Thread is a secure, reliable, scalable, and upgradeable wireless IPv6 mesh networking protocol. It provides low-cost bridging to other IP networks while optimized for low-power / battery-backed operation. The Thread stack is designed specifically for Connected Home applications where IP-based networking is desired and a variety of application layers may be required.

OpenThread released by Google is an open-source implementation of Thread. Google has released OpenThread in order to accelerate the development of products for the connected home and commercial buildings. With a narrow platform abstraction layer and a small memory footprint, OpenThread is highly portable. It supports system-on-chip (SoC), network co-processor (NCP), and radio co-processor (RCP) designs.

Silicon Labs has developed an OpenThread-based SDK tailored to work with Silicon Labs hardware. The Silicon Labs OpenThread SDK is a fully tested enhanced version of the GitHub source. It supports a broader range of hardware than does the GitHub version, and includes documentation and example applications not available on GitHub.

These release notes cover SDK version(s):

2.0.2.0 GA released on March 9, 2022
2.0.1.0 GA released on January 26, 2022
2.0.0.0 GA released on December 15, 2021

### Compatibility and Use Notices

For information about security updates and notices, see the Security chapter of the Gecko Platform Release notes installed with this SDK or on the TECH DOCS tab on https://www.silabs.com/developers/thread. Silicon Labs also strongly recommends that you subscribe to Security Advisories for up-to-date information. For instructions, or if you are new to the Silicon Labs OpenThread SDK, see Using This Release.

### Compatible Compilers:

GCC (The GNU Compiler Collection) version 10.2.1, provided with Simplicity Studio.

### Key Features

- EFR32MG24 support
- Multiprotocol and multi-PAN radio coprocessor (RCP) model
- Thread Duckhorn feature support
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1 New Items

1.1 New Components
None

1.2 New Features

Added in release 2.0.2.0
The versions of OpenThread and the OpenThread Border Router have been updated. See sections 8.2 and 8.3.
This version of OpenThread includes low-power TCP support. This is not a mandatory Thread 1.3 component, so it is turned off by default in our sample apps.

Added in release 2.0.1.0
The versions of OpenThread and the OpenThread Border Router have been updated. See sections 8.2 and 8.3.

Added in release 2.0.0.0

Multiprotocol and multi-PAN radio coprocessor
This release supports a multiprotocol and multi-PAN radio coprocessor (RCP) model. For more information, see AN1333: Running Zigbee, OpenThread, and Bluetooth Concurrently on a Linux Host with a Multiprotocol RCP, provided with the OpenThread and Zigbee SDKs.

Thread Duckhorn Features
All Thread Duckhorn features in the OpenThread GitHub repo up to and including commit 9dedd1869 and the OpenThread Border Router GitHub repo up to and including commit 58d09bee8 are included and enabled by default.

Documentation
The following documents have been added:
• AN1372: Configuring OpenThread Applications for Thread 1.3
• AN1333: Running Zigbee, OpenThread, and Bluetooth Concurrently on a Linux Host with a Multiprotocol RCP
None
## 3 Fixed Issues

### Fixed in release 2.0.2.0

<table>
<thead>
<tr>
<th>ID</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>620720</td>
<td>The ‘diag radio state’ CLI command used with the Factory Diagnostics Module now operates correctly and no longer just returns 'invalid'.</td>
</tr>
<tr>
<td>745530</td>
<td>Fixed Thread 1.1 certification test 5.8.4 with Thread 1.2 Leader DUT fails for missing Discovery Reply.</td>
</tr>
<tr>
<td>750315</td>
<td>Fix compilation issue that occurs when FreeRTOS is added to a project.</td>
</tr>
<tr>
<td>814247</td>
<td>Fixed 'SL_OPENTHREAD_RTOS_TASK_PRIORITY' undeclared compilation error.</td>
</tr>
<tr>
<td>816037</td>
<td></td>
</tr>
<tr>
<td>818555</td>
<td>Fixed 'SL_OPENTHREAD_RTOS_TASK_PRIORITY' undeclared compilation error.</td>
</tr>
<tr>
<td>817517</td>
<td>Added the ability to utilize the custom EUI64 manufacturing token. To enable, define RADIO_CONFIG_ENABLE_CUSTOM_EUI_SUPPORT.</td>
</tr>
</tbody>
</table>

### Fixed in release 2.0.1.0

<table>
<thead>
<tr>
<th>ID</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>757778</td>
<td>All OpenThread applications now include the rail_util_rssi component.</td>
</tr>
<tr>
<td>759209</td>
<td>Fixed issue where building OpenThread apps on ef32mg2x parts with coexistence enabled gives undeclared identifier error for SL_RAIL_UTIL_COEX_RUNTIME_PHY_SELECT.</td>
</tr>
<tr>
<td>764331</td>
<td>For Raspberry Pi and Linux users, please make sure to run &quot;sudo modprobe ip6table_filter&quot; for OTBR firewall support. This allows OTBR scripts to create rules inside the Docker container before otbr-agent starts. This step should be done before starting a docker container.</td>
</tr>
</tbody>
</table>

