

# Si7210 I<sup>2</sup>C 霍尔效应磁性位置和温度传感器数据表

Silicon Labs 提供的 Si7210 霍尔效应磁性传感器产品系列结合了斩波稳定型霍尔元件以及低噪声模拟放大器、13 位 AD 转换器和 1 个 I<sup>2</sup>C 接口。借助 Silicon Labs 成熟的 CMOS 设计技术，Si7210 产品系列融入数字信号处理，为温度和失调漂移提供精密补偿。

与现有霍尔效应传感器相比，Si7210 产品系列具有行业领先的灵敏度，使传感器能够在较大气隙和较小磁体条件下使用。集成的 13 位高精度 ADC 可以实现高输出线性度，在极低噪声环境下达到最高的测量精度。

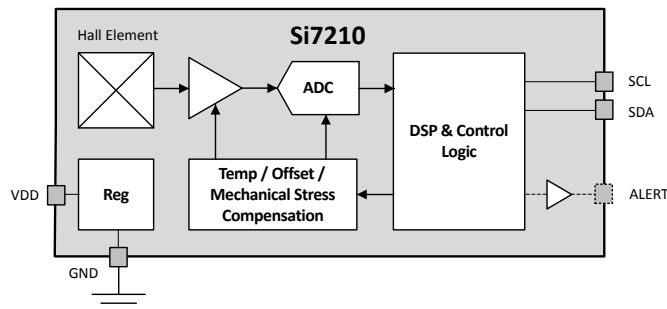
Si7210 产品系列支持双向 I<sup>2</sup>C 接口，该接口可以提供霍尔效应传感器操作点和释放点的完整配置。在任何时候，都可以通过该 I<sup>2</sup>C 接口读取 13 位磁场强度。

## 应用

- 消费、工业和应用中的机械位置传感器
- 簧片开关的替代品
- 液位测量
- 速度传感
- 公用事业电表
- 控制旋钮和选择器开关

## 特性:

- 高灵敏度霍尔效应传感器
  - 可调整满量程（标准量程为  $\pm 20\text{mT}$  和  $\pm 200\text{mT}$  满量程）
  - 为温度和失调漂移提供补偿的集成数字信号处理
  - 高精度 13 位信号通路
  - 输出带宽高达 20 kHz
  - 在  $0\text{--}70^\circ\text{C}$  温度范围内，灵敏度漂移幅度  $< \pm 5\%$
- 数字 I<sup>2</sup>C 接口
  - 4 种可选 I<sup>2</sup>C 地址
  - 可选的数字警报输出
  - 可选的比率式模拟输出
- 电源电压范围广（1.7 至 5.5 V）
- I<sup>2</sup>C 同样拥有温度传感器数据（精度  $\pm 1^\circ\text{C}$ ）
- 睡眠模式电流消耗低至 50 nA
- 行业标准封装
  - 表面安装式 SOT-23 封装
  - 1.4 x 1.6 mm 8 引脚 DFN 封装（即将推出）



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## 1. Electrical Specifications

Unless otherwise specified, all min/max specifications apply over the recommended operating conditions.

**Table 1.1. Recommended Operating Conditions**

Parameter	Temp Grade	Symbol	Test Condition	Min	Typ	Max	Unit
Power Supply		V <sub>DD</sub>		1.71		5.5	V
Temperature	I	T <sub>A</sub>		-40		+125	°C

**Table 1.2. General Specifications**

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Input Voltage High	V <sub>IH</sub>	SCL, SDA pins	0.7 x V <sub>DD</sub>	-	-	V
Input Voltage Low	V <sub>IL</sub>	SCL, SDA pins	-	-	0.3 x V <sub>DD</sub>	V
Input Voltage Range	V <sub>IN</sub>	SCL, SDA with respect to ground	0		V <sub>DD</sub>	V
Input Leakage	I <sub>IL</sub>	SDA, SCL		< 0.1	1	μA
Output Voltage Low	V <sub>OL</sub>	SCL, SDA I <sub>OL</sub> = 3 mA V <sub>DD</sub> > 2 V			0.4	V
		SCL, SDA I <sub>OL</sub> = 2 mA V <sub>DD</sub> > 1.71 V			0.2	V
		SCL, SDA I <sub>OL</sub> = 6 mA V <sub>DD</sub> > 2 V			0.6	V
Current Consumption	I <sub>DD</sub>	Sleep timer enabled average at V <sub>DD</sub> = 3.3 V and 200 msec sleep time		0.4		μA
		Sleep mode V <sub>DD</sub> = 3.3 V, T = 25 °C		50		nA
		Sleep mode V <sub>DD</sub> = 3.3 V, T = 70 °C			1000	
		Sleep mode V <sub>DD</sub> = 5.5 V, T = 125 °C			5000	
		Conversion in progress: 1.8 V		3.5	4.5	mA
		3.3 V		5.0	6	
		5.0 V		6.8	8.5	
		Idle mode		360	1000	μA
Conversion Time	T <sub>CONV</sub>	Conversion time for first measure- ment in a burst		11		μs
		Additional conversions in a burst		8.8		μs

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Sleep Time	T <sub>SLEEP</sub>	Factory configurable from 1 to 200 msec ±20%		-		
Idle Time <sup>1</sup>	T <sub>IDLE</sub>	slTime = 0x01 slFast = 1	11.9	13.2	14.5	µs
		slTime = 0xFF slFast = 0	185	206	227	msec
Wake Up Time	T <sub>WAKE</sub>	Time from V <sub>DD</sub> > 1.7 V to first measurement			1	msec
<b>Note:</b> 1. Part can go to either idle more or sleep mode between conversions. If part is in idle mode with slTime = 0x00 and slFast = 1 conversion are continuous at 8.8 µsec interval.						

