<tr>
<td>HID_SMBUS_MODE_PUSH_PULL</td>
<td>1</td>
<td>Push-Pull</td>
</tr>
</tbody>
</table>

4. `special`—is a bitmask that specifies the special behavior of GPIO.0, GPIO.1, and GPIO.7.

<table>
<thead>
<tr>
<th>Definition</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>HID_SMBUS_MASK_FUNCTION_GPIO_7_CLK</td>
<td>0x00</td>
<td>Enables or disables the clock output function of</td>
</tr>
<tr>
<td></td>
<td></td>
<td>GPIO.7</td>
</tr>
<tr>
<td>HID_SMBUS_MASK_FUNCTION_GPIO_0_TXT</td>
<td>0x01</td>
<td>Enables or disables the TX toggle function of</td>
</tr>
<tr>
<td></td>
<td></td>
<td>GPIO.0</td>
</tr>
<tr>
<td>HID_SMBUS_MASK_FUNCTION_GPIO_1_RXT</td>
<td>0x04</td>
<td>Enables or disables the RX toggle function of</td>
</tr>
<tr>
<td></td>
<td></td>
<td>GPIO.1</td>
</tr>
</tbody>
</table>

5. `clkDiv`—is the clock output divider value used for GPIO.7 when configured in clock output mode. The frequency is equal to 48 MHz / (2 x `clkDiv`) when `clkDiv` is between 1 and 255 and equal to 48 MHz when `clkDiv` is 0.

Return Value: `HID_SMBUS_STATUS`
- `HID_SMBUS_SUCCESS`
- `HID_SMBUS_INVALID_DEVICE_OBJECT`
- `HID_SMBUS_DEVICE_IO_FAILED`
2.26 HidSmbus_GetGpioConfig

Description: This function returns the GPIO pins' directions and modes.

Prototype: `HID_SMBUS_STATUS HidSmbus_GetGpioConfig (HID_SMBUS_DEVICE device, BYTE* direction, BYTE* mode, BYTE* special, BYTE* clkDiv)`

Parameters:
1. device—is the device object pointer as returned by HidSmbus_Open().
2. direction—returns a bitmask that specifies each GPIO pin's direction.
3. mode—returns a bitmask that specifies each GPIO pin's mode.

<table>
<thead>
<tr>
<th>Definition</th>
<th>Bit Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>HID_SMBUS_MODE_OPEN_DRAIN</td>
<td>0</td>
<td>Open-Drain</td>
</tr>
<tr>
<td>HID_SMBUS_MODE_PUSH_PULL</td>
<td>1</td>
<td>Push-Pull</td>
</tr>
</tbody>
</table>

4. special—returns a bitmask that specifies the special behavior of GPIO.0, GPIO.1, and GPIO.7.

<table>
<thead>
<tr>
<th>Definition</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>HID_SMBUS_MASK_FUNCTION_GPIO_7_CLK</td>
<td>0x00</td>
<td>Enables or disables the clock output function of GPIO.7</td>
</tr>
<tr>
<td>HID_SMBUS_MASK_FUNCTION_GPIO_0_TXT</td>
<td>0x01</td>
<td>Enables or disables the TX toggle function of GPIO.0</td>
</tr>
<tr>
<td>HID_SMBUS_MASK_FUNCTION_GPIO_1_RXT</td>
<td>0x04</td>
<td>Enables or disables the RX toggle function of GPIO.1</td>
</tr>
</tbody>
</table>

5. clkDiv—returns the clock output divider value used for GPIO.7 when configured in clock output mode. The frequency is equal to 48 MHz / (2 x clkDiv) when clkDiv is between 1 and 255 and equal to 48 MHz when clkDiv is 0.

Return Value: `HID_SMBUS_STATUS`
- HID_SMBUS_SUCCESS
- HID_SMBUS_INVALID_DEVICE_OBJECT
- HID_SMBUS_INVALID_PARAMETER
- HID_SMBUS_DEVICE_IO_FAILED
2.27 HidSmbus_ReadLatch

Description: This function returns the current GPIO latch value.

Prototype: HID_SMBUS_STATUS HidSmbus_ReadLatch (HID_SMBUS_DEVICE device,
BYTE* latchValue)

Parameters: 1. device—is the device object pointer as returned by HidSmbus_Open().
2. latchValue—returns the current GPIO latch value.

Return Value: HID_SMBUS_STATUS
• HID_SMBUS_SUCCESS
• HID_SMBUS_INVALID_DEVICE_OBJECT
• HID_SMBUS_INVALID_PARAMETER
• HID_SMBUS_DEVICE_IO_FAILED

Remarks: If a pin is configured as an input, then the latchValue bit represents the logical voltage level received on the pin. If a pin is configured as an output, then the latchValue bit represents the logical voltage level driven on the pin.

