



# Wireless Gecko™ Multiprotocol Module MGM260P Errata



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This document contains information on the MGM260P errata. The latest available revision of this device is revision V2.

Errata that have been resolved remain documented and can be referenced for previous revisions of this device.

Errata effective date: June, 2025.

## 1. Errata Summary

The following table lists all the known and unresolved errata for the MGM260P.

**Table 1.1. Errata Overview**

Designator	Title/Problem	Workaround Exists	Exists on Revision	
			V1	V2
DCDC_E304	<a href="#">Leakage Current at High Temperatures Exceeds PFM Mode Maximum Output Current</a>	Yes	X	X
LCD_E301	<a href="#">LOADBUSY Status Goes Inactive Early With Prescaled Clock</a>	Yes	X	X
SE_E302	<a href="#">DPA Countermeasure Unavailable for Some Operations</a>	Yes	X	X
USART_E304	<a href="#">PRS Transmit Unavailable in Synchronous Secondary Mode</a>	No	X	X

## 2. Current Errata Descriptions

### 2.1 DCDC\_E304 – Leakage Current at High Temperatures Exceeds PFM Mode Maximum Output Current

<b>Description of Errata</b>
<p>By default, the DCDC operates in PFM mode, which supports up to 60 mA of output current. When additional current is required, 120 mA is available by enabling PFMX mode. RAIL typically enables PFMX mode for TX/RX events and then reverts to PFM mode after radio operation is complete.</p> <p>Because digital leakage currents on EFR32xG26 at high temperatures can exceed 60 mA with no MCU or radio activity at all, PFMX mode must be enabled at all times in EM0 or EM1.</p> <p>PFM mode may safely be used in EM2 and EM3.</p>
<b>Affected Conditions / Impacts</b>
At lower load currents, PFMX mode may have reduced efficiency compared to PFM mode. See the efficiency curves in 4.28.3 DC-DC Converter of the EFR32MG26 data sheet.
<b>Workaround</b>
RAIL enables PFMX mode for EM0/1 operation on EFR32xG26 devices and no additional workaround is required. PFMX mode can be enabled before RAIL initialization by setting the <code>DCDC-&gt;CTRL.PFMXEXTREQ</code> bit.
<b>Resolution</b>
There is currently no resolution for this issue.

### 2.2 LCD\_E301 — LOADBUSY Status Goes Inactive Early With Prescaled Clock

<b>Description of Errata</b>
The LCD_STATUS_LOADBUSY bit erroneously reports completion of writes to the LCD_BACTRL, LCD_AREGA, LCD_AREGB, and LCD_SEGDn registers before synchronization is complete when <code>LCD_CTRL.PRESCALE &gt; 3</code> .
<b>Affected Conditions / Impacts</b>
If LOADBUSY is used to gate consecutive writes to one of the affected registers, only the data associated with the last write is guaranteed to be latched into the register.
<b>Workaround</b>
<p>For each write to one of the affected registers, insert a delay equal to <math>\text{LCD\_CTRL\_PRESCALE} \div f_{\text{LCDCLK}}</math> after LOADBUSY transitions from 1 to 0 before issuing the next write to the same register.</p> <p><b>Note:</b> LOADBUSY reports when data written from the PCLK register domain into the LCD controller's low-frequency clock domain has been synchronized. It does not indicate when data written into one of the affected registers is actually driven on the LCD controller pins.</p> <p>In cases where writes to these registers, such as LCD_SEGDn, are intended to have the change in pin state be observable on the connected display, LOADBUSY should not be used to gate consecutive writes. Instead, the CPU should issue the register write and wait to issue the next write until a display update event or frame counter update event occurs as reported by the LCD_IF register DISPLAY or FC flag bits. Interrupts associated with these flags can and should be enabled in such cases to minimize energy use by keeping the CPU in a low-energy mode (e.g., EM2) between such consecutive register writes.</p>
<b>Resolution</b>
There is currently no resolution for this issue.

## 2.3 SE\_E302 – DPA Countermeasure Unavailable for Some Operations

<b>Description of Errata</b>
Differential power analysis (DPA) countermeasures for ECDH on Curve25519, ECDH on Curve448, and EdDSA signing on Curve25519 are unavailable due to a lack of hardware support on all Series 2 devices with a Hardware Secure Engine (HSE).
<b>Affected Conditions / Impacts</b>
<p>A successful DPA attack may be possible if the impacted algorithms are implemented in a customer's product. However, a DPA attack is not an easy/straightforward attack as it requires specific equipment, many traces, physical access to the device, and some control over device operation.</p> <p>If a successful DPA attack occurs, an attacker may be able to gain access to confidential information, such as private keys or encrypted communications between devices.</p>
<b>Workaround</b>
No fix is available to provide the affected DPA countermeasures on Series 2 devices. Refer to Security Advisory A-00000534 for mitigation recommendations, which include refreshing key pairs or using a key pair only once to reduce the risk of a successful DPA attack.
<b>Resolution</b>
There is currently no resolution for this issue.

## 2.4 USART\_E304 — PRS Transmit Unavailable in Synchronous Secondary Mode

<b>Description of Errata</b>
When the USART is configured for synchronous secondary operation, the transmit output (MISO) is not driven if the signal is routed to a pin using the PRS producer (e.g., SOURCESEL = 0x20 and SIGSEL = 0x4 for USART0).
<b>Affected Conditions / Impacts</b>
Systems cannot operate the USART in synchronous secondary mode if the PRS is used to route the transmit output to the RX (MISO) pin. Operation is not affected in main mode when the transmit output is routed to the TX (MOSI) pin using the PRS producer nor is operation affected in any mode when the GPIO_USARTn_RXROUTE and GPIO_USARTn_TXROUTE registers are used.
<b>Workaround</b>
There is currently no workaround for this issue.
<b>Resolution</b>
There is currently no resolution for this issue.

### 3. Revision History

#### Revision 0.3

June, 2025

- Added [SE\\_E302](#).

#### Revision 0.2

February, 2025

- Updated for module revision V2.

#### Revision 0.1

October, 2024

- Initial release.

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**Silicon Laboratories Inc.**  
400 West Cesar Chavez  
Austin, TX 78701  
USA

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