Table 1.3. Output Pin Specifications

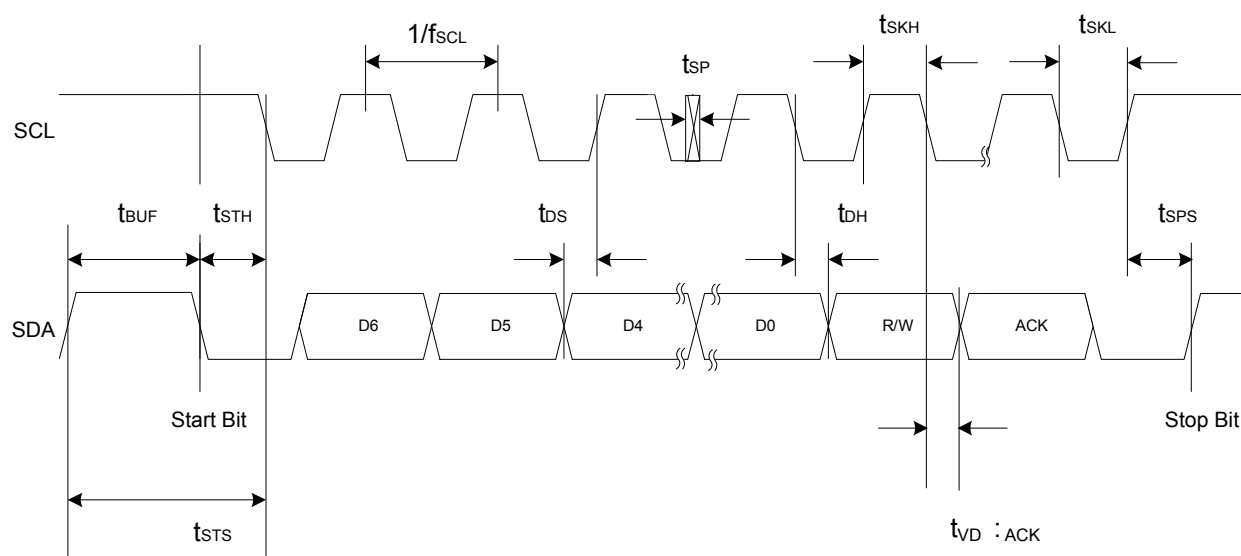
Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Output Voltage Low	V <sub>OL</sub>	I <sub>OL</sub> = 3 mA V <sub>DD</sub> > 2 V			0.4	V
Output Pin Open Drain or Push Pull		I <sub>OL</sub> = 2 mA V <sub>DD</sub> > 1.7 V			0.2	V
		I <sub>OL</sub> = 6 mA V <sub>DD</sub> > 2 V			0.6	V
Leakage Output high Output Pin Open Drain	I <sub>OH</sub>				1	µA
Output Voltage High	V <sub>OH</sub>	I <sub>OH</sub> = 2 mA V <sub>DD</sub> > 2.25 V	V <sub>DD</sub> - 0.4			V
Output Pin Push Pull						
Slew Rate Digital Output Mode	T <sub>SLEW</sub>			5		%V <sub>DD</sub> /ns

**Table 1.4. I<sup>2</sup>C Interface Specification**

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
SCL Clock Frequency	f <sub>SCL</sub>		0		400	kHz
Start Condition Hold Time	t <sub>SDH</sub>		0.6			μs
LOW Period of SCL	t <sub>SKL</sub>		1.3			μs
HIGH Period of Clock	t <sub>SKH</sub>		0.6			μs
Set Up Time for a Repeated Start	t <sub>SU:STA</sub>		0.6			μs
Data Hold Time	t <sub>DH</sub>		0			
Data Set Up Time	t <sub>DS</sub>		100			ns
Set Up Time for a STOP Condition	t <sub>SPS</sub>		0.6			μs
Bus Free Time between STOP and START	t <sub>BUF</sub>		1.3			μs
Data Valid Time (SCL Low to Data Valid)	t <sub>VD;DAT</sub>				0.9	μs
Data Valid Acknowledge Time (time from SCL Low to SDA Low)	t <sub>VD;ACK</sub>				0.9	μs
Hysteresis		Digital input hysteresis SDA and SCL	7		17	%V <sub>DD</sub>
Suppressed Pulse Width <sup>1</sup>	t <sub>SP</sub>		50			ns

**Note:**

1. Pulses up to and including 50 nsec will be suppressed.



**Figure 1.1. I<sup>2</sup>C Interface Timing**

**Table 1.5. Magnetic Sensor**

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Offset (Digital Output Mode)	B <sub>OFF</sub>	20 mT scale		±250	±450, -350	μT
		Full temperature and V <sub>DD</sub> range				
		0 - 70°C and 1.71 V to 3.6 V			±250	μT
Gain Accuracy		0 - 70°C			5	%
		Full temperature range			10	%
RMS Noise <sup>1</sup>		Temp = 25 °C, 20 mT range, V <sub>DD</sub> = 5 V		30		μT rms

**Note:**

1. For a single conversion. This may be reduced by filtering.

**Table 1.6. Temperature Compensation**

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Gain Variation with Temperature		Flat Tempco.		< +/-0.05		%/°C
		0 - 70°C				
		Neodymium compensation		-0.12		%/°C
		Ceramic compensation		-0.2		%/°C

**Table 1.7. Average Temperature Measurement Error**

Parameter	Symbol	Test Conditon	Min	Typ	Max	Unit
Average Temperature Measurement Error After Gain and Offset Correction		-10 to +85°C		±1	±1.5	°C

**Table 1.8. Thermal Characteristics**

Parameter	Symbol	Test Condition	Value	Unit
Junction to Air Thermal Resistance	$\theta_{JA}$	JEDEC 4 layer board no airflow SOT23-5	212.8	°C/W
Junction to Board Thermal Resistance	$\theta_{JB}$	JEDEC 4 layer board no airflow SOT23-5	45	°C/W

**Table 1.9. Absolute Maximum Ratings**

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Ambient Temperature Under Bias			-55		125	°C
Storage Temperature			-65		150	°C
Voltage on I/O Pins			-0.3		$V_{DD}+0.3$	V
Voltage on VDD with Respect to Ground			-0.3		6	V
ESD Tolerance		HBM			2	kV
		CDM			500	V

**Note:**

1. Absolute maximum ratings are stress ratings only, operation at or beyond these conditions is not implied and may shorten the life of the device or alter its performance.

## 2. Functional Description

The Si7210 family of parts are I<sup>2</sup>C programmable Hall effect magnetic position sensors. These parts digitize the component of the magnetic field in the z axis of the device (positive field is defined as pointing into the device from the bottom). The parts are normally used to detect the presence or absence of a magnet in security systems, as position sensors or for counting revolutions.

In addition to being able to control the conversion process and read the result of magnetic field conversions by I<sup>2</sup>C, the 5-pin packages offer an output pin. The output pin can act as an alert (push pull or open collector) which goes high or low when the magnetic field crosses a threshold. Alternatively the output pin can be configured as an analog output. The output pin configuration is determined by the type of part ordered (this is not I<sup>2</sup>C configurable).

The parts are preconfigured for the magnetic field measurement range, sleep time, temperature compensation, tamper threshold, and digital filtering, and will wake into the preconfigured mode when first powered. The specific configuration, as well as the I<sup>2</sup>C address and output type (open collector or push pull), are determined by the part number. Magnetic field trip points are typically configured by I<sup>2</sup>C, and the part is allowed to go into its normal sleep and measurement cycle. If the bit `UseStore` is set to 1, the output pin trip points are retained in sleep mode. Data other than magnetic field trip points is not retained in sleep mode. If there is not a need to go to full sleep mode, the other parameters may be configured, and this data will be kept in idle mode.