2.28 HidSmbus_WriteLatch

Description: This function sets the current GPIO latch value for the specified bits.

Prototype: HID_SMBUS_STATUS HidSmbus_WriteLatch (HID_SMBUS_DEVICE device,
BYTE latchValue, BYTE latchMask)

Parameters: 1. device—is the device object pointer as returned by HidSmbus_Open().
2. latchValue—is the output value to drive on GPIO pins configured as outputs.
3. latchMask—is the bitmask specifying which bits to modify.

Definition | Bit Value
--- | ---
HID_SMBUS_MASK_GPIO_0 | 0x01
HID_SMBUS_MASK_GPIO_1 | 0x02
HID_SMBUS_MASK_GPIO_2 | 0x04
HID_SMBUS_MASK_GPIO_3 | 0x08
HID_SMBUS_MASK_GPIO_4 | 0x10
HID_SMBUS_MASK_GPIO_5 | 0x20
HID_SMBUS_MASK_GPIO_6 | 0x40
HID_SMBUS_MASK_GPIO_7 | 0x80

Return Value: HID_SMBUS_STATUS
• HID_SMBUS_SUCCESS
• HID_SMBUS_INVALID_DEVICE_OBJECT
• HID_SMBUS_DEVICE_IO_FAILED

Remarks: Only GPIO pins configured as outputs with their corresponding latchMask bits set can be written to.
2.29 HidSmbus_GetPartNumber

**Description**: This function retrieves the part number and version of the CP2112 device.

**Prototype**: HID_SMBUS_STATUS HidSmbus_GetPartNumber (HID_SMBUS_DEVICE device,
BYTE* partNumber, BYTE* version)

**Parameters**: 
1. device—is the device object pointer as returned by HidSmbus_Open().
2. partNumber—returns the device part number.

<table>
<thead>
<tr>
<th>Definition</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>HID_SMBUS_PART_CP2112</td>
<td>0x0C</td>
<td>CP2112</td>
</tr>
</tbody>
</table>

3. version—returns the version. This value is not user-programmable.

**Return Value**: HID_SMBUS_STATUS
- HID_SMBUS_SUCCESS
- HID_SMBUS_INVALID_DEVICE_OBJECT
- HID_SMBUS_INVALID_PARAMETER
- HID_SMBUS_DEVICE_IO_FAILED

2.30 HidSmbus_GetLibraryVersion

**Description**: This function returns the HID USB-to-SMBus Interface Library version.

**Prototype**: HID_SMBUS_STATUS HidSmbus_GetLibraryVersion (BYTE* major, BYTE* minor,
BOOL* release)

**Parameters**: 
1. major—returns the major library version number. This value ranges from 0 to 255.
2. minor—returns the minor library version number. This value ranges from 0 to 255.
3. release—returns TRUE if the library is a release build; otherwise, the library is a Debug build.

**Return Value**: HID_SMBUS_STATUS
- HID_SMBUS_SUCCESS
- HID_SMBUS_INVALID_PARAMETER

2.31 HidSmbus_GetHidLibraryVersion

**Description**: This function returns the version of the HID Device Interface Library that is currently in use.

**Prototype**: HID_SMBUS_STATUS HidSmbus_GetHidLibraryVersion (BYTE* major,
BYTE* minor, BOOL* release)

**Parameters**: 
1. major—returns the major library version number. This value ranges from 0 to 255.
2. minor—returns the minor library version number. This value ranges from 0 to 255.
3. release—returns TRUE if the library is a release build; otherwise, the library is a Debug build.

**Return Value**: HID_SMBUS_STATUS
- HID_SMBUS_SUCCESS
- HID_SMBUS_INVALID_PARAMETER
2.32 HidSmbus_GetHidGuid

Description: This function obtains the HID GUID. This can be used to register for surprise removal notifications (Windows Only).

Prototype: HidSmbus_Status HidSmbus_GetHidGuid (void* guid)

Parameters:
1. guid — returns the HID GUID.

Return Value: HidSmbus_Status
- HidSmbus_Success
- HidSmbus_Invalid_Parameter
3. User Customization API Functions

The following parameters are programmable on the device. Different functions are provided to program these parameters. Each parameter may only be programmed once and only if the parameter is not locked.

