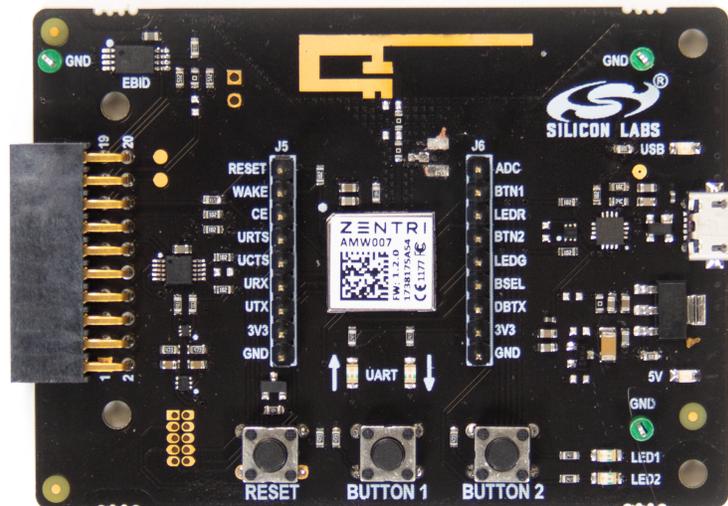


QSG162: Wireless Xpress AMW007 Kit Quick-Start Guide

The Wireless Xpress AMW007 Kit is an excellent way to get started with Wi-Fi connectivity. This document explains how to quickly connect to the AMW007 module as an access point.

KIT CONTENTS

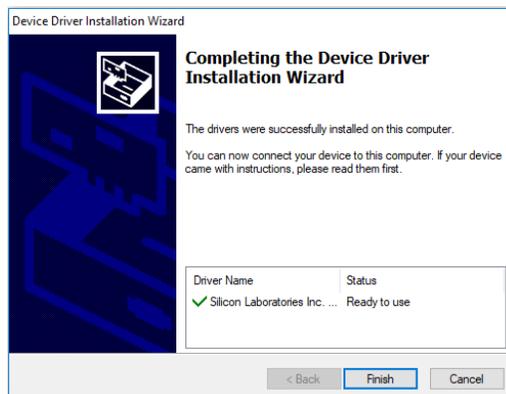
- Wireless Xpress AMW007 Expansion Board
- Micro USB Cable
- Getting Started card



1. Getting Started

Software Requirements

1. The CP210x VCP driver allows a terminal program to communicate with the kit over a serial COM port. AMW007 evaluation boards labeled AMW007-E04.2 or higher that are connected to Windows and Linux machines should be configured to this driver automatically. However, if the board is not automatically recognized by the operating system, please download and install the latest version of the CP210x VCP driver: <https://www.silabs.com/products/development-tools/software/usb-to-uart-bridge-vcp-drivers>.



2. A terminal program (Tera Term, RealTerm, Coolterm, Terminal, etc.) to communicate to the kit over a serial COM port.

Hardware Setup

1. Connect the AMW007 board to your PC using the provided micro USB cable.

Software Setup

- For Windows, use a terminal program set to 115200, 8N1.
- For a Mac, the terminal can be accessed using `[tty.usbserial]`. There may be a modifier at the end of this for your computer. Type `[tty.usbserial_modifier 115200,8n1]` to set the connection to the right settings. If using a utility like CoolTerm, make sure the settings are configured to 115200, 8N1.

Checking the Version

After connecting the board to the PC and opening the terminal program, press the **[RESET]** button on the board. You should see a header with the version information for the device. Ensure this version is 2.1.5 or newer. If you find you are using an older version of firmware, perform an over the air update on the board as described on docs.silabs.com.

help

The **[help]** command provides information both for commands and variables on the device.

Variables are system-level variables that determine the configuration of the AMW007 module.

Commands are actions that can be taken.

1. Type **[help]** to see the options for the help command.
2. Type **[help commands]** to see a list of commands supported by this module.