Following is a list of I<sup>2</sup>C interface configurable options:

- *Measurement range.* This is normally set so that after temperature compensation the full scale (15b unsigned) digital output is  $\pm 20.47$  mT (0.00125 mT/bit) or  $\pm 204.7$  mT (0.0125 mT/bit). (Note: 1 Gauss = 0.1 mT). For convenience these are referred to as the 20 mT and 200 mT scales.
- *Digital filtering.* To reduce noise in the output (normally 0.03 mT RMS on the 20 mT scale), digital filtering can be applied. The digital filtering can be done to a burst of measurements (FIR filter) or can be configured to average measurements in IIR style. The filtering can be done over a number of samples in powers of 2 (1,2,4,8,...) for up to 2<sup>12</sup> (4096) samples.
- *Time between measurements* (or measurement bursts for the case of FIR filtering)
  - For lowest power, the part can be configured to sleep between measurements. However, remember some configuration data is lost in sleep mode.
  - For faster measurement rates, the part is configured to idle between samples.
  - The part can also be configured to take a single measurement on command.
- *The digital output pin* (for parts that support this option)
  - Threshold at which the digital output will change for increasing field (Bop) and for decreasing field (Brp).
  - The direction in which the output pin goes in response to an increase in field
  - There is an option to take the magnitude of the field prior to the comparison so that the polarity is not field dependent
  - The settings will be retained in sleep mode.
  - A “tamper threshold”. This is intended to signal the presence of a strong magnet, which may indicate tampering. In the case of tamper detection, the output pin will go to its zero field value (which in security systems is normally an indication of door or window open).
- *Temperature compensation of the magnetic field response to compensate for the nominal drop in magnetic field output of common magnets with increasing temperature.*
- *An on chip coil that generates a large enough field to allow self-test of the sensor*
  - The coil can be turned on in either polarity

For greater precision in programming the part, a number of calibration data points are stored in memory (OTP).

- The nominal magnetic field output of the on-chip coil normalized to the power supply voltage
- Coefficients to be used for setting gain and temperature compensation



### 3. I<sup>2</sup>C Interface

The Si7210 complies with “fast” mode I<sup>2</sup>C operation and 7 bit addressing at speeds up to 400 kHz. The I<sup>2</sup>C address is factory programmed to one of 4 values 0x30, 0x31, 0x32, or 0x33 (0110000b through 0110011b).

At power-up the registers are initialized, as will be described in the register definitions, and then they can be read or written in standard fashion for I<sup>2</sup>C devices. A special sequence must be used to read OTP data, as will be described.

The host command for writing an I<sup>2</sup>C register is:

START	Address	W	ACK	register	ACK	data	ACK	STOP
-------	---------	---	-----	----------	-----	------	-----	------

The host command for reading an I<sup>2</sup>C register is:

START	Address	W	ACK	Register	ACK	Sr	Address	R	Data	NACK*	STOP
-------	---------	---	-----	----------	-----	----	---------	---	------	-------	------

\*NACK by host

Where:

START is SDA going low with SCL high

Sr is a repeated START

Address is 0x30 up to 0x33

0 indicates a write and 1 indicates a read

ACK is SDA low

Data is the Read or Write data

NACK is SDA high

STOP is SDA going high with SCL high

Writing or Reading of sequential registers can be supported by setting the `arautoinc` bit of register 0xC5 (see register description). In the case of a read sequence where the `arautoinc` bit has been set, the data can be ACK'd to allow reading of sequential registers. For example, a two byte read of the conversion data in registers 0xC1 and 0xC2 would be:

START	Address	W	ACK	0xC1	ACK	Sr	Address	ACK	data	ACK*	data	NACK*	STOP
-------	---------	---	-----	------	-----	----	---------	-----	------	------	------	-------	------

\* ACK or NACK by host

To wake a part from sleep mode or to interrupt a measurement loop from idle mode, send the sequence:

START	Address	W	ACK	STOP
-------	---------	---	-----	------

In this case, if the host continued with a register, the Si7210 would NACK which would be unexpected.

or use:

START	Address	R	ACK	data	NACK*	STOP
-------	---------	---	-----	------	-------	------

\*NACK by host

In this case the Si7210 will produce 0xFF for the data.

Allow 10 µsec between the ACK of the address and the next START for the Si7210 to wake from sleep. In most cases this will happen automatically due to the 400 kHz maximum speed of the I<sup>2</sup>C bus.

The sequence will put the part in idle mode with the `stop` bit set.

**Note:** It is recommended that the part be put in stop mode prior to changing data that will affect a measurement outcome.

To make a single conversion having woken the part, set the `oneburst` bit of register 0xC4 to 1 and the `stop` bit to 0. The `stop` bit resets to 1 by the time the measurement is complete.

To put the part back to sleep after reading the data, set `stop` bit to 0. The bit `slTimeena` is normally factory set to 1, so it does not need to be set. The bit `sleep` is not set.

To put the part to sleep with no measurements (sleep timer disabled), write the `sleep` bit to 1 and the `stop` bit to 0.

If it is desired to re-enable the sleep timer having put the part to sleep with `sleeptimer` disabled, then wait 500  $\mu$ sec after setting the `sltimeena` bit before putting the part to sleep.

## 4. Register Definitions

The Si7210 has 21 registers in locations 0xC0 – 0xE4.

Configuration data is loaded at start up from OTP data and can be modified by I<sup>2</sup>C writes.

**Note:** This data will be reloaded when the part wakes from sleep mode (other than 0xC6 and 0xC7 which are not reloaded if bit `Usestore` is set).

ADDR	7	6	5	4	3	2	1	0
0xC0	chipid (RO)				revid (RO)			
0xC1	Dpsigm							
0xC2	Dpsigl							
0xC3						dspisgsel		
0xC4	meas(RO)				Usestore	oneburst	stop	sleep
0xC5								arautoinc
0xC6	sw_low4field	sw_op						
0xC7	sw_fieldpolsel			sw_hyst				
0xC8	slTime							
0xC9	sw_tamper						slFast	slTimeena
0xCA	a0							
0xCB	a1							
0xCC	a2							
0xCD	df_burstsize			df_bw				df_iir
0xCE	a3							
0xCF	a4							
0xD0	a5							
0xE1	otp_addr							
0xE2	otp_data							
0xE3							otp_read_e n	otp_busy(RO)
0xE4							tm_fg	

As can be seen many of the bit fields are not aligned with register boundaries. When writing a particular bit field, it is best to use a read, modify, write procedure to ensure that other bit fields are not unintentionally changed. That is, read the register, modify the bit field of interest while keeping other bits the same, and then write the register back. Unspecified bits should not be changed from the factory configuration.