### Fixed in release 2.0.0.0

<table>
<thead>
<tr>
<th>ID</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>624220</td>
<td>MBEDTLS_SSL_MAX_CONTENT_LEN needs to be increased to 900 for CoAP.</td>
</tr>
<tr>
<td>703615</td>
<td>If the RCP is taken offline, the OTBR doesn't recover.</td>
</tr>
<tr>
<td>714451</td>
<td>Issues with promptness and accuracy of enhanced ACKs to CSL children.</td>
</tr>
<tr>
<td>731194</td>
<td></td>
</tr>
<tr>
<td>730680</td>
<td>Host with CPCd support crashes on cpc read.</td>
</tr>
<tr>
<td>752385</td>
<td>OpenThread Sleepy-demo apps that utilize LED and Button ports and pins conflict for 43xx boards.</td>
</tr>
</tbody>
</table>
## 4 Known Issues in the Current Release

Issues in bold were added since the previous release. If you have missed a release, recent release notes are available on [https://www.silabs.com/developers/thread](https://www.silabs.com/developers/thread) in the Tech Docs tab.

<table>
<thead>
<tr>
<th>ID #</th>
<th>Description</th>
<th>Workaround</th>
</tr>
</thead>
<tbody>
<tr>
<td>482915</td>
<td>A known limitation with the UART driver can cause characters to be lost on CLI input or output. This can happen during particularly long critical sections that may disable interrupts, so it can be alleviated by repeating the CLI or waiting long enough for state changes.</td>
<td>No known workaround</td>
</tr>
<tr>
<td>495241</td>
<td></td>
<td></td>
</tr>
<tr>
<td>754514</td>
<td>Double ping reply observed for OTBR ALOC address.</td>
<td>No known workaround</td>
</tr>
<tr>
<td>815275</td>
<td>Ability to modify the Radio CCA Modes at compile-time using a configuration option in Simplicity Studio is currently not supported.</td>
<td>Use the SL_OPENTHREAD_RADIO_CCA_MODE configuration option defined in openthread-core-efr32-config.h header file included with your project.</td>
</tr>
</tbody>
</table>
5  Deprecated Items

None
6 Removed Items

Removed in release 2.0.0.0

AN1295: Developing with Thread 1.2 has been removed.
7 Multiprotocol Gateway and RCP

7.1 New Items
None

7.2 Improvements

**Changed in release 2.0.2.0**

The CPC secondary UART driver has been improved to use HW Flow Control.

The default flow control value for rcp-uart-802154.slcp and rcp-uart-802154-blehci.slcp has been changed to `usrAtHwFlowControlCtsAndRts`. The default UART_HARDFLOW value in cpcd.conf has been changed to `true` to match. Silicon Labs recommends use of hard flow control when using CPC over UART.

The CPC daemon can now be configured to restart the secondary in bootloader using pins nRESET and nWAKE. cpcd.conf has been modified; SPI_WAKE_GPIO has been removed and replaced by 3 configurations: BOOTLOADER_RECOVERY_PINS_ENABLED, BOOTLOADER_WAKE_GPIO, and BOOTLOADER_RESET_GPIO

7.3 Fixed Issues

**Fixed in release 2.0.2.0**

<table>
<thead>
<tr>
<th>ID #</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>759772</td>
<td>Fixed an issue in which turning CPCd tracing off caused communication issues between host applications, such as OTBR and zigbeed, and the multiprotocol RCP.</td>
</tr>
<tr>
<td>759780</td>
<td>Fixed issue where restarting the multi-PAN RCP would cause CPC-enabled host apps such as zigbeed, otbr-agent, and ot-cli to disconnect from CPCd.</td>
</tr>
<tr>
<td>774747</td>
<td>Fixed a bug in the CPC UART driver that caused OTBR to lose its CPC connection to the multi-PAN RCP, especially at higher baud rates and at startup.</td>
</tr>
<tr>
<td>812170</td>
<td>Increased default zigbeed table sizes.</td>
</tr>
<tr>
<td>813499</td>
<td>Fixed a bug introduced in GSDK 4.0.1 that prevented CPCd from connecting to the multiprotocol RCP (rcp-uart-802154-blehci and rcp-spi-802154-blehci)</td>
</tr>
<tr>
<td>814284</td>
<td>Fixed an issue where the multi-PAN RCP could assert in radioProcessTransmitSecurity under certain circumstances. This was causing intermittent failure of host applications such as OTBR and zigbeed.</td>
</tr>
<tr>
<td>815222</td>
<td>Zigbeed now correctly picks the custom MFG EUI64 if one exists on the chip.</td>
</tr>
<tr>
<td>817692</td>
<td>Fixed a zigbeed issue in which join attempts were causing an assert on a 64 bit machine (Raspberry Pi OS).</td>
</tr>
</tbody>
</table>

7.4 Known Issues in the Current Release

None

7.5 Deprecated Items

None

7.6 Removed Items

None
8 Using This Release

This release contains the following:

- Silicon Labs OpenThread stack
- Silicon Labs OpenThread sample applications
- Silicon Labs OpenThread border router

For more information about the OpenThread SDK see QSG170: Silicon Labs OpenThread QuickStart Guide. If you are new to Thread see UG103.11: Thread Fundamentals.