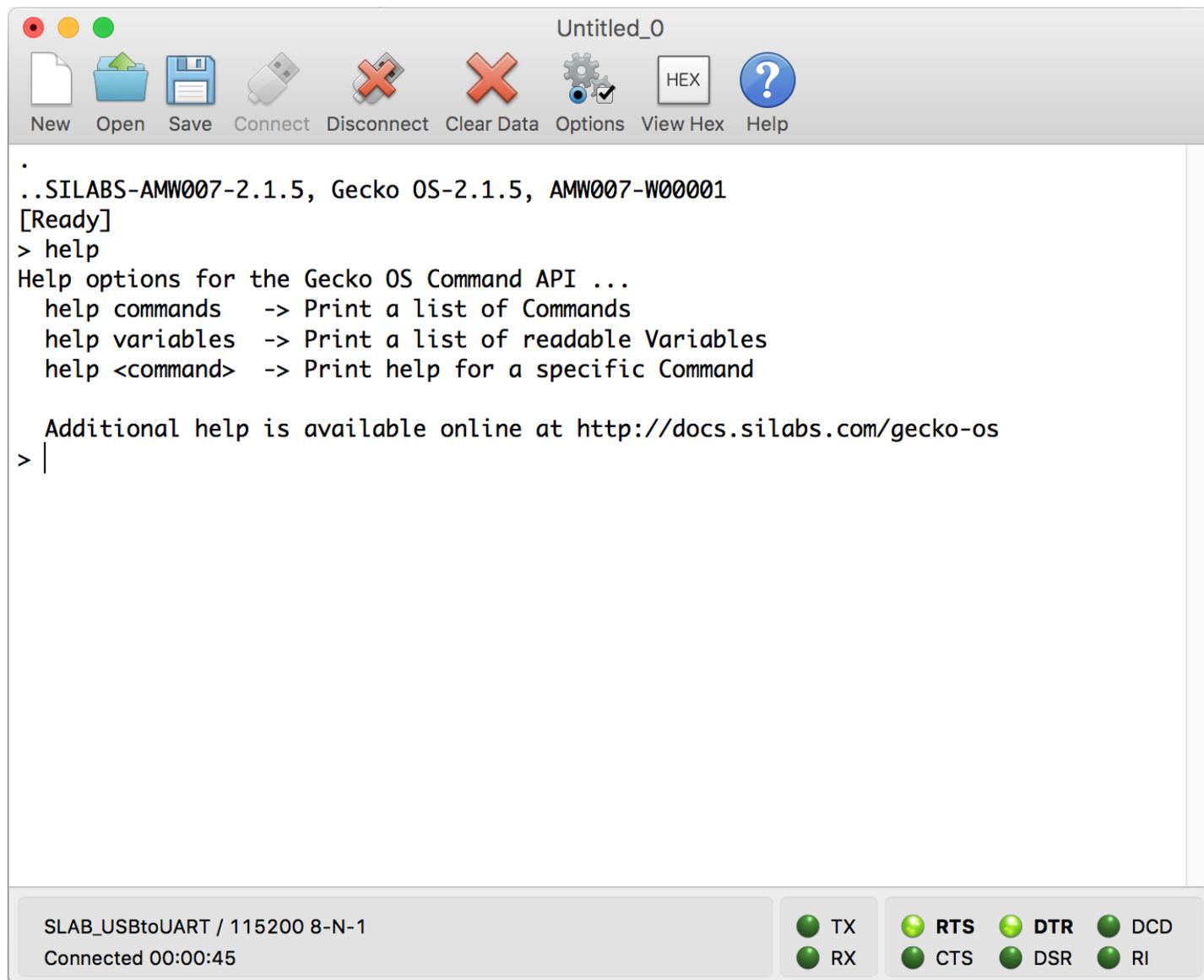


Figure 1.1. help

Commands used:

- <https://docs.silabs.com/gecko-os/latest/cmd/commands#help>

Configuring the AMW007 as a Soft Access Point

To set up the AMW007 as an access point:

1. Set/Get commands access variables that configure operation and features in the device. Type `[set setup.web.ssid]` to `["GeckoOS #"]`, where `[#]` is a unique SSID that will be easy to see on a list of other SSIDs as shown in Figure 1.3. Ensure this SSID does not match any nearby SSIDs. Note that you will need quotes around the network name if it contains spaces.
2. To read the password on the network, type `[get setup.web.passkey]`. The default password is "password". Set the password for the network by typing `[set setup.web.passkey]`.
3. Type `[save]` to save the new SSID and password values.
4. Type `[setup web]` to enable the module as a Wi-Fi access point and web server. A computer or phone can then be used configure the module.

```

set setup.web.ssid "Gecko OS 12345"
Set OK
> get setup.web.passkey
password
> set setup.web.passkey "MyPassword"
Set OK
> get setup.web.passkey
MyPassword
> save
Success
> setup web
In progress
> IPv4 address: 10.10.10.1
SoftAP 'Gecko OS 12345' started on channel 1
HTTP and REST API server listening on port: 80
Web setup started with the SSID: Gecko OS 12345 on channel 1
gpio_dir 5 in
Set OK
> |
    
```