### 4.1 Field Descriptions

#### 4.1.1 Chip ID

`chipid` (RO) – This ID 0x1 for all Si7210 parts.

`revid` (RO) – This ID 0x4 for revision B.

#### 4.1.2 Fields Associated with Reading DATA

`Dpsigm` – Bits [6:0] are the most significant byte of the last conversion result. The most significant bit is a “fresh” bit indicating the register has been updated since last read. Reading the `Dpsigm` register causes the register `Dpsigl` to be loaded with the least significant byte of the last conversion result.

`Dpsigl` – The least significant byte of the last conversion result. Read `Dpsigm` first to align the bytes. The complete 15b unsigned result is  $256 * Dpsigm[6:0] + Dpsigl[7:0]$ . A result of 16384 means zero field. More negative results mean negative field, and more positive results mean more positive field. With the normal recommended gain settings, the magnetic field data is scaled to 1 LSB = 0.00125 mT ( $\pm 20.47$  mT full scale) or 1 LSB = 0.0125 mT ( $\pm 204.7$  mT full scale)

Magnetic field is calculated from the formula:

$$B = (256 * Dpsigm[6:0] + Dpsigl[7:0] - 16384) * (0.00125 \text{ or } 0.0125)$$

**Note:** The data for `a0` - `a5` in registers 0xC9 through 0xD0 is appropriate for the default averaging which is typically 1 sample (`df_burstsize=0`). The data in registers 0x21 - 0x44 is appropriate when averaging is turned on (`df_burstsize>0`). If using the coefficients in 0x21 - 0x44 (for example, to change the measurement scale) and there is no averaging, then subtract 0.1mT from the calculated B field..

Setting `dpsigsel` to 0x01 will give the output of an internal temperature sensor. See also [5. Making Temperature Measurements](#).

`meas(RO)` – indicates a measurement is in process. In most cases this bit is not needed as the fresh bit of `Dpsigm` can be used instead.

`oneburst` – Setting this bit initiates a single conversion. Set `stop` = 0 when setting `oneburst` = 1. The `oneburst` bit will auto clear once the conversion initiates and the `stop` bit will be set to 1 when the conversion completes.

`stop` - Setting this bit causes the control state machine measurement loop to pause after the current measurement burst completes. Once set, clearing this bit restarts the measurement loop.

`sleep` - Setting this bit causes the part to enter sleep mode after the current measurement burst completes. Once set, clearing this bit restarts the measurement loop.

`arautoinc` – enables auto increment of the I<sup>2</sup>C register address pointer. This bit is not retained in sleep mode

### 4.1.3 Fields Associated with Configuring the Output Pin

**Usestore** – Setting this bit causes the current state of OTP registers for the `sw_op`, `sw_hyst`, `sw_low4field`, and `sw_fieldpolsel` bits to be saved and restored during the next sleep and wakeup sequence instead of using data read from the OTP.

**Note:** Allowing a part to enter sleep mode will result in reloading other parameters, such as the filtering data. This bit will also be retained in sleep mode.

`sw_low4field` - selects logic sense; output is low when the field is strong when the bit is set. Output is high when the field is strong when the bit is cleared.

`sw_op` – this 7 bit number sets the center point of the decision point for magnetic field high or low. The actual decision point is the center point plus or minus the hysteresis.

The 15b data that can be read from I<sup>2</sup>C is truncated to 13b prior to the logic that makes the decision. The middle of the decision point relative to full scale (13b signed or +/-4096 counts) is:

$$threshold = (16 + sw\_op[3 : 0]) \times 2^{sw\_op[6:4]}$$

threshold = 0, when `sw_op` = 127

These numbers run from 16 to 3840. On the 20 mT scale each LSB of the 15b number is 0.00125 mT. In 13b representation the LSB is 0.005 mT/bit so the middle of the decision point can be programmed from 0.08 mT to 19.2 mT (16\*0.005 to 3840\*0.005).

Similarly, on the 200 mT scale, the middle point of the decision threshold can be programmed from 0.8 mT to 192 mT.

The special case of `sw_op` = 127 is for “latches”. A Hall effect latch is like a Hall effect switch except the decision points are generally symmetrical around zero. A Hall effect latch is useful for detecting wide range of motion such as a garage door where there are magnets of opposite polarities at the extremes of travel.

`sw_fieldpolsel`

- 00b: absolute value of the field is taken before comparing to threshold (omnipolar)
- 01b: field is multiplied by -1 before being compared to (positive) threshold (unipolar operating in negative field region)
- 10b: field is multiplied by 1 before being compared to (positive) threshold (unipolar operating in positive field region). Also compatible with Latch operation.
- 11b: unused

`sw_hyst` - the formula for switch hysteresis is:

$$hysteresis = (8 + sw\_hyst[2 : 0]) \times 2^{sw\_hyst[5:3]}$$

If `sw_op` = 127, (latch mode) the hysteresis is multiplied by 2

When `sw_hyst` = 63, the hysteresis is set to zero.

These numbers can range from 8 to 1792 or 16 to 3584 when the sensor is in “latch” mode with `sw_op` = 127.

On the 20 mT scale this corresponds to ±0.04 mT to ±8.96 mT hysteresis when the part is in switch mode and ±0.08 mT to ±17.92 mT in latch mode. On the 200 mT scale, these numbers are multiplied by 10.

Note that

$$Bop = (threshold + hysteresis) \times \frac{0.05mT}{bit}, \text{ or } = (threshold + hysteresis) \times \frac{0.5mT}{bit}$$

And

$$Brp = (threshold - hysteresis) \times \frac{0.05mT}{bit}, \text{ or } = (threshold - hysteresis) \times \frac{0.5mT}{bit}$$

So that

$$Bop - Brp = 2 \times hysteresis \times \frac{0.05mT}{bit}, \text{ or } = 2 \times hysteresis \times \frac{0.5mT}{bit}$$

`sw_tamper` – For the Si7210 if there is a strong magnetic field and the tamper threshold is exceeded, the output pin will go to the same value it would have been at if the measured field was zero. For a security application, if someone tried to “fool” the sensor by putting a strong magnet near it, the output indication would be the same as “door open” or low magnetic field indicating possible tampering.

The formula for the tamper threshold is:

$$tamper = (16 + sw\_tamper[3 : 0]) \times 2^{sw\_tamper[5:4]+5}$$

The tamper feature is disabled if  $sw\_tamper = 63$

This formula can give numbers ranging from 512 to 7936 (which is greater than the full scale of the part. Generally any setting of switch  $tamper(5:4) = 3$  (11b) effectively disables the tamper feature as well. With switch  $tamper = 101111b$  the tamper threshold is 3968 which is 96.895 % of full scale. On the 20 mT scale a setting of 000000b (threshold = 512) gives a tamper threshold of 2.65 mT and a setting of 101111b (threshold = 3968) gives a tamper threshold of 19.84 mT. On the 200 mT scale these numbers are multiplied by 10.