<table>
<thead>
<tr>
<th>Name</th>
<th>Size</th>
<th>Short Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>VID</td>
<td>2</td>
<td>USB Vendor ID</td>
</tr>
<tr>
<td>PID</td>
<td>2</td>
<td>USB Product ID</td>
</tr>
<tr>
<td>Power</td>
<td>1</td>
<td>Power request in mA/2</td>
</tr>
<tr>
<td>Power Mode</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>Release Version</td>
<td>2</td>
<td>Major and Minor release version</td>
</tr>
<tr>
<td>Manufacturer String</td>
<td>60</td>
<td>Product Manufacturer (English Unicode)</td>
</tr>
<tr>
<td>Product Description String</td>
<td>60</td>
<td>Product Description (English Unicode)</td>
</tr>
<tr>
<td>Serial String</td>
<td>60</td>
<td>Serialization String (English Unicode)</td>
</tr>
</tbody>
</table>

The following API functions are provided to allow user customization/one-time programming:

<table>
<thead>
<tr>
<th>Definition</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>HidSmbus_SetLock()</td>
<td>Prevents further OTP programming/customization</td>
</tr>
<tr>
<td>HidSmbus_GetLock()</td>
<td>Gets the OTP lock status</td>
</tr>
<tr>
<td>HidSmbus_SetUsbConfig()</td>
<td>Sets VID, PID, power, power mode, and release version</td>
</tr>
<tr>
<td>HidSmbus_GetUsbConfig()</td>
<td>Gets VID, PID, power, power mode, and release version</td>
</tr>
<tr>
<td>HidSmbus_SetManufacturingString()</td>
<td>Sets the USB manufacturing string</td>
</tr>
<tr>
<td>HidSmbus_GetManufacturingString()</td>
<td>Gets the USB manufacturing string</td>
</tr>
<tr>
<td>HidSmbus_SetProductString()</td>
<td>Sets the USB product string</td>
</tr>
<tr>
<td>HidSmbus_GetProductString()</td>
<td>Gets the USB product string</td>
</tr>
<tr>
<td>HidSmbus_SetSerialString()</td>
<td>Sets the USB serial string</td>
</tr>
<tr>
<td>HidSmbus_GetSerialString()</td>
<td>Gets the USB serial string</td>
</tr>
</tbody>
</table>
### 3.1 HidSmbus_SetLock

**Description:** This function permanently locks/disables device customization.

**Prototype:**

```c
HID_SMBUS_STATUS HidSmbus_SetLock (HID_SMBUS_DEVICE device, BYTE lock)
```

**Parameters:**
1. *device*—is the device object pointer as returned by `HidSmbus_Open()`.
2. *lock*—is the bitmask specifying which fields can be customized/programmed and which fields are already customized.

#### Bit Definition

<table>
<thead>
<tr>
<th>Bit</th>
<th>Definition</th>
<th>Mask</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>HID_SMBUS_LOCK_VID</td>
<td>0x01</td>
<td>VID</td>
</tr>
<tr>
<td>1</td>
<td>HID_SMBUS_LOCK_PID</td>
<td>0x02</td>
<td>PID</td>
</tr>
<tr>
<td>2</td>
<td>HID_SMBUS_LOCK_POWER</td>
<td>0x04</td>
<td>Power</td>
</tr>
<tr>
<td>3</td>
<td>HID_SMBUS_LOCK_POWER_MODE</td>
<td>0x08</td>
<td>Power Mode</td>
</tr>
<tr>
<td>4</td>
<td>HID_SMBUS_LOCK_RELEASE_VERSION</td>
<td>0x10</td>
<td>Release Version</td>
</tr>
<tr>
<td>5</td>
<td>HID_SMBUS_LOCK_MFG_STR</td>
<td>0x20</td>
<td>Manufacturing String</td>
</tr>
<tr>
<td>6</td>
<td>HID_SMBUS_LOCK_PRODUCT_STR</td>
<td>0x40</td>
<td>Product String</td>
</tr>
<tr>
<td>7</td>
<td>HID_SMBUS_LOCK_SERIAL_STR</td>
<td>0x80</td>
<td>Serial String</td>
</tr>
</tbody>
</table>

#### Definition

<table>
<thead>
<tr>
<th>Definition</th>
<th>Bit Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>HID_SMBUS_LOCK_UNLOCKED</td>
<td>0</td>
<td>Field can be customized</td>
</tr>
<tr>
<td>HID_SMBUS_LOCK_LOCKED</td>
<td>1</td>
<td>Field has already been customized or has been locked</td>
</tr>
</tbody>
</table>

**Return Value:** `HID_SMBUS_STATUS`
- `HID_SMBUS_SUCCESS`
- `HID_SMBUS_INVALID_DEVICE_OBJECT`
- `HID_SMBUS_DEVICE_IO_FAILED`

**Remarks:** When this function is successfully called, the specified fields are fully locked and cannot be further customized. The user customization functions can be called and may return `HID_SMBUS_SUCCESS` even though the device was not programmed. Call the function's corresponding get function to verify that customization was successful. Each field is stored in one time programmable memory (OTP) and can only be customized once. After a field is customized, the corresponding lock bits are set to 0.
3.2 HidSmbus_GetLock

Description: This function returns the device customization lock status.