8.1 Installation and Use

The OpenThread SDK is part of the Gecko SDK (GSDK), the suite of Silicon Labs SDKs. To quickly get started with OpenThread and the GSDK, start by installing Simplicity Studio 5, which will set up your development environment and walk you through GSDK installation. Simplicity Studio 5 includes everything needed for IoT product development with Silicon Labs devices, including a resource and project launcher, software configuration tools, full IDE with GNU toolchain, and analysis tools. Installation instructions are provided in the online Simplicity Studio 5 User’s Guide.

Alternatively, Gecko SDK may be installed manually by downloading or cloning the latest from GitHub. See https://github.com/SiliconLabs/gecko_sdk for more information.

The GSDK default installation location has changed with Simplicity Studio 5.3, used with this release.

- Windows: C:\Users\<NAME>\SimplicityStudio\SDKs\gecko_sdk
- MacOS: /Users/<NAME>/SimplicityStudio/SDKs/gecko_sdk

Documentation specific to the SDK version is installed with the SDK. API references and other information about this release are available on https://docs.silabs.com/openthread/1.2/.

8.2 OpenThread GitHub Repository

The Silicon Labs OpenThread SDK includes all changes from the OpenThread GitHub repo (https://github.com/openthread/openthread) up to and including commit 3b79cb0d084. An enhanced version of the OpenThread repo can be found in the following Simplicity Studio 5 GSDK location:

<GSDK Installation Location>/util/third_party/openthread

8.3 OpenThread Border Router GitHub Repository

The Silicon Labs OpenThread SDK includes all changes from the OpenThread border router GitHub repo (https://github.com/openthread/ot-br-posix) up to and including commit 5be35949c6f. An enhanced version of the OpenThread border router repo can be found in the following Simplicity Studio 5 GSDK location:

<GSDK Installation Location>/util/third_party/ot-br-posix

8.4 Using the Border Router

For ease of use, Silicon Labs recommends the use of a Docker container for your OpenThread border router. Refer to AN1256: Using the Silicon Labs RCP with the OpenThread Border Router for details on how to set up the correct version of OpenThread border router Docker container. It is available at https://hub.docker.com/r/siliconlabsinc/openthread-border-router.

If you are manually installing a border router, using the copies provided with the Silicon Labs OpenThread SDK, refer to AN1256: Using the Silicon Labs RCP with the OpenThread Border Router for more details.

Although updating the border router environment to a later GitHub version is supported on the OpenThread website, it may make the border router incompatible with the OpenThread RCP stack in the SDK.
8.5 NCP/RCP Support

The OpenThread NCP support is included with OpenThread SDK but any use of this support should be considered experimental. The OpenThread RCP is fully implemented and supported.

8.6 Security Information

Secure Vault Integration

When deployed to Secure Vault High devices, sensitive keys are protected using the Secure Vault Key Management functionality. The following table shows the protected keys and their storage protection characteristics.

<table>
<thead>
<tr>
<th>Wrapped Key</th>
<th>Exportable / Non-Exportable</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>Thread Master Key</td>
<td>Exportable</td>
<td>Must be exportable to form the TLVs</td>
</tr>
<tr>
<td>PSKc</td>
<td>Exportable</td>
<td>Must be exportable to form the TLVs</td>
</tr>
<tr>
<td>Key Encryption Key</td>
<td>Exportable</td>
<td>Must be exportable to form the TLVs</td>
</tr>
<tr>
<td>MLE Key</td>
<td>Non-Exportable</td>
<td></td>
</tr>
<tr>
<td>Temporary MLE Key</td>
<td>Non-Exportable</td>
<td></td>
</tr>
<tr>
<td>MAC Previous Key</td>
<td>Non-Exportable</td>
<td></td>
</tr>
<tr>
<td>MAC Current Key</td>
<td>Non-Exportable</td>
<td></td>
</tr>
<tr>
<td>MAC Next Key</td>
<td>Non-Exportable</td>
<td></td>
</tr>
</tbody>
</table>

Wrapped keys that are marked as “Non-Exportable” can be used but cannot be viewed or shared at runtime.

Wrapped keys that are marked as “Exportable” can be used or shared at runtime but remain encrypted while stored in flash.

For more information on Secure Vault Key Management functionality, see AN1271: Secure Key Storage.

Security Advisories

To subscribe to Security Advisories, log in to the Silicon Labs customer portal, then select Account Home. Click HOME to go to the portal home page and then click the Manage Notifications tile. Make sure that ‘Software/Security Advisory Notices & Product Change Notices (PCNs)’ is checked, and that you are subscribed at minimum for your platform and protocol. Click Save to save any changes.
8.7 Support

Development Kit customers are eligible for training and technical support. Use the Silicon Laboratories Thread web page to obtain information about all Silicon Labs OpenThread products and services, and to sign up for product support.

You can contact Silicon Laboratories support at http://www.silabs.com/support.
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www.silabs.com/simplicity

Quality
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