Example:

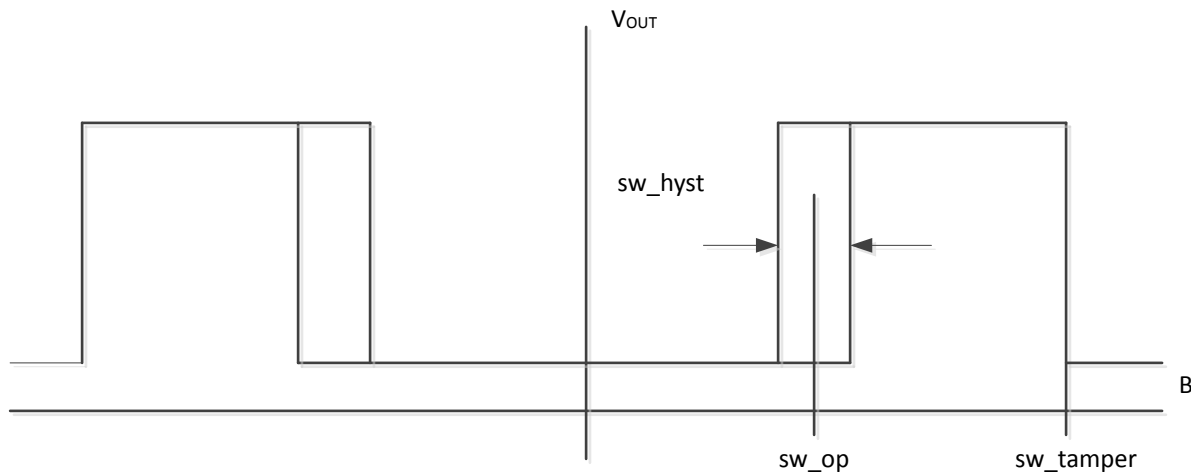


Figure 4.1. Ompipolar Switch with Tamper

#### 4.1.4 Registers Associated with Control of Idle Time

$slTime$  - Controls duration of sleep or IDLE interval.

**Note:** For the case of sleep between measurements ( $slTimeena = 1$ ), the sleep time is not user configurable and it is recommended that this register should not be changed. The register will be reloaded every time a measurement is made when the part wakes from sleep.

The idle counter duration is

$$t_{idle} = (32 + slTime[4 : 0]) \times \frac{2^{8-6 \times slFast + slTime[7:5]}}{10MHz}$$

For the idle counter,  $slFast = 1$  and  $slTime = 0$  overrides to mean actual zero idle time. The AFE runs continuously and a new sample is taken every 8.8  $\mu$ sec.

Idle times are variable from 13.2  $\mu$ sec to 206 msec nominally. Idle times are  $\pm 10\%$ .

$slFast$  - When set, causes a reduction in programmed sleep and idle times as in the above equations.

$slTimeena$  - Enables the sleep timer. 0 means the part goes into complete sleep once the sleep bit is set. 1 means the parts will wake a factory set interval between 1 and 200 msec, make a measurement, set the output pin value and return to sleep.

The sleep time is not user configurable. This is determined by the part number ordered and is factory adjustable in the range of 1 to 20 msec  $\pm 20\%$ .

#### 4.1.5 Registers Associated with Setting the Output Scale

$a_0, a_1, a_2, a_3, a_4, a_5$  - These parameters are associated with the trimming of the part and setting the analog measurement range. 6 sets of these parameters are stored in OTP for the 2 standard ranges of  $\pm 20$  mT and  $\pm 200$  mT and the 3 standard temperature compensations as in [Table 1.6 Temperature Compensation on page 6](#).

Parts are shipped pre-configured for a given output scale. To change the output scale, copy these 5 numbers from OTP to I<sup>2</sup>C memory. (See also section on OTP memory.)

#### 4.1.6 Registers Associated with Adding Digital Filtering

$df\_burstsize$  - Rather than taking a single sample, each time the part wakes up, the Si7210 can be configured to take a burst of measurements. The time required to take one measurement is 11  $\mu$ sec. Each additional measurement takes 8.8  $\mu$ sec.

The maximum setting of  $df\_bw$  is 12. The number of samples to average is  $2^{df\_bw}$ . This can be 1,2,4,8,...up to 4096. In FIR mode the number of samples per burst is controlled by  $df\_bw$

In FIR mode the average is the sum of the samples divided by the number of samples.

$$output(T) = \frac{\sum_{t=T+1-2^{df\_bw}}^T sample(t)}{2^{df\_bw}}$$

$df\_iir = 0$  means the averaging is done FIR style, 1 means the averaging is done IIR style

In IIR mode, the averaging is done using:

$$output(T) = \frac{(2^{df\_bw} - 1)}{2^{df\_bw}} \times output(T - 1) + \frac{1}{2^{df\_bw}} \times sample(T)$$

In IIR mode, the number of measurements in a burst is  $2^{df\_burstsize}$ , so this is 1,2,4,8,... up to 128 samples. Normally, in IIR mode  $df\_burstsize$  is set to 0, but it is possible to use burst averaging on each sample and IIR averaging of the bursts.

#### 4.1.7 Registers to Read OTP Data

The following are used for reading the OTP data:

otp\_addr - is the address of the data to read

otp\_data - is the data once read

otp\_read\_en - must be set to 1 to initiate a read; this bit is auto cleared

otp\_busy – indicates the OTP is busy. For normal I<sup>2</sup>C reads, the data will be available by the time the read enable bit is set and the data is read, so in most cases this bit is not needed.

The table below is the map for OTP memory. Registers 0x04 – 0x0F correspond to the I<sup>2</sup>C registers and are loaded at power up or wake from sleep. If the bit `UseStore` is set, then the first two registers are not reloaded on a wake from sleep.