Prototype: 

\[
\text{HID_SMBUS_STATUS HidSmbus_GetLock (HID_SMBUS_DEVICE device, BYTE* lock)}
\]

Parameters:
1. device—is the device object pointer as returned by HidSmbus_Open().
2. lock—returns a bitmask specifying which fields are locked.

<table>
<thead>
<tr>
<th>Bit</th>
<th>Definition</th>
<th>Mask</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>HID_SMBUS_LOCK_VID</td>
<td>0x01</td>
<td>VID</td>
</tr>
<tr>
<td>1</td>
<td>HID_SMBUS_LOCK_PID</td>
<td>0x02</td>
<td>PID</td>
</tr>
<tr>
<td>2</td>
<td>HID_SMBUS_LOCK_POWER</td>
<td>0x04</td>
<td>Power</td>
</tr>
<tr>
<td>3</td>
<td>HID_SMBUS_LOCK_POWER_MODE</td>
<td>0x08</td>
<td>Power Mode</td>
</tr>
<tr>
<td>4</td>
<td>HID_SMBUS_LOCK_RELEASE_VERSION</td>
<td>0x10</td>
<td>Release Version</td>
</tr>
<tr>
<td>5</td>
<td>HID_SMBUS_LOCK_MFG_STR</td>
<td>0x20</td>
<td>Manufacturing String</td>
</tr>
<tr>
<td>6</td>
<td>HID_SMBUS_LOCK_PRODUCT_STR</td>
<td>0x40</td>
<td>Product String</td>
</tr>
<tr>
<td>7</td>
<td>HID_SMBUS_LOCK_SERIAL_STR</td>
<td>0x80</td>
<td>Serial String</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Definition</th>
<th>Bit Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>HID_SMBUS_LOCK_UNLOCKED</td>
<td>0</td>
<td>Field can be customized</td>
</tr>
<tr>
<td>HID_SMBUS_LOCK_LOCKED</td>
<td>1</td>
<td>Field has already been customized or has been locked</td>
</tr>
</tbody>
</table>

Return Value: 

- HID_SMBUS_STATUS
  - HID_SMBUS_SUCCESS
  - HID_SMBUS_INVALID_DEVICE_OBJECT
  - HID_SMBUS_INVALID_PARAMETER
  - HID_SMBUS_DEVICE_IO_FAILED
3.3 HidSmbus_SetUsbConfig

Description: This function allows one-time customization of the USB configuration, which includes vendor ID, product ID, power, power mode, and release version settings. Each field can be independently programmed one time via the mask field.

Prototype: HID_SMBUS_STATUS HidSmbus_SetUsbConfig (HID_SMBUS_DEVICE device,

WORD vid, WORD pid, BYTE power, BYTE powerMode, WORD releaseVersion,

BYTE mask)

Parameters:
1. device—is the device object pointer as returned by HidSmbus_Open().
2. vid—is the vendor ID.
3. pid—is the product ID.
4. power—specifies the current requested by the device in millamps/2. The maximum power setting is 500 mA or 250 (0xFA). This value only applies when the device is configured to be bus-powered.
5. powerMode—configures the device as bus-powered or self-powered.

<table>
<thead>
<tr>
<th>Definition</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>HID_SMBUS_BUS_POWER</td>
<td>0x00</td>
<td>Device is bus powered</td>
</tr>
<tr>
<td>HID_SMBUS_SELF_POWER_VREG_DIS</td>
<td>0x01</td>
<td>Device is self powered (voltage regulator disabled)</td>
</tr>
<tr>
<td>HID_SMBUS_SELF_POWER_VREG_EN</td>
<td>0x02</td>
<td>Device is self powered (voltage regulator enabled)</td>
</tr>
</tbody>
</table>

6. releaseVersion—is the user-programmable release version. The MSB is the major revision and the LSB is the minor revision. Both revisions can be programmed to any value from 0 to 255. This version is not the same as the device release number described in the USB device descriptor.

7. mask—is the bitmask specifying which fields to customize.