SLAB_USBtoUART / 115200 8-N-1
Connected 00:12:12

TX RX RTS CTS DTR DSR DCD RI

Figure 1.2. setup web / set setup.web.ssid / save / get setup.web.passkey

5. Configure GPIO 5 to be an input by executing the command 'gpio_dir 5 in'. Note that this is done to illustrate additional capability in step 9 of this QSG. This command is not typically required to configure your device.

6. Using your computer or phone, connect to the Gecko OS access point [**GeckoOS #**] using the password.



Figure 1.3. Connecting to the Gecko OS Access Point

7. Using a web browser, navigate to setup.com. You are now connected to a website that is being served by the AMW007 web server. The source code for this website is fully customizable and available for download from docs.silabs.com.

8. Click the [**GPIOs**] area on the left side of the browser.

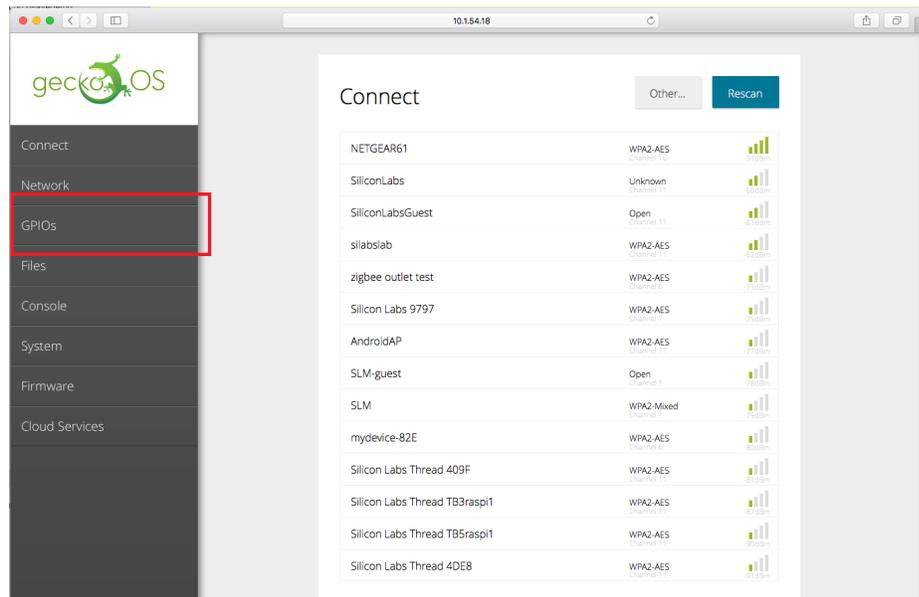


Figure 1.4. Navigating to the Gecko OS webserver homepage

9. Press and hold the **[BUTTON 2]** switch on the AMW007 board to change the GPIO toggle on the webpage. Note that this functionality is enabled through the GPIO configuration in step #5 above.