OTP BYTE	7	6	5	4	3	2	1	0
0x04	sw_low4field		sw_op					
0x05	sw_fieldpolsel			sw_hyst				
0x06	slTime							
0x08	sw_tamper					slFast		slTimeena
0x09	power up a0							
0x0A	power up a1							
0x0B	power up a2							
0x0C	df_burstsize			df_bw				df_iir
0x0D	power up a3							
0x0E	power up a4							
0x0F	power up a5							
0x14	Base part number dropping the “Si72”, for example 01 for Si7201							
0x15	Variant according to data sheet represented in hex., for example, variant 50 is 0x32							
0x16 – 0x17	Reserved							
0x18 – 0x1B	4 byte serial number							
0x1C	Reserved							
0x1D	Temperature sensor offset adjustment							
0x1E	Temperature sensor gain adjustment							
0x20	Reserved							
0x21 - 0x26	a0 – a5 for 20 mT scale and no magnet temperature compensation							
0x27 - 0x2C	a0 - a5 for 200 mT scale and no magnet temperature compensation							
0x2D - 0x32	a0 – a5 for 20 mT scale at 25°C -0.12%/°C magnet temperature compensation (Neodymium)							
0x33 - 0x38	a0 – a5 for 200 mT scale at 25°C -0.12%/°C magnet temperature compensation (Neodymium)							
0x39 - 0x3E	a0 – a5 for 20 mT scale at 25°C -0.2%/°C magnet temperature compensation (Ceramic)							
0x3F - 0x44	a0 – a5 for 200 mT scale at 25°C -0.2%/°C magnet temperature compensation (Ceramic)							



#### 4.1.8 Control of On-Chip Test Coil

tm\_fg - Test Field Generator Coil

tm_fg	Current in coil
00b (State 0)	None
01b (State 1)	Positive direction
10b (State 2)	Negative direction
11b (State 3)	None

Avoid transitions between states 1 & 2, due to a possible short term high current spike.

The nominal magnetic field output of the on chip generator varies with coil current. The coil current varies with coil resistance and power supply voltage, so the nominal magnetic field output varies according to

$$B_{out} = B_{perVnom} \times V_{DD}$$

BperVnom is 1.16 mT/V

This can be used to calculate the expected magnetic field from the test coil for a given V<sub>DD</sub>. This is somewhat temperature dependent so the actual measured field will vary according to the accuracy of the part as well as temperature. Generally, as the coil is turned on and off the measured variation in field should be within ±25% of expectation based on the calculated field generation.

## 5. Making Temperature Measurements

Every magnetic field conversion has an associated temperature measurement. During magnetic field measurement cycles, this data is used for compensating the hall sensor data to keep the desired temperature coefficient of magnetic field measurement.

The temperature data is available by setting the `dspsigsel` field of register 0xC3 to 0x01.

Once the `dspsigsel` field is set, the temperature sensor data is read from registers 0xC1 and 0xC2 as 15b unsigned number (see also [4.1.2 Fields Associated with Reading DATA](#)).

The temperature sensor data can be read after one conversion or after a burst of conversions.

**Note:** The temperature sensor data is not averaged after performing a burst. Only the magnetic field data is averaged.

The data in 0xc1 and 0xc2 is combined into a 12 bit signed number:

$$value = 32 \times Dspigm[6 : 0] + (Dspisig[7 : 0] > 3)$$

$$Temperature\_raw = -3.83 \times 10^{-6} \times value^2 + 0.16094 \times value - 279.80$$

The data read in this way does not have offset and gain correction applied. The offset and gain correction is stored in registers 0x1D and 0x1E which are read as signed integers.

$$Offset = \frac{signed\_value(0x1D)}{16}$$

$$Gain = 1 + \frac{signed\_value(0x1E)}{2048}$$

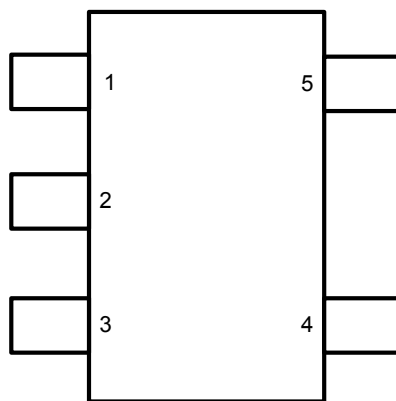
And finally

$$Temperature = gain \times (Temperature\_raw) + offset - (0.222 \times VDD)$$

If VDD is not known, then use VDD = 3.3 V.

Typically, the gain and offset terms are calculated only once and then are saved. The temperature measurement circuit has noise and quantization errors of approximately  $\pm 0.3$  °C. Adding averaging to the calculated temperature will reduce these errors.