<table>
<thead>
<tr>
<th>Bit</th>
<th>Definition</th>
<th>Mask</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>HID_SMBUS_SET_VID</td>
<td>0x01</td>
<td>VID</td>
</tr>
<tr>
<td>1</td>
<td>HID_SMBUS_SET_PID</td>
<td>0x02</td>
<td>PID</td>
</tr>
<tr>
<td>2</td>
<td>HID_SMBUS_SET_POWER</td>
<td>0x04</td>
<td>Power</td>
</tr>
<tr>
<td>3</td>
<td>HID_SMBUS_SET_POWER_MODE</td>
<td>0x08</td>
<td>Power Mode</td>
</tr>
<tr>
<td>4</td>
<td>HID_SMBUS_SET_RELEASE_VERSION</td>
<td>0x10</td>
<td>Release Version</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Definition</th>
<th>Bit Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>HID_SMBUS_SET_IGNORE</td>
<td>0</td>
<td>Field will be unchanged</td>
</tr>
<tr>
<td>HID_SMBUS_SET_PROGRAM</td>
<td>1</td>
<td>Field will be programmed</td>
</tr>
</tbody>
</table>

Return Value: HID_SMBUS_STATUS
- HID_SMBUS_SUCCESS
- HID_SMBUS_INVALIDDEVICE_OBJECT
- HID_SMBUS_INVALID_PARAMETER
- HID_SMBUS_DEVICE_IO_FAILED
3.4 HidSmbus_GetUsbConfig

**Description**: This function retrieves USB configuration, which includes vendor ID, product ID, power, power mode, release version, and flush buffers settings.

**Prototype**: `HID_SMBUS_STATUS HidSmbus_GetUsbConfig (HID_SMBUS_DEVICE device, WORD* vid, WORD* pid, BYTE* power, BYTE* powerMode, WORD* releaseVersion)`

**Parameters**:
1. `device`—is the device object pointer as returned by `HidSmbus_Open()`.
2. `vid`—returns the vendor ID.
3. `pid`—returns the product ID.
4. `power`—returns the current requested by the device in milliamps / 2. This value only applies when the device is bus-powered.
5. `powerMode`—returns the device power mode.

<table>
<thead>
<tr>
<th>Definition</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>HID_SMBUS_BUS_POWER</td>
<td>0x00</td>
<td>Device is bus powered</td>
</tr>
<tr>
<td>HID_SMBUS_SELF_POWER_VREG_DIS</td>
<td>0x01</td>
<td>Device is self powered (voltage regulator disabled)</td>
</tr>
<tr>
<td>HID_SMBUS_SELF_POWER_VREG_EN</td>
<td>0x02</td>
<td>Device is self powered (voltage regulator enabled)</td>
</tr>
</tbody>
</table>

6. `releaseVersion`—returns the user-programmable release version, revision, and the LSB is the minor revision. Both revisions can be programmed to any value from 0 to 255. This version is not the same as the device release number described in the USB device descriptor.

**Return Value**: `HID_SMBUS_STATUS`
- `HID_SMBUS_SUCCESS`
- `HID_SMBUS_INVALID_DEVICE_OBJECT`
- `HID_SMBUS_INVALID_PARAMETER`
- `HID_SMBUS_DEVICE_IO_FAILED`

3.5 HidSmbus_SetManufacturingString

**Description**: This function allows one-time customization of the USB manufacturing string.

**Prototype**: `HID_SMBUS_STATUS HidSmbus_SetManufacturingString (HID_SMBUS_DEVICE device, char* manufacturingString, BYTE strlen)`

**Parameters**:
1. `device`—is the device object pointer as returned by `HidSmbus_Open()`.
2. `manufacturingString`—is a variable of type `HID_SMBUS_CP2112_MFG_STR`, a 30-byte character buffer containing the ASCII manufacturing string.
3. `strlen`—is the length of `manufacturingString` in bytes.

**Return Value**: `HID_SMBUS_STATUS`
- `HID_SMBUS_SUCCESS`
- `HID_SMBUS_INVALID_DEVICE_OBJECT`
- `HID_SMBUS_INVALID_PARAMETER`
- `HID_SMBUS_DEVICE_IO_FAILED`
3.6 HidSmbus_GetManufacturingString

Description: This function retrieves the USB manufacturing string.

Prototype: `HID_SMBUS_STATUS HidSmbus_GetManufacturingString (HID_SMBUS_DEVICE device, char* manufacturingString, BYTE* strlen)`

Parameters:
1. `device`—is the device object pointer as returned by `HidSmbus_Open()`.
2. `manufacturingString`—is a variable of type `HID_SMBUS_CP2112_MFG_STR`, a 30-byte character buffer that will contain the ASCII manufacturing string.
3. `strlen`—returns the length of the string in bytes.