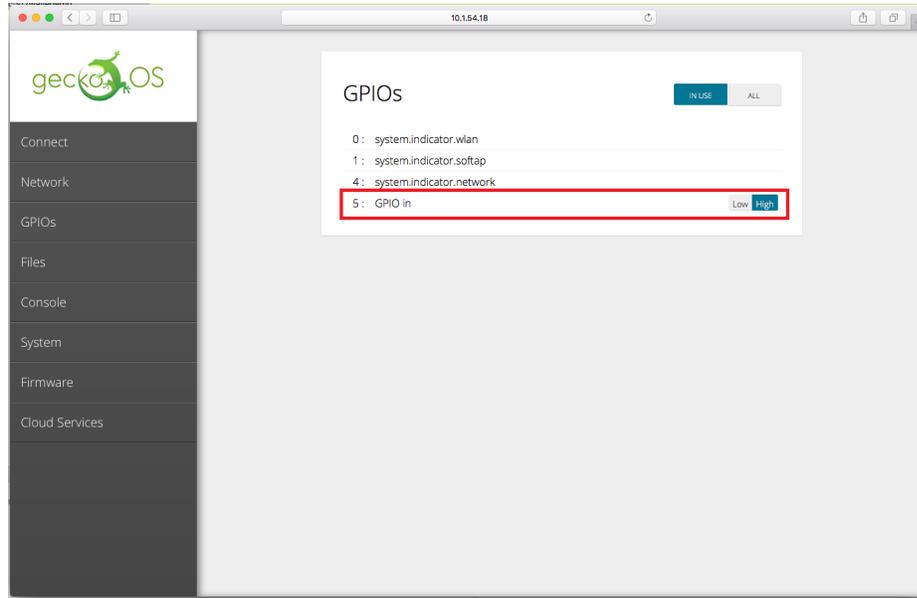


Figure 1.5. Toggling the GPIO Using the Buttons

For a detailed description of each command and variable used in this tutorial, please see <https://docs.silabs.com/>

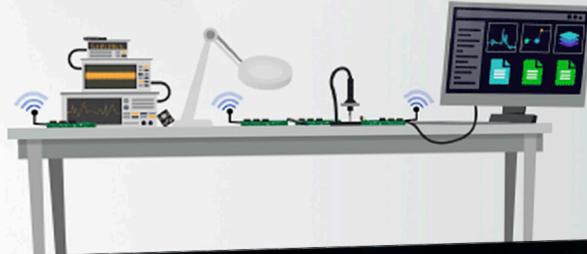
2. Additional Resources

For more information, see the following resources:

- GeckoOS API and other documentation are available at <https://docs.silabs.com/>
 - All commands can be found at <https://docs.silabs.com/gecko-os/latest/cmd/commands>
- Wireless Xpress AMW007 Kit User's Guide at <https://www.silabs.com/documents/public/user-guides/ug370-amw007-user-guide.pdf>

Silicon Labs

Simplicity Studio™4



Simplicity Studio

One-click access to MCU and wireless tools, documentation, software, source code libraries & more. Available for Windows, Mac and Linux!



IoT Portfolio
www.silabs.com/IoT



SW/HW
www.silabs.com/simplicity



Quality
www.silabs.com/quality



Support and Community
community.silabs.com

Disclaimer

Silicon Labs intends to provide customers with the latest, accurate, and in-depth documentation of all peripherals and modules available for system and software implementers using or intending to use the Silicon Labs products. Characterization data, available modules and peripherals, memory sizes and memory addresses refer to each specific device, and "Typical" parameters provided can and do vary in different applications. Application examples described herein are for illustrative purposes only. Silicon Labs reserves the right to make changes without further notice and limitation to product information, specifications, and descriptions herein, and does not give warranties as to the accuracy or completeness of the included information. Silicon Labs shall have no liability for the consequences of use of the information supplied herein. This document does not imply or express copyright licenses granted hereunder to design or fabricate any integrated circuits. The products are not designed or authorized to be used within any Life Support System without the specific written consent of Silicon Labs. A "Life Support System" is any product or system intended to support or sustain life and/or health, which, if it fails, can be reasonably expected to result in significant personal injury or death. Silicon Labs products are not designed or authorized for military applications. Silicon Labs products shall under no circumstances be used in weapons of mass destruction including (but not limited to) nuclear, biological or chemical weapons, or missiles capable of delivering such weapons.

Trademark Information

Silicon Laboratories Inc.®, Silicon Laboratories®, Silicon Labs®, SiLabs® and the Silicon Labs logo®, Bluegiga®, Bluegiga Logo®, Clockbuilder®, CMEMS®, DSPLL®, EFM®, EFM32®, EFR®, Ember®, Energy Micro, Energy Micro logo and combinations thereof, "the world's most energy friendly microcontrollers", Ember®, EZLink®, EZRadio®, EZRadioPRO®, Gecko®, ISOModem®, Micrium, Precision32®, ProSLIC®, Simplicity Studio®, SiPHY®, Telegesis, the Telegesis Logo®, USBXpress®, Zentri, Z-Wave, and others are trademarks or registered trademarks of Silicon Labs. ARM, CORTEX, Cortex-M3 and THUMB are trademarks or registered trademarks of ARM Holdings. Keil is a registered trademark of ARM Limited. All other products or brand names mentioned herein are trademarks of their respective holders.



Silicon Laboratories Inc.
400 West Cesar Chavez
Austin, TX 78701
USA

<http://www.silabs.com>