## 6. Pin Description



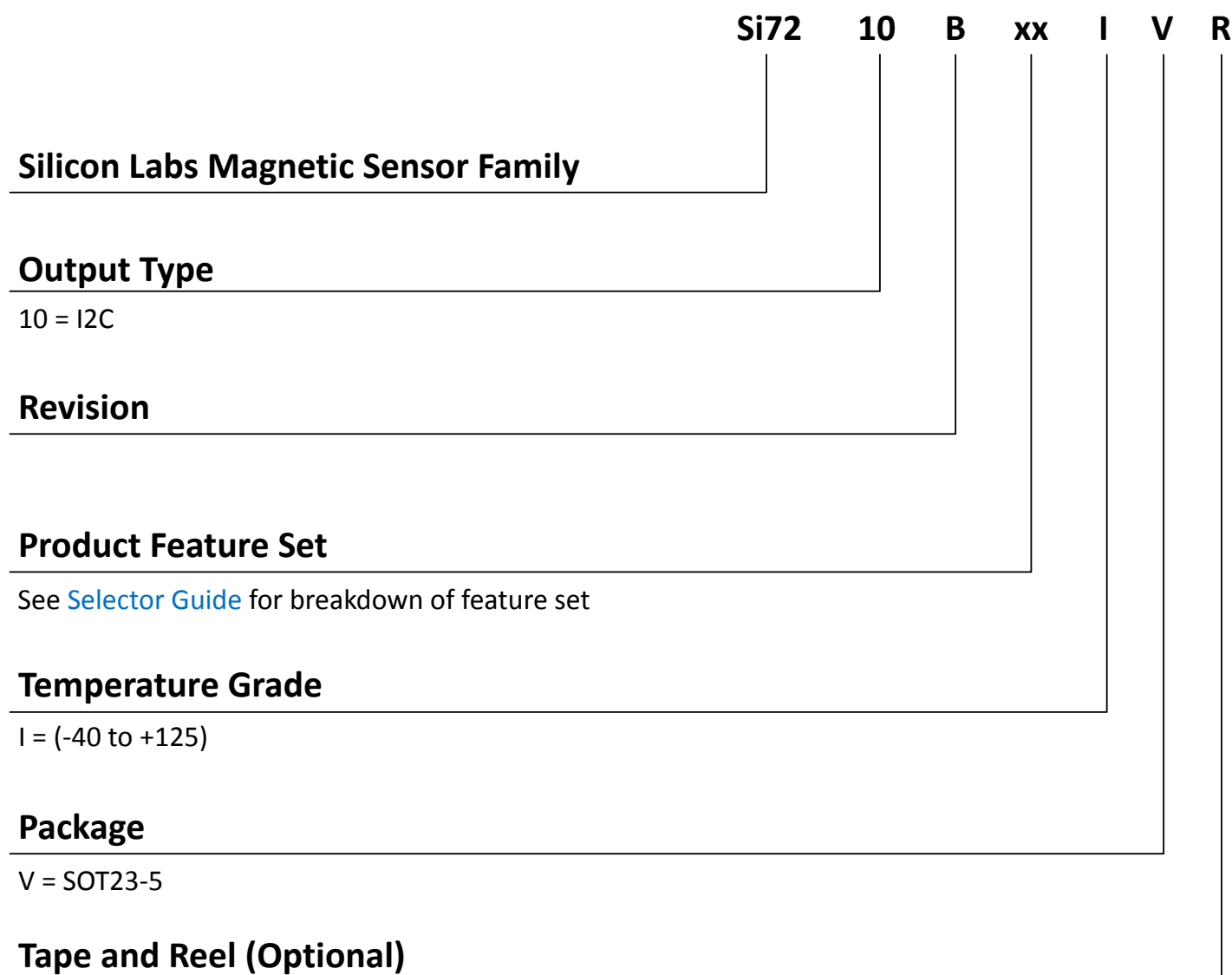
SOT-23, 5-Pin  
Top View

Figure 6.1. Pin Assignments

Table 6.1. 5-Pin SOT23-5 Package

Pin Name	Pin Number	Description
SDA	1	I <sup>2</sup> C data
GND	2	Ground
SCL	3	I <sup>2</sup> C clock
V <sub>DD</sub>	4	Power +1.7 to +5.5 V
ALERT	5	Digital output

## 7. Ordering Information



**Figure 7.1. Si7210 Part Numbering**

**Table 7.1. Product Selection Guide**

Part No.	Default Brp and Bop	Default Output Polarity (High Field)	Default Scale	I2C Address
Si7210 V <sub>DD</sub> = 1.7 - 5.5 V, I <sub>DD</sub> = 0.4 μA typical at V <sub>DD</sub> = 3.3 V. Temperature rating -40 °C to 125 °C. Digital Filtering = None, Sleep/Idle Time = 200 msec (sleep)				
Si7210-B-00-IV(R)	Bop = ±1.1 mT (max) Brp = ±0.2 mT (min)  Bop - Brp  = 0.4 mT (typ)	High (push-pull)	20 mT	0x30
Si7210-B-01-IV(R)	Bop = ±1.1 mT (max) Brp = ±0.2 mT (min)  Bop - Brp  = 0.4 mT (typ)	Low (open drain)	20 mT	0x30

Part No.	Default Brp and Bop	Default Output Polarity (High Field)	Default Scale	I2C Address
Si7210-B-02-IV(R)	Bop = ±1.1 mT (max) Brp = ±0.2 mT (min)  Bop - Brp  = 0.4 mT (typ)	Low (push-pull)	20 mT	0x31
Si7210-B-03-IV(R)	Bop = ±1.1 mT (max) Brp = ±0.2 mT (min)  Bop - Brp  = 0.4 mT (typ)	Low (push-pull)	20 mT	0x32
Si7210-B-04-IV(R)	Bop = ±1.1 mT (max) Brp = ±0.2 mT (min)  Bop - Brp  = 0.4 mT (typ)	Low (push-pull)	20 mT	0x33
Si7210-B-05-IV(R)	Bop = ±2.15 mT (max) Brp = ±0.35 mT (min)  Bop - Brp  = 0.8 mT (typ)	Low (push-pull)	200 mT	0x33

### Additional Information

For information on the below specifications for each OPN, refer to the [Magnetic Sensors Selector Guide](#):

- Default B Release Point (Brp)
- Default B Operate Point (Bop)
- Tamper threshold
- Temperature sensor accuracy

Factory configuration options include:

- The I2C address
- The output pin can be open drain or push pull

In sleep mode, the operate and release point setting are saved if the bit Usestore is set. Other parameters for sleep timer operation are factory configured:

- The tamper indication point
- The sample rate
- Samples per measurement burst (FIR mode only)
- Measurement scale and temperature compensation

**Note:** North pole of a magnet at the bottom of an SOT23-5 package and top of a DFN 8 package (coming soon) is defined as positive field.

## 8. Package Outline

### 8.1 SOT23-5 5-Pin Package

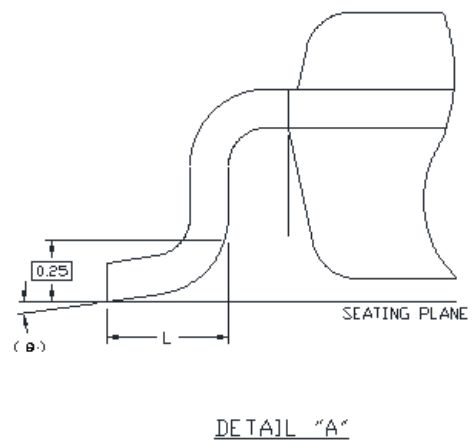
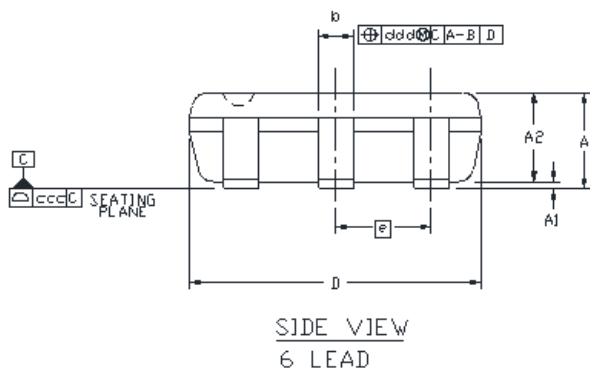
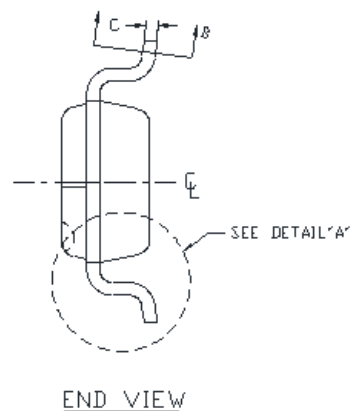
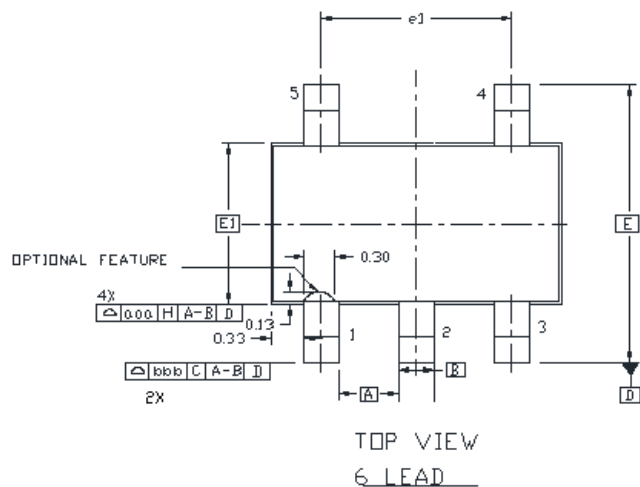