Return Value: `HID_SMBUS_STATUS`
- `HID_SMBUS_SUCCESS`
- `HID_SMBUS_INVALID_DEVICE_OBJECT`
- `HID_SMBUS_INVALID_PARAMETER`
- `HID_SMBUS_DEVICE_IO_FAILED`

3.7 HidSmbus_SetProductString

Description: This function allows one-time customization of the USB product string.

Prototype: `HID_SMBUS_STATUS HidSmbus_SetProductString (HID_SMBUS_DEVICE device, char* productString, BYTE strlen)`

Parameters:
1. `device`—is the device object pointer as returned by `HidSmbus_Open()`.
2. `productString`—is a variable of type `HID_SMBUS_CP2112_PRODUCT_STR`, a 30-byte character buffer containing the ASCII product string.
3. `strlen`—is the length of `productString` in bytes. The maximum string length is 30 bytes.

Return Value: `HID_SMBUS_STATUS`
- `HID_SMBUS_SUCCESS`
- `HID_SMBUS_INVALID_DEVICE_OBJECT`
- `HID_SMBUS_INVALID_PARAMETER`
- `HID_SMBUS_DEVICE_IO_FAILED`

3.8 HidSmbus_GetProductString

Description: This function retrieves the USB product string.

Prototype: `HID_SMBUS_STATUS HidSmbus_GetProductString (HID_SMBUS_DEVICE device, char* productString, BYTE* strlen)`

Parameters:
1. `device`—is the device object pointer as returned by `HidSmbus_Open()`.
2. `productString`—is a variable of type `HID_SMBUS_CP2112_PRODUCT_STR`, a 30-byte character buffer that will contain the ASCII product string.
3. `strlen`—returns the length of the string in bytes.

Return Value: `HID_SMBUS_STATUS`
- `HID_SMBUS_SUCCESS`
- `HID_SMBUS_INVALID_DEVICE_OBJECT`
- `HID_SMBUS_INVALID_PARAMETER`
- `HID_SMBUS_DEVICE_IO_FAILED`
3.9 HidSmbus_SetSerialString

Description: This function allows one-time customization of the USB serial string.

Prototype:

```c
HID_SMBUS_STATUS HidSmbus_SetSerialString (HID_SMBUS_DEVICE device,
    char* serialString, BYTE strlen)
```

Parameters:
1. `device`—is the device object pointer as returned by `HidSmbus_Open()`.
2. `serialString`—is a variable of type `HID_SMBUS_CP2112_SERIAL_STR`, a 30-byte character buffer containing the ASCII serial string.
3. `strlen`—is the length of `serialString` in bytes. The maximum string length is 30 bytes.

Return Value:
- `HID_SMBUS_SUCCESS`
- `HID_SMBUS_INVALID_DEVICE_OBJECT`
- `HID_SMBUS_INVALID_PARAMETER`
- `HID_SMBUS_DEVICE_IO_FAILED`

3.10 HidSmbus_GetSerialString

Description: This function retrieves the USB product string.

Prototype:

```c
HID_SMBUS_STATUS HidSmbus_GetSerialString (HID_SMBUS_DEVICE device,
    char* serialString, BYTE* strlen)
```

Parameters:
1. `device`—is the device object pointer as returned by `HidSmbus_Open()`.
2. `serialString`—is a variable of type `HID_SMBUS_CP2112_SERIAL_STR`, a 30-byte character buffer that will contain the ASCII product string.
3. `strlen`—returns the length of the string in bytes.

Return Value:
- `HID_SMBUS_SUCCESS`
- `HID_SMBUS_INVALID_DEVICE_OBJECT`
- `HID_SMBUS_INVALID_PARAMETER`
- `HID_SMBUS DEVICE IO FAILED`
4. HID_SMBUS_STATUS Return Codes

Each library function returns an `HID_SMBUS_STATUS` return code to indicate that the function returned successfully or to describe an error. The following table describes each error code.