Table 8.1. SOT23-5 5-Pin Package Dimensions

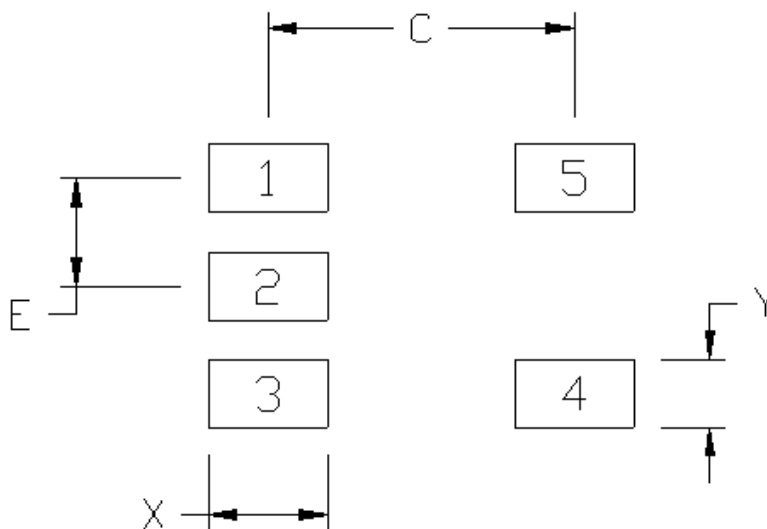
Dimension	Min	Max
A	--	1.25
A1	0.00	0.10
A2	0.85	1.15
b	0.30	0.50
c	0.10	0.20
D	2.90 BSC	
E	2.75 BSC	
E1	1.60 BSC	
e	0.95 BSC	
e1	1.90 BSC	
L	0.30	0.60
L2	0.25 BSC	
$\theta$	0°	8°
aaa	0.15	
bbb	0.20	
ccc	0.10	
ddd	0.20	

**Note:**

1. All dimensions shown are in millimeters (mm) unless otherwise noted.
2. Dimensioning and Tolerancing per ANSI Y14.5M-1994.
3. This drawing conforms to the JEDEC Solid State Outline MO-193, Variation AB.
4. Recommended card reflow profile is per the JEDEC/IPC J-STD-020D specification for Small Body Components.

## 9. Land Patterns

### 9.1 SOT23-5 5-Pin PCB Land Pattern



Dimension	(mm)
C	2.70
E	0.95
X	1.05
Y	0.60

**Note:****General**

1. All dimensions shown are in millimeters (mm) unless otherwise noted.
2. Dimensioning and Tolerancing is per the ANSI Y14.5M-1994 specification.
3. This Land Pattern Design is based on the IPC-7351 guidelines.
4. All dimensions shown are at Maximum Material Condition (MMC). Least Material Condition (LMC) is calculated based on a Fabrication Allowance of 0.05 mm.

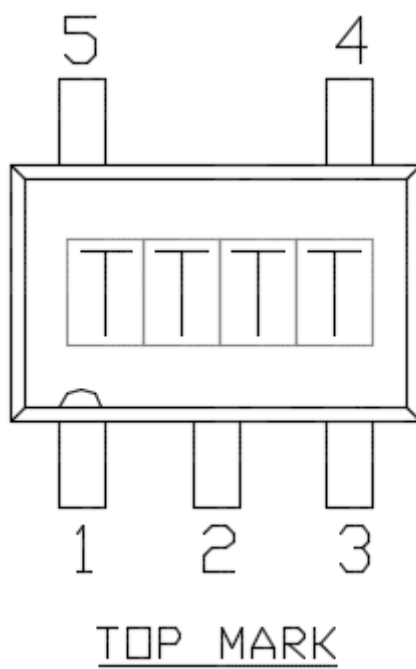
**Card Assembly**

1. A No-Clean, Type-3 solder paste is recommended.
2. The recommended card reflow profile is per the JEDEC/IPC J-STD-020D specification for Small Body Components.



## 10. Top Marking

### 10.1 SOT23-5 5-Pin Top Marking



**Note:** TTTT is a manufacturing code.

## 11. Revision History

### Revision 1.1

March, 2019

- Removed all mention of AEC-Q100 qualification in product description and feature list.

### Revision 1.0

April 2018

- Updated power numbers to be consistent with production test limits.
- Moved detailed ordering guide to a separate selection guide.
- Updated detailed description to be clearer and more accurate.
- Added Default Bop, Brp column to Ording Guide.

### Revision 0.9

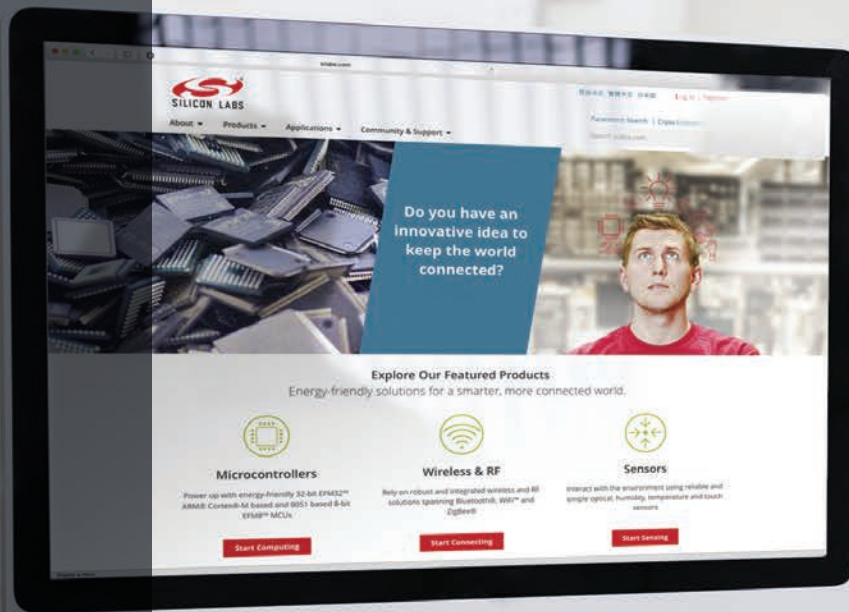
June 30, 2017

- Updated [1. Electrical Specifications](#).
- Updated [7. Ordering Information](#).
- Minor typo corrections.

### Revision 0.1

February 1, 2016

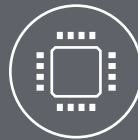
- Initial release.



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