**Table 4.1. Error Code Descriptions**

<table>
<thead>
<tr>
<th>Definition</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>HID_SMBUS_SUCCESS</code></td>
<td>0x00</td>
<td>Function returned successfully.¹</td>
</tr>
<tr>
<td><code>HID_SMBUS_DEVICE_NOT_FOUND</code></td>
<td>0x01</td>
<td>Indicates that no devices are connected or that the specified device does not exist.</td>
</tr>
<tr>
<td><code>HID_SMBUS_INVALID_HANDLE</code></td>
<td>0x02</td>
<td>Indicates that the handle value is NULL or <code>INVALID_HANDLE_VALUE</code> or that the device with the specified handle does not exist.</td>
</tr>
<tr>
<td><code>HID_SMBUS_INVALID_DEVICE_OBJECT</code></td>
<td>0x03</td>
<td>Indicates that the device object pointer does not match the address of a valid HID USB-to-SMBus device.</td>
</tr>
<tr>
<td><code>HID_SMBUS_INVALID_PARAMETER</code></td>
<td>0x04</td>
<td>Indicates that a pointer value is NULL or that an invalid setting was specified.</td>
</tr>
<tr>
<td><code>HID_SMBUS_INVALID_REQUEST_LENGTH</code></td>
<td>0x05</td>
<td>Indicates that the specified number of bytes to read or write is invalid. Check the read and write length limits.</td>
</tr>
<tr>
<td><code>HID_SMBUS_READ_ERROR</code></td>
<td>0x10</td>
<td>Indicates that the read was not successful and did not time out. This means that the host could not get an input interrupt report.</td>
</tr>
<tr>
<td><code>HID_SMBUS_WRITE_ERROR</code></td>
<td>0x11</td>
<td>Indicates that the write was not successful. This means that the output interrupt report failed or timed out.</td>
</tr>
<tr>
<td><code>HID_SMBUS_READ_TIMED_OUT</code></td>
<td>0x12</td>
<td>Indicates that a read failed to return the number of bytes requested before the read timeout elapsed. The read timeout should be increased.</td>
</tr>
<tr>
<td><code>HID_SMBUS_WRITE_TIMED_OUT</code></td>
<td>0x13</td>
<td>Indicates that a write failed to complete sending the number of bytes requested before the write timeout elapsed. The write timeout should be increased.</td>
</tr>
<tr>
<td><code>HID_SMBUS_DEVICE_IO_FAILED</code></td>
<td>0x14</td>
<td>Indicates that the host was unable to get or set a feature report. The device might be disconnected.</td>
</tr>
<tr>
<td><code>HID_SMBUS_DEVICE_ACCESS_ERROR</code></td>
<td>0x15</td>
<td>Indicates that the device or device property could not be accessed. Either the device is not opened, already opened when trying to open, or an error occurred while trying to get HID information.</td>
</tr>
<tr>
<td><code>HID_SMBUS_DEVICE_NOT_SUPPORTED</code></td>
<td>0x16</td>
<td>Indicates that the current device does not support the corresponding action. Functions listed in this document are for the CP2112 only.</td>
</tr>
<tr>
<td><code>HID_SMBUS_UNKNOWN_ERROR</code></td>
<td>0xFF</td>
<td>This is the default return code value. This value should never be returned.</td>
</tr>
</tbody>
</table>

**Note:**
1. Set functions may return success, indicating that the device received the request; however, there is no indication that the device actually performed the request (i.e., the setting was invalid). The user must call the corresponding get function to verify that the settings were properly configured.
5. Thread Safety

The HID USB-to-SMBus library and associated functions are not thread safe. This means that calling library functions simultaneously from multiple threads may have undesirable effects.

To use the library functions in more than one thread, the user should do the following:

1. Call library functions from within a critical section such that only a single function is being called at any given time. If a function is being called in one thread, then the user must prevent another thread from calling any function until the first function returns.

2. HidSmbus_GetReadResponse(), HidSmbus_GetTransferStatusResponse(), HidSmbus_TransferStatusRequest(), and HidSmbus_CancelTransfer() issue pending read requests that cannot be canceled from another thread. If the user calls HidSmbus_Close() in a different thread than the thread in which the read request was created, then the device will not be accessible after calling HidSmbus_Close(). The thread that issued the pending read request must return/terminate successfully before the device can be accessed again. See 6. Thread Read Access Models for Windows for more information.
6. Thread Read Access Models for Windows

There are several common read access models when using the HID USB-to-SMBus library. There are some restrictions on the valid use of a device handle based on these models. CancelIo() can only cancel pending I/O (reads/writes) issued in the same thread in which CancelIo() is called. Due to this limitation, the user is responsible for cancelling pending I/O before closing the device. Failure to do so will result in an inaccessible HID USB-to-SMBus device until the thread releases access to the device handle. The following tables describe five common access models and the expected behavior.

Note:
1. HidSmbus_Close() calls CancelIo() prior to calling CloseHandle().
2. QueueInterruptReports() issues a pending interrupt report read request. The request completes if at least one input report is read. The request is still pending if the operation times out. The following functions call QueueInterruptReports():
   - HidSmbus_GetReadResponse()
   - HidSmbus_GetTransferStatusResponse()
   - HidSmbus_TransferStatusRequest()
   - HidSmbus_CancelTransfer()
3. HidSmbus_CancelIo() forces any pending requests issued by the same thread to complete (cancelled).
4. * indicates that a read is still pending and was issued in the specified thread.
5. ? indicates that a read is still pending and was issued in one of the threads (indeterminate).

Table 6.1. Single Thread Access Model (Safe)

<table>
<thead>
<tr>
<th>Thread A</th>
<th>Thread B</th>
<th>Result</th>
</tr>
</thead>
<tbody>
<tr>
<td>HidSmbus_Open()</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td>QueueInterruptReports(*)</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td>HidSmbus_Close()</td>
<td>—</td>
<td>OK</td>
</tr>
</tbody>
</table>

Table 6.2. Split Thread Access Model (Unsafe)

<table>
<thead>
<tr>
<th>Thread A</th>
<th>Thread B</th>
<th>Result</th>
</tr>
</thead>
<tbody>
<tr>
<td>HidSmbus_Open()</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td>—</td>
<td>QueueInterruptReports(*)</td>
<td></td>
</tr>
<tr>
<td>HidSmbus_Close()</td>
<td>—</td>
<td>Error: Device inaccessible</td>
</tr>
<tr>
<td>—</td>
<td>Terminate Thread</td>
<td>OK: Thread relinquishes device access</td>
</tr>
</tbody>
</table>

Table 6.3. Split Thread Access Mode (Safe)

<table>
<thead>
<tr>
<th>Thread A</th>
<th>Thread B</th>
<th>Result</th>
</tr>
</thead>
<tbody>
<tr>
<td>HidSmbus_Open()</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td>—</td>
<td>QueueInterruptReports(*)</td>
<td>—</td>
</tr>
<tr>
<td>—</td>
<td>HidSmbus_CancelIo()</td>
<td>—</td>
</tr>
<tr>
<td>HidSmbus_Close()</td>
<td>—</td>
<td>OK</td>
</tr>
</tbody>
</table>
## Table 6.4. Multi-Thread Access Model (Unsafe)

<table>
<thead>
<tr>
<th>Thread A</th>
<th>Thread B</th>
<th>Result</th>
</tr>
</thead>
<tbody>
<tr>
<td>HidSmbus_Open()</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td>QueueInterruptReports()?</td>
<td>QueueInterruptReports()?</td>
<td>—</td>
</tr>
<tr>
<td>HidSmbus_Close()</td>
<td>—</td>
<td>QueueInterruptReports()? * Thread A: OK</td>
</tr>
<tr>
<td></td>
<td></td>
<td>QueueInterruptReports()? * Thread B: Error: Device inaccessible</td>
</tr>
<tr>
<td>—</td>
<td>Terminate Thread</td>
<td>OK: Thread relinquishes device access</td>
</tr>
</tbody>
</table>

## Table 6.5. Multi-Thread Access Model (Safe)

<table>
<thead>
<tr>
<th>Thread A</th>
<th>Thread B</th>
<th>Result</th>
</tr>
</thead>
<tbody>
<tr>
<td>HidSmbus_Open()</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td>QueueInterruptReports()?</td>
<td>QueueInterruptReports()?</td>
<td>—</td>
</tr>
<tr>
<td>—</td>
<td>HidSmbus_CancelIo()</td>
<td>—</td>
</tr>
<tr>
<td>HidSmbus_Close()</td>
<td>—</td>
<td>OK</td>
</tr>
</tbody>
</table>
7. Surprise Removal (For Windows)

HidSmbus_GetHidGuid() returns the HID GUID so that Windows applications or services can register for the WM_DEVICECHANGE Windows message. Once registered, the application will receive device arrival and removal notices for HID devices. The application must retrieve the device path to filter devices based on VID/PID. Similarly, if a DBT_DEVICEREMOVECOMPLETE message is received, the application must check to see if the device path matches the device path of any connected devices. If this is the case, then the device was removed and the application must close the device. Also, if a DBT_DEVICEARRIVAL message is received, the application might add the new device to a device list so that users can select any HID device matching the required VID/PID. See accompanying example code for information on how to implement surprise removal and device arrival. The following KnowledgeBase articles include programming examples for C++, Visual Basic .NET, and Visual C#:

- C++
- Visual Basic .NET
- Visual C#
8. Document Change List

8.1 Revision 0.3
March 17th, 2017
Updated formatting.
Added the Linux library to 1. Include Files.
Updated the links to the KnowledgeBase articles discussing Surprise Removal in 7. Surprise Removal (For Windows).
Updated 2.17 HidSmbus_GetTransferStatusResponse to define detailedStatus behavior for CP2112-F03 devices.

8.2 Revision 0.2
November 2010
Added 1. Include Files.
Added support for the Mac OS X dynamic library.
Removed Appendix.

8.3 Revision 0.1
May 2010
Initial